

# CONTROL DATA® DISK STORAGE UNIT BR308

PREVENTIVE MAINTENANCE CORRECTIVE MAINTENANCE DIAGRAMS WIRE LISTS

Volume 1 of 2

HARDWARE MAINTENANCE MANUAL

	REVISION RECORD
REVISION	DESCRIPTION
A	Manual released by Engineering Change Order PE39149. Engineering Change Orders
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	are incorporated in this manual.
В	Add Corrective maintenance section.
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ablication No. 83308100	

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or use Comment Sheet in the back of this manual.

# LIST OF EFFECTIVE PAGES

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#### **PREFACE**

This manual has been prepared for customer engineers and other technical personnel directly involved with maintaining the disk storage unit (drive).

Maintenance information is provided by five sections in this manual. Section numbers and a brief description of their contents are listed below.

- Section 1 Installation and Checkout.

  Provides information on preparing the drive for initial use:
  unpacking, power/signal cabling,
  and initial checkout.
- Section 2 Preventive Maintenance.
  Provides detailed procedures
  on maintaining the equipment.

- Section 3 Corrective Maintenance. Provides check/adjustment and replacement information for various components and assemblies in the device.
- Section 4 Diagrams. Contains logic diagrams and assembly schematics.
- Section 5 Wire Lists. Provides documentation on wiring for logic and mechanical assemblies.

Manuals applicable to the BR308 Disk Storage Unit are as follows:

Publication No.	<u>Title</u>
83308100	Maintenance
83308200	Reference
83308300	Parts Data

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# SECTION 1

# INSTALLATION AND CHECKOUT

#### INTRODUCTION

This section contains the steps involved in unpacking each unit. For air shipment, each unit is covered with a plastic dust shield, enclosed within an outer corrugated fiber-board carton, and then strapped to a wooden pallet. For domestic surface shipment, each unit is packaged in the same manner as for air shipment but is not placed on a wooden pallet. This permits each unit to be moved about on its own casters.

#### INSPECTION

When uncrating the units, inspect each carton for possible shipping damage. All claims for this type of damage should be filed with the carrier involved. Most crating materials may be reused if reasonable care is taken while uncrating. When uncrating is complete, check off all parts listed in the Shipping Bill accompanying the equipment. Discrepancies, missing items, damaged equipment, etc., should be reported to the CDC Account Sales Representative responsible for the equipment.

#### **UNCRATING**

1. Remove external packing material.



Use care when cutting straps as they may whip when  $\operatorname{cut}\nolimits.$ 

Remove polypropylene straps securing unit to skid and remove dust shield.



The DSU weighs approximately 750 lbs when crated. To prevent injury to personnel or damage to unit, use Rol-a-Lifts or equivalent to remove unit from pallet.

- 3. Remove unit from skid.
- Remove filler tubes from top of pack cover glass. Remove material (if any) contained inside tubes.

#### NOTE

The pack cover is locked in place by a manually operated latch. Open cover by pulling upward on latch until clear of catch (see Figure 1-1).

- 5. Lift pack cover.
- 6. Remove logic chassis-to-frame retainer.
- 7. Swing logic chassis out.
- 8. Remove all material shipped inside unit.
- 9. Remove deck cover (see Figure 1-2).
- 10. Remove front panel.
- 11. Remove side skins (if installed).
- 12. Remove front deck hold-down bolts two
  places (see Figure 1-3).
- Remove shipping hardware holding spindle motor plate (see Figure 1-4).
- 14. Remove rear deck hold-down bolts two places. These bolts are identified by plastic plugs. Replace plugs after removing hold-down bolts.
- 15. Remove actuator tie-bolt cord.
- 16. Remove logic chassis access cover and check all cards for proper seating. Replace access cover.
- 17. Replace deck cover.
- 18. Thoroughly vacuum-clean unit.
- 19. Replace front panel.
- 20. Replace side skins.
- 21. Reposition pack cover.
- 22. Swing logic chassis to closed position.

#### INSTALLATION REQUIREMENTS

Site space and environmental requirements are listed in Table 1-1.

Figure 1-5 illustrates recommended clearances required for maintenance.

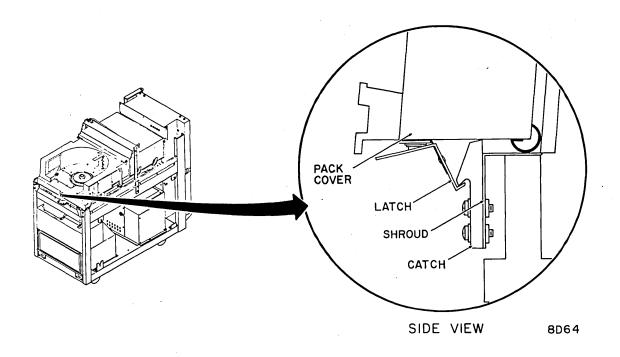


Figure 1-1. Pack Cover Latch

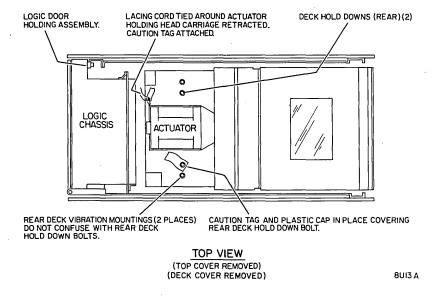


Figure 1-2. Drive Top View

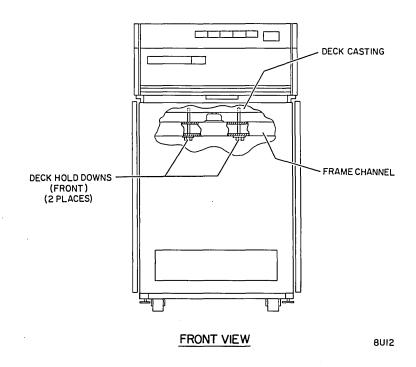


Figure 1-3. Drive Front View

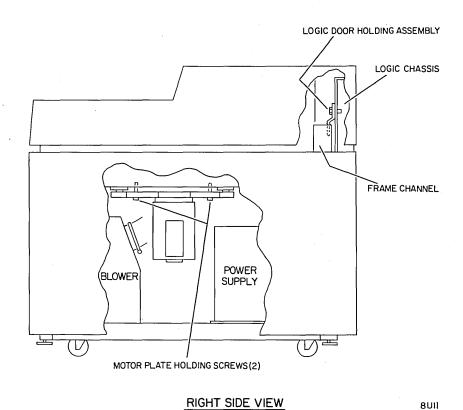


Figure 1-4. Drive Right Side View

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TABLE 1-1. INSTALLATION SPECIFICATIONS

PHYSICAL (Approximate)						
<u>Size</u>	Uncrated					
Height	39.5 in.					
Width	22 in.					
Depth	44.5 in.					
Weight	700 lbs.					
ENVIRONMENT				····		
Characteristic	Cond	<u>ition</u>		Spe	cificatio	<u>on</u>
Temperature	Operat	ing		60°F (15.6°	C) to 900	OF (32.2°C)
	Gradie	nt		12°F (6.6°C) per hour		
	Non-Op	erating		-30°F (-34°C) to +150°F (66°C)		
Relative Humidity	Operat	ing		20% to 80%		
(no condensation)	Non-Op	erating		5% to 95%		
Altitude	Operat	ing		-1000 ft (-305 m) t (3.05 km)		o +10,000 ft
	Non-Op	erating		-1000 ft to	+34,000	ft (10.7 km)
POWER						
Consumption		Standby			Accessin	<u>a</u>
	60 Hz	50 Hz	400 Hz	60 Hz	<u>50 Hz</u>	400 Hz
Amps/Phase	0.8	0.9	1.0	4.4	5.0	2.4
True Power (KW)	0.15	0.18	0.3	0.8	0.8	0.7
Power Factor	0.9	0.9	8.0	0.8	0.8	0.8
BTU/Hour	510	610	1020	2730	2730	2380
Starting Current (App	roximate and N	on-Linear)				
<u>Time</u>	<u>208V</u>	<u>220V</u>				
0-6 seconds	38	40				
6-8 seconds	38	25				
8-10 seconds	20	12	•			
10-12 seconds	12	8				
12-14 seconds	8	<b>-</b>				
POWER CONNECTOR					-	
Unit	Description	<u>.</u>		Connector	Mat	ting Receptacle
	le, 3-wire, wi mp, 250v, ac o			CDC 9436800 Hubble 2321		CDC 94368004 Hubble 2323
	le, 3-wire, wi mp, 277v, ac o			CDC 9436880 Hubble 2331		CDC 94368801 Hubble 2333

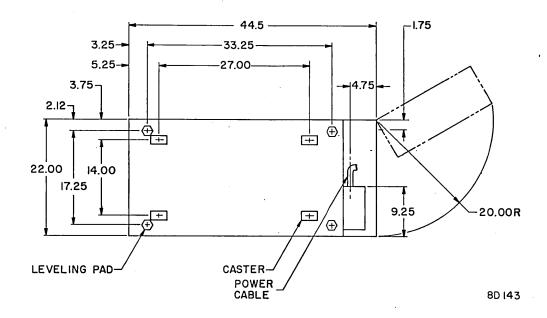


Figure 1-5. Space Requirements

#### LEVELING PAD INSTALLATION

Install leveling pads on each unit as .
follows:

- Remove floor panel and roll cabinet so that one corner hangs over opening in floor.
- Working from opening, install leveling pad in bottom of unit and screw in until pad clears floor.
- 3. Repeat steps 1 and 2 for remaining pads.

#### LEVELING AND ALIGNING CABINET

- 1. Turn down leveling pads until casters are completely off of floor.
- Place spirit level on main deck so ends of level point to front and rear of deck.
- Adjust leveling pads until surface is horizontal within three angular degrees.
- Place spirit level on main deck so ends of level point toward sides.
- Adjust leveling pads until surface is horizontal within three angular degrees.

6. Repeat procedure until main deck is horizontal within three angular degrees regardless of spirit level orientation.

#### **POWER WIRING**

#### SITE ELECTRICAL REQUIREMENTS

#### **General Requirements**

Drive power requirements are listed in Table 1-1.

#### Power System Grounding Requirements

The site ac power system must have provisions for correct equipment safety grounding. All of the following conditions must be met:

- 1. The branch circuit supplying ac power to the drive must have safety ground provisions. Therefore, this circuit must include an insulated grounding conductor that is identical to the grounded and ungrounded branch circuit conductors. The insulated grounding conductor shall show either a green color or green with a yellow strip.
- The grounding conductor specified in step 1 is to be grounded at the service equipment.

3. All power receptacles (including convenience outlets for oscilloscopes and other test equipment) must be at a common ground potential to prevent shock hazards if two equipments are touched simultaneously. Therefore, all attachment-plug receptacles in the vicinity of the drive are to be of the grounding type; furthermore, the grounding conductors serving these receptacles are to be connected to the same grounding conductor that serves the drive.

#### SYSTEM GROUNDING

The controller and its attached drives must be connected to earth ground. The permissible grounding schemes, listed in preferred order, are:

- 1. Controller and drives connected to qualified site floor ground. A qualified ground would be a floor grid where the horizontal and vertical members of the grid are mechanically secure and have ground straps or their equivalent joining them to assure a constant ground potential. In turn, the grid must be connected to earth ground. An alternate qualified floor ground is a grounding grid or grounding bus system provided under the false floor.
- Controller and drives connected to otherwise qualified floor grid, except that floor grid is isolated from earth ground. In this case, controller is then connected to earth ground to ground the system.
- No site floor grid available: controller and drives connected to each other in a daisy chain configuration. Controller connected to earth ground.

#### Floor Grid Available

If a floor grid is available (schemes 1 or 2), each drive is to be individually connected to the floor grid. Ground each drive as follows:

- 1. Open logic chassis.
- Grounding block is mounted at the bottom end of unit, next to the ac circuit breaker box. Route braided strap with free end into floor cutout.
- 3. Drill 11/32-inch hole in grid.
- Secure strap lug to grid using screw (P/N 17901524) and lockwasher (P/N 10126403). Lockwasher goes under terminal lug.

#### Floor Grid Not Available

If a floor grid is not available, all of the drives must be connected to the controller in a daisy chain grounding configuration. In turn, the controller must be connected to earth ground.

The ground connections are via flat braided shielding (P/N 93267009). Cut this shielding to the lengths required to go from drive to drive, drive to controller, and controller to earth ground. Crimp and solder a terminal lug (P/N 40125601) to the end of each strap.

Earth ground at the site may be available at the main power distribution panel (if it is connected to building ground), at the steel plate in contact with the masonry below the panel (if the panel is not connected to earth ground), or to an earth ground bus. Connect one end of a prepared ground strap to the available ground.

Connect remainder of grounds as follows:

- 1. Open logic chassis.
- Grounding block is mounted at the bottom end of unit, next to the ac circuit breaker box. Loosen grounding block screw that secures 3-foot length of ground strap (other end of this strap is not connected). Remove ground strap.
- Attach two ground straps to this screw.
   One strap will go to each of the two closest drives. Tighten screws.
- 4. Repeat step 3 for remaining drives. Drive closest to controller is to be connected to controller ground. Drive farthest from controller has only one ground strap connected to it.
- 5. Connect controller to earth ground.

#### **AC POWER CONNECTIONS**

Each drive receives its 50 or 60 Hz power via an eight foot cable having a three-pole connector. This cable originates from the UNIT POWER circuit breaker located in the ac power supply at the rear of the drive. The 400 Hz cabling for each drive must be provided at the site. The 400 Hz cable is connected to terminal board AlTBl located in the ac circuit breaker box.

All motors in the drive are single phase (connected phase-to-phase for 60 Hz and phase-to-neutral for 50 Hz). Although each drive uses single phase power, three phase power should be available at the site. External phase connections to the drives should be rotated from drive to drive so that each

group of three drives presents a balanced load to a three-phase system.

Phasing is controlled prior to the connector on the drive's cable. Phase assignments of the connector are:

#### 60 Hz

- X Phase A (Brown)
- Y Phase B (Blue)
- G Ground (Green)

#### 50 Hz

- X Phase A (Brown)
- W Neutral (Blue)
- G Ground (Green)

The green wire is safety ground. It is not to be used as neutral as it is not a current-

carrying ground. This wire connects to a lug inside the UNIT POWER circuit breaker box. Make sure that this is a secure connection.

#### SIGNAL CABLING

Each drive communicates with a controller by means of two interconnecting cables. System cables are illustrated in Figure 1-6. Signal functions are listed in Tables 1-2 and 1-3.

#### CAUTION

When installing I/O cables, use care so that signal pins are not damaged.

The I/O connectors are located on the frame below the logic chassis. There are four I/O connectors provided: two for each channel. Connectors IJ1 and IJ2 are for channel I; IIJ1 and IIJ2 are for channel II.

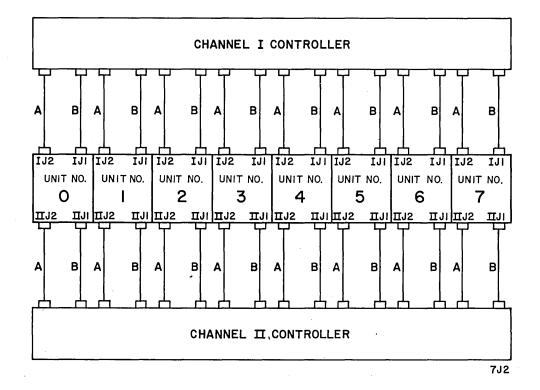


Figure 1-6. System Cabling

TABLE 1-2. "A" CABLE I/O CONNECTOR PIN ASSIGNMENT (J2)

Pin No.	Signal Name
Signa	ls From Unit To Controller
	Status Bit
1-4	0
2-5	1
3-7	2
8-12	3
10-13	4
11-14	5
15-18	6
16-20	7
17-21	8
22-25	9
74-77	On Sector
75-78	Seek Error
Sign	als From Controller To Unit
	Address and Control Bus Bit
23-26	0
24-27	1
28-31	2
29-32	3
30-33	4
34-37	5
35-38	6
36-39	7
40-43	8
41-44	Open Cable Detector
42-45	Difference Select
46-49	Cylinder Select
47-50	Sector Select
48-51	Head Select
52-55	Control Select
53-56	Read Cylinder Status
54-57	Read Difference Status
58-62	Read Head Status
59-63	Read Sector Counter Status
60-64	Read Sector Register Status
65-70	Read Interlock Status
66-71	Read Positioner Status
67-72	Read Fault Status
73-76	Read Control Status

TABLE 1-3. "B" CABLE I/O CONNECTOR PIN ASSIGNMENT (J1)

Pin No.	Signal Name				
Signa	Signals From Unit To Controller				
х-у	Double Density (Both Grounded To Unit)				
A-C	Unit Ready				
B-D	Unit Busy				
Е-Н	Unit Selected				
F-J	On Line - $F = On Line J = gnd$				
к	Read Data "1" (Coax)				
L	Read Clock (Coax)				
М	Write Clock (Coax)				
Signa	als From Controller To Unit				
Y-a	Unit Select				
z-b	Release				
с-е	Clear All Other Channel Reserves				
d-f	Clear Fault				
BB-DD	Write Data				
<del>t</del> -v	Open Cable Detector				
P-S	Bit 9 (Address and Control Bus)				
CC-EE Write Strobe					
Sequ	ence Power Lines				
h	Power Sequence 0				
j	Power Sequence 1				
k	Power Sequence 2				
m	Power Sequence 3				
n	Power Sequence 4				
P	Power Sequence 5				
r	Shield (Not Grounded To Unit)				
Misc	ellaneous				
s	Ground				

### INITIAL CHECKOUT AND STARTUP

This procedure assumes that all of the preceding procedures have been completed. Before performing this procedure, become familiar with the safety precautions and maintenance preliminary conditions specified in Section 3. Proceed as follows:

1. Turn off both UNIT POWER circuit breakers.

Turn off all dc power supply circuit breakers.

#### CAUTION

Bearing damage can occur if media cleaning solution runs into spindle.

- Wipe spindle clean with lint-free gauze that is slightly dampened (not soaked) with media cleaning solution.
- Using vacuum cleaner, remove dust or dirt from interior of shroud and cabinet.
- 5. Open cabinet rear door. Verify that all logic chassis cards are firmly seated in their connectors. Check all miscellaneous connectors to see that they are properly seated.
- 6. Open top cover and remove deck cover.
- Check that logic cards next to actuator assembly are firmly seated. Check that head connectors are properly seated.
- 8. Replace deck cover and close top cover.
- Verify that drive is connected to external power source and that source circuit breaker is on.
- 10. Turn on UNIT POWER circuit breakers.

  Determine that blower motor and elapsed time meter begin to operate.
- If START switch indicator is lighted, press switch to turn off indicator.
- 12. Set LOCAL/REMOTE switch on power supply to LOCAL.

#### NOTE

Sequence power is now available to all drives with higher Unit Number indicator designations. For example, if unit 2 is set to LOCAL, any of the units 3 through 7 with pack installed and START switch turned on will power up in sequence.

- 13. Position maintenance panel switches as
   follows:
  - ON LINE/OFF LINE/WRITE DISABLE switch to OFF LINE
  - CARRIAGE OFFSET switch to NORMAL
  - DATA WINDOW switch to NORMAL
  - TAG LINE SELECT switch to INTERLOCK
- 14. Turn on all dc power supply circuit
  breakers. Verify the following:

- a. All output voltages are at nominal values.
- b. All control panel lights off, except MAINTENANCE is on.
- c. ADDRESS & CONTROL BUS indicators are as follows:

Bit	State	<u>Function</u>
0	on	Pack On
1	on	Interlocks Closed
2	off	Heads Loaded
3	off	Load Heads
4	off	START switch
5	on	LOCAL
6	off	Motor On
7	on	Cooling Air OK
8	on	Logic Temp OK

- 15. Install clean scratch pack as directed in Section 2.
- 16. Open top cover from rear and remove deck cover.
- 17. Remove one of the voice coil wires. This will prevent the heads from loading.

#### NOTE

Only one drive should be accelerating the pack at a time. The second drive may be started after the first drive reaches operating speed (approximately 15 seconds).

- 18. Press the START switch. Observe the
   following:
  - a. START indicator lights.
  - b. Spindle motor starts.

Purge unit in this mode for one minute.

- 19. Stop unit and replace voice coil wire.
- 20. Press START switch. Observe the following:
  - a. START indicator lights.
  - b. Spindle motor starts.
  - c. Bits 3, 4, and 6 of ADDRESS & CONTROL BUS light.
- 21. When first seek interlock delay is complete (approximately 15 seconds), heads will load to cylinder 000. Verify the following:

- a. Unit Number indicator on operator control panel lights.
- b. ADDRESS & CONTROL BUS indicator bit
  2 turns on; bit 3 goes out.
- 22. Set ON LINE/OFF LINE/WRITE DISABLE switch to ON LINE.
- 23. Check head/arm alignment. If necessary, perform Head/Arm Alignment procedure in Corrective Maintenance section.
- 24. Perform required controller/system checks.

# WARNING

If unit fails to power down, refer to Normal Power Off Sequence in Theory of Operation section of Reference manual.

#### CAUTION

If unit fails to power down when START switch is pressed, disconnect yellow leadwire to voice coil and manually unload heads to clear disk pack before troubleshooting malfunction. Refer to Corrective Maintenance section of this manual.

25. To stop spindle motor, press operator START switch. To remove power to drive, turn off both UNIT POWER circuit breakers.

# SECTION 2

# PREVENTIVE MAINTENANCE

#### **SCOPE**

Maintenance procedures listed within this section are written so that a person familiar with the procedure need only read up to the colon in each step of the procedure. Information listed after the colon is a detailed account of how to perform that step. It is recommended that before performing any maintenance procedure that the entire procedure be read.

Performance of the drive is dependent on the proper and timely execution of a preventive maintenance routine. Such a routine is provided by the Preventive Maintenance Index (Table 2-1).

The index consists of six levels based on a calendar period or hours of operation (whichever comes first). The power supply elapsed time meter keeps a cumulative record of hours of operation. Perform preventive maintenance in accordance with the indication of this meter. The Preventive Maintenance column (Table 2-1) lists the title of the paragraph containing the required instructions.

TABLE 2-1. PREVENTIVE MAINTENANCE INDEX

		<del> </del>
Level*	Est.Time (Minutes)	Procedure
3	10	Inspect actuator assembly
3	1 .	Clean pack access cover glass
3	10	Clean primary air filter
3	2	Check power supply outputs
4	1	Clean shroud and spindle
4	2	Clean and lubricate lockshaft
4	5	Clean carriage rails and bearings
4	120	Check head/arm alignment
6	20	Replace absolute air filter

<sup>\*</sup>Intervals are maximum times. Preventive maintenance may be required more frequently depending on level of dust contamination in operating area.

The following levels of scheduled preventive maintenance are required:

- Level 1 Weekly or 150 hours (no preventive maintenance scheduled)
- Level 2 Monthly or 500 hours (no preventive maintenance scheduled)
- Level 3 Quarterly or 1,500 hours
- Level 4 Semiannually or 3,000 hours
- Level 5 Anually or 6,000 hours (no preventive maintenance scheduled)
- Level 6 Biennially or 9,000 hours

#### PREVENTIVE MAINTENANCE MATERIALS

The materials used in the procedures of this section are listed in Table 2-2.

TABLE 2-2. PREVENTIVE MAINTENANCE MATERIALS

Material	Source			
Detergent	Commercially available			
Filter Coat	CDC* 12210958			
Lint-Free Gauze	CDC 12209713			
Lubricant Paste	CDC 95016101			
Media Cleaning Solution	CDC 95033502			
Plastic Spatulas (or wooden tongue depressor)	Commercially available			
Tape, Adhesive	Commercially available			
*CDC® is a registered trademark of Control Data Corporation.				

#### LEVEL 3 MAINTENANCE PROCEDURES

#### INSPECT ACTUATOR ASSEMBLY

 Remove disk pack: Press START switch to stop spindle motor. Open pack access cover, remove disk pack and close access pack cover.

- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Remove voice coil yellow leadwire: Open cabinet top cover and remove deck cover. Remove voice coil yellow leadwire.
- 4. Inspect entire actuator for presence of dust and other foreign materials. Pay particular attention to the following areas:
  - a. Circular cutout in face of magnet assembly (receives voice coil).
  - b. Rail surfaces (particularly horizontal surfaces) or carriage track on which carriage and bearing assembly travels.
- Clean actuator area: Use lint free gauze dampened with media cleaning solution (not soaked) to remove deposits or attracted particles.
- 6. Clean rails and bearings: Refer to Manually Positioning Carriage With Power Off (located in Section 3 of this manual) and install head cam tool. Refer to Clean Carriage Rails and Bearings procedure (located in this Section) for method of cleaning rails and bearings.
- 7. Remove head cam tool.
- Check that heads are fully retracted. Install voice coil yellow leadwires.
- Install deck cover and close cabinet top cover.
- 10. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

#### CLEAN PACK ACCESS COVER GLASS:

- Remove disk pack: Press START switch to stop spindle motor. Open pack access cover and remove disk pack (leave cover open).
- 2. Clean pack access cover glass (both sides): Use a lint-free gauze dampened (not soaked) with media cleaning solution to remove smudges and deposits from the glass (both sides) in the pack access cover. Close pack access cover.

#### CLEAN PRIMARY AIR FILTER

 Remove disk pack: Press START switch to stop spindle motor. Open pack access cover, remove disk pack and close pack access cover.

- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- 3. Remove primary air filter: Remove cabinet front panel and set panel aside. Remove primary air filter from bottom of air supply assembly at front of cabinet (Figure 2-1) by pressing upward on clips while pulling filter out. Remove filter from air supply.
- 4. Clean primary air filter: Agitate filter in a mild detergent solution. Thoroughly flush filter with water from a low pressure nozzle. Shake any excess water from filter and allow filter to dry.
- 5. Spray primary air filter with filter coat: When filter is completely dry, thoroughly coat both sides of the filter with Filter Coat spray.
- 6. Install primary air filter: Position primary air filter in bottom trough of air supply. While pressing upward on retaining clips, push filter against air supply and release retaining clips. Check that filter is properly seated in air supply. Install cabinet front panel.
- Set UNIT POWER circuit breakers to ON and close cabinet rear door.

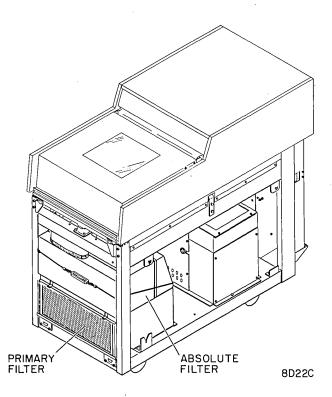


Figure 2-1. Cabinet Air Filters

#### CHECK POWER SUPPLY OUTPUTS

- Install a scratch pack: Press START switch to stop spindle motor. Open pack access cover, remove customer disk pack. Install scratch disk pack and close pack access cover.
- 2. Connect Off Line Tester to drive: Open cabinet rear door. Set UNIT POWER circuit breakers to OFF. Remove logic chassis card cover. Install Off Line Tester as directed in Reference manual. After tester is installed set the UNIT POWER circuit breakers to ON. Leave cabinet rear door open.
- Load Heads: Press START switch to start spindle motor and to load heads.
- Using Off Line Tester command repeat seeks between cylinder 0 and 32. (See Reference manual for tester operating procedures.)
- 5. Measure output voltages at corresponding test jacks on logic chassis maintenance panel: Using an ac/dc volt/ ohmmeter measure the following test points on the logic chassis maintenance panel (located on inside, and at top of cabinet rear door):
  - a. Measure +5v. Meter shall read +4.95 to +5.05 volts dc. If voltage is not within limits, adjust potentiometer shaft on edge of +5v regulator board (refer to Section 3 of this manual).
  - b. Measure -5v. Meter shall read -4.95 to -5.05 volts dc. If voltage is not within limits, adjust potentiometer shaft on edge of -5v regulator board (refer to Section 3 of this manual.)
- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- 7. Disconnect Off Line Tester: Set UNIT POWER circuit breakers to OFF. Disconnect tester from drive. Install logic chassis card cover. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

#### LEVEL 4 MAINTENANCE PROCEDURES

#### CLEAN SHROUD AND SPINDLE

 Remove disk pack: Press START switch to stop spindle motor. Open Pack access cover and remove disk pack (leave pack access cover open). 2. Clean shroud: Using lint-free gauze that is slightly dampened (not soaked) with media cleaning solution, wipe shroud to remove all dirt and smudges.

#### CAUTION

Do not allow media cleaning solution to run into spindle or bearing damage could occur.

- 3. Clean spindle: Using lint-free gauze that is slightly dampened (not soaked) with media cleaning solution, wipe spindle top surface to remove all dirt and smudges.
- 4. Remove any remaining particles: Use a wad of adhesive-type tape and pick up any particles that were not picked up with gauze.
- 5. Close pack access cover.

#### CLEAN AND LUBRICATE LOCKSHAFT

- 1. Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover and remove disk pack (leave pack access cover open).
- Clean top of spindle: Use (dry) lintfree gauze and a brush or sharp instrument to clean lockshaft threads on top end of spindle.
- Lubricate lockshaft: Apply a thin coat of lubricant paste to the lockshaft threads.
- 4. Check lockshaft movement: Check for free movement of lockshaft by depressing lockshaft and checking that it freely returns to its original position. If lockshaft does not depress or stays depressed, replace lockshaft.
- 5. Close pack access cover.

#### CLEAN CARRIAGE RAILS AND BEARINGS

- Remove disk pack: Press START switch to stop spindle motor. Open pack access cover and remove disk pack (leave pack access cover open).
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- 3. Install head cam tool: Install head cam tool per Manual Carriage Positioning With Power Off procedure (located in Section 3 of this manual).

- 4. Open cabinet top cover and remove deck cover. Clean rails and bearings per following steps:
  - a. Using lint-free gauze that is slightly dampened (not soaked) with media cleaning solution, wipe rails and bearing surfaces (Figure 2-2).
  - b. Check rail and bearing cleanliness by manually moving carriage through operating range. If any resistance to free rolling is encountered, clean rails and bearings again. If problem still exists, have a qualified CE inspect actuator.
- 5. Remove head cam tool: Fully retract carriage and remove head cam tool.
- 6. Install voice coil yellow leadwire.
- Set UNIT POWER circuit breakers to ON and close cabinet rear door.
- Install deck cover. Close cabinet top cover and pack access cover.

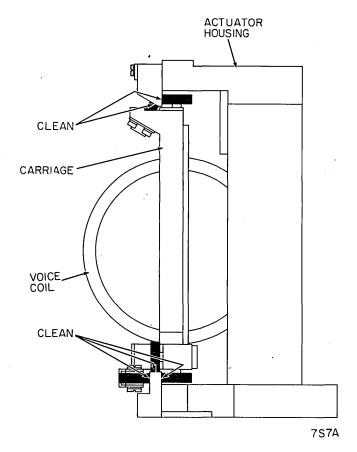


Figure 2-2. Carriage Rails and Bearings

#### LEVEL 6 MAINTENANCE PROCEDURES

#### REPLACE ABSOLUTE AIR FILTER

- Remove disk pack: Press START switch to stop spindle motor. Open pack access cover, remove disk pack and close pack access cover.
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- 3. Remove cabinet front panel.
- 4. Remove and clean primary air filter per the Clean Primary Air Filter procedure listed under Level 3 Maintenance Procedures in this section. (Do not install primary air filter until instructed to do so.)
- 5. Remove absolute filter:
  - a. Loosen turnbuckle securing plenum and air filter. Allow wire and turnbuckle to fall free.
  - b. Swing air plenum up and remove absolute filter.
- 6. Install replacement absolute filter:
  - a. Position replacement absolute filter in air plenum.
  - b. Position wire and turnbuckle over air filter and plenum. Tighten turnbuckle until plenum is secure.
- 7. Install primary filter: Position primary filter in bottom trough of air supply. While pressing upward on retaining clips, push filter against air supply and release retaining clips.
- 8. Install cabinet front panel.

#### CAUTION

In the next step the blower is run for several minutes to purge dust or dirt particles from unit. Do not install a disk pack until after purging unit.

 Set UNIT POWER circuit breakers to ON (ensure the blower starts). Allow blower to purge unit for two minutes before installing disk pack.

# SECTION 3

# CORRECTIVE MAINTENANCE

#### **CORRECTIVE MAINTENANCE**

#### SCOPE

This section contains the instructions for drive maintenance. The information is provided in the form of Electrical Checks and Adjustments, and Mechanical Corrective Maintenance.

Maintenance procedures listed within this section are written so that a person familiar with the procedure need only read up to the colon in each step of the procedure. Information listed after the colon is a detailed account of how to perform that step. It is recommended that the entire step be read before performing any action.

#### SAFETY PRECAUTIONS

Observe the following safety precautions at all times. Failure to do so may cause equipment damage and/or personal injury.

- Use care while working with power supply. Line voltages are present inside the ac power assembly.
- Keep hands away from actuator during seek operations and when reconnecting leads to voice coil. (Under certain conditions, emergency retract voltage may be present, causing sudden reverse motion and head unloading.)
- Use caution while working near heads.
   If heads are touched, fingerprints can damage them. Clean heads immediately if they are touched.
- Keep pack access cover closed unless it must be open for maintenance. This prevents entrance of dust into pack area.
- Keep all watches, disk packs, meters, and other test equipment at least two feet away from voice coil magnet when deck cover is off.
- Do not use customer disk pack; otherwise, customer data may be destroyed.
- Do not use CE alignment disk pack unless specifically directed to do so. These packs contain prerecorded alignment data that can be destroyed if test procedure requires drive to write. This alignment data cannot be generated in the field.
- If drive fails to power down when START switch is pressed (to turn off indicator) disconnect yellow leadwire to voice coil and manually retract heads before troubleshooting malfunction.

- Before manually moving carriage to load heads (disk pack not in place), install head cam tool per Manual Carriage Positioning procedure.
- Make certain that heads are unloaded before turning off power.
- If power to spindle motor is lost while heads are loaded and voice coil leadwire is disconnected, immediately retract carriage. Otherwise heads will crash when disk speed is insufficient to permit heads to fly.

#### MAINTENANCE PRELIMINARY CONDITIONS

#### OFF-LINE OPERATIONS

Certain procedures require execution of operational commands (seek, read, etc.). These commands can be generated by the Off-Line Tester. Refer to Reference Manual for instructions on installing and operating Off-Line Tester.

#### MANUAL POSITIONING OF HEADS WITH POWER OFF

Manually positioning of heads (with power off and/or disk pack removed) requires installation of the head cam tool. Install head cam tool as follows:

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover and remove disk pack (leave pack access cover open).
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Open cabinet top cover and remove deck cover.
- 4. Disconnect voice coil yellow leadwire.
- 5. Install head cam tool as follows:
  - a. With one hand, position head cam tool flush against head cam such that it is aligned with similar contour of head cam. Refer to Figure 3-1.
  - b. With other hand, move carriage forward until head/arm assemblies completely slide into head cam tool but do not protrude out of it.
  - c. Move head cam tool along with forward movement of head/arm assemblies until head/arm assembly cam surfaces pass free of the head cam.

- d. Release hold on head cam tool. Carriage is now free to move without damaging heads.
- Position carriage as required for maintenance procedure.
- 7. Remove head cam tool as follows:
  - a. Retract carriage until head/arm cam surfaces begin to contact head cam.
  - b. Grasp head cam tool using one hand.
  - c. With other hand, retract carriage until head/arm assemblies release hold on head cam tool. Remove tool.
- 8. Install voice coil yellow leadwire.
- Install deck cover, close cabinet top cover and pack access cover.
- 10. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

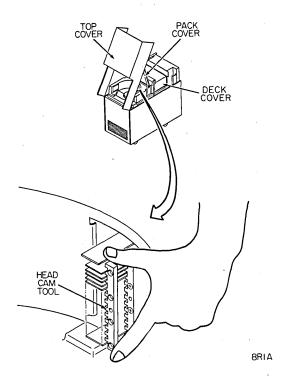


Figure 3-1. Head Cam Tool Installation

#### MANUAL POSITIONING OF HEADS WITH POWER ON

#### CAUTION

Manual loading and unloading of heads is not recommended unless required by the maintenance procedure.

Manually positioning of heads (with power on and disk pack up to speed) is possible if the voice coil yellow leadwire is removed. Manually position carriage as follows:

- 1. Observe following safety precaution during manual carriage operation.
  - Make certain that heads are unloaded before turning power off.
  - If power to spindle motor is lost while heads are loaded and voice coil leadwire is disconnected, immediately retract carriage. Otherwise heads will crash when disk speed is insufficient to permit heads to fly.
  - When positioning heads, do not use excessive downward force on coil.
  - Before reconnecting yellow leadwire, make sure fingers and tools are clear of coil and actuator. Rapid positioner movement will occur if difference counter contains a value other than 1023 or if an emergency retract condition exists.

#### NOTE

Do not use a CE disk pack unless specifically directed to do so. Use only the type of pack called for in the maintenance procedure.

- Install disk pack: Press START switch to stop spindle drive motor. Open pack access cover, install disk pack and close pack access cover.
- Press START switch and allow a normal power-up first seek.
- Open cabinet top cover and remove deck cover.
- 5. Disconnect voice coil yellow leadwire.
- Position carriage by grasping flange of coil assembly cap with fingers and moving forward or backward.
- 7. Perform desired maintenance procedure(s).

#### CAUTION

Keep hands away from actuator.

- 8. Install voice coil yellow leadwire.
- Install deck cover and close cabinet top cover.

#### MAINTENANCE TOOLS AND MATERIALS

The tools, test equipment, and materials recommended for drive corrective maintenance are listed in Table 3-1.

# **ELECTRICAL CHECKS AND ADJUSTMENTS**

#### INTRODUCTION:

The electrical checks and adjustments should be performed prior to replacing any parts. This ensures that apparent malfunctions are not caused simply by misadjustments. Also, these procedures should be performed whenever logic cards or other electrical components are repaired or replaced.

These checks and adjustments are divided into four sections:

- Power Supply Checks Checks power supply voltages, power sequencing, and data protection sensing.
- Servo Circuit Checks and Adjustments-Checks and adjusts circuitry involved in moving actuator to selected cylinder.
- Read/Write Circuit Checks and Adjustments - Checks read signal amplitude and checks/adjusts read recovery timing.
- Miscellaneous Logic Checks Checks logic and circuits not included above, such as power up blanking, start/stop time, sector sensing, etc.

Before performing any of the following procedures, be throughly familiar with the safety precautions and preliminary conditions specified earlier in this section.

#### **POWER SUPPLY CHECKS**

#### Introduction

The first power supply check, Sequencing Functional Check, provides a quick check of power supply sequencing. It does not, however, check all capabilities. For a complete power supply checkout, perform all tests.

Figure 3-2 is a troubleshooting guide that will assist in isolating malfunctions. Locations of parts within the circuit breaker box are illustrated in Figure 3-3; locations of parts within the ac power supply are illustrated in Figure 3-4, and locations

of parts within the dc power supply are illustrated in Figure 3-5.

#### CAUTION

Unless otherwise specified, sequence power from the controller should be off when performing any of these tests.

#### Sequencing Function Checks

This procedure provides a quick check of the power supply sequencing. Proceed as follows:

- Install a scratch disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove customer disk pack, install scratch disk pack and close pack access cover.
- Open cabinet rear door and set all power supply circuit breakers to OFF.
- 3. Set LOCAL/REMOTE switch to REMOTE.
- Open top cover from rear. Remove deck cover.
- Disconnect yellow leadwire from voice coil.
- Set ON LINE/OFF LINE/WRITE DISABLE switch to OFF LINE.
- 7. Set TAG LINE SELECT switch to INTERLOCK.
- 8. Set UNIT POWER circuit breakers to ON.
- 9. Check if blower motor is operating. If not, check:
  - a. Site ac power available at terminal board AlCBl.
  - b. UNIT POWER circuit breakers.
  - c. Relay AlK4.
  - d. +20Y supply as described below.
- 10. Check that +20Y indicator on dc power supply panel lights. If not, check for +22V at A2TB1-16 (terminal board on back of logic chassis). If present, bulb is defective. If absent, check +20Y fuses. If fuses are good, check dc power supply rectifier AlCR1-2+ and transformer AlT3.
- 11. Set +10v and -10v circuit breakers to ON.
- 12. Set LOCAL/REMOTE switch to LOCAL. Check that MAINTENANCE indicator on operator panel lights. If not:

TABLE 3-1. CORRECTIVE MAINTENANCE TOOLS AND MATERIALS

Description	Part Number	Description	Part Number		
Actuator Stop Adjustment Tool	CDC* 87008000	None-Mettalic Feeler Gage, 0.005 inch	CDC 12205600		
Adapter (3/16 Hex to 1/4 Sq)	CDC 12262582	Oscilloscope, Dual Trace	Tektronix 454 or equivalent		
Ball End Hex Driver (3/16 Hex)	CDC 12263201	Oscilloscope Hood	Tektronix 016-0083-00		
Card Extender (Half-Size)	CDC 54099700	Pin Straightener	CDC 87369400		
Card Extender (Full-Size)	CDC 54109700	Pulley Gage	CDC 87098800		
Card Extraction Tool	CDC 87399200	Push-Pull Gage	CDC 12210797		
Carriage Alignment Arm	CDC 87007900	Rail Adjustment Tool	CDC 87053600		
Carriage Alignment Ring	CDC 87389800	Removal Tool, 20-30 Gage	CDC 12259183		
CE Disk Pack	CDC 70430003	Scope Probe Tip (Hatchet Type)	CDC 12212885		
Chip Extender-Chip Cliplog Disk Pack (9883-61)	CDC 12212196 CDC 70430501	Shim Assortment (used for carriage stop adjustment when replacing actuator)	CDC 75039400		
Offline Tester	CDC 86073405	Spindle Adjustment Tool	CDC 87059900		
Grease, Slicone	CDC 95109000	Torque Screwdriver	CDC 12218425		
Head Adjustment Tool	CDC 75009100	Torque Screwdriver Bit	CDC 87016701		
Head Alignment Card	CDC 54226505	Torque Wrench, 1/4 inch	CDC 12263205		
Head Cam Tool	CDC 72842700	Volt/ohmmeter	Ballantine 345		
Head Installation and Removal Tool	CDC 73678500		or equivalent digital voltmeter		
Loctite, Grade C	Loctite Corp.	Wire Wrap Bit, 30 Gage	CDC 12218402		
Loctite Primer, Grade N	Loctite Corp.	Wire Wrap Gun, Electric	CDC 12259111		
Media Cleaning Solution	CDC 95033502	Wire Wrap Sleeve, 30 Gage	CDC 12218403		
*CDC is a registered trademark of Control Data Corporation.					

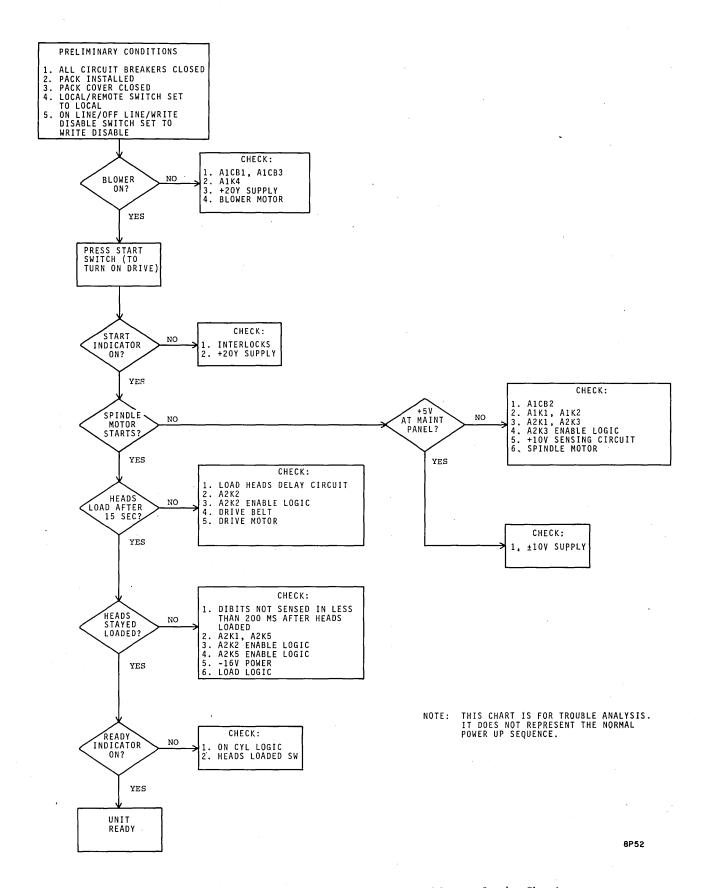


Figure 3-2. Power Sequencing Trouble Analysis Chart

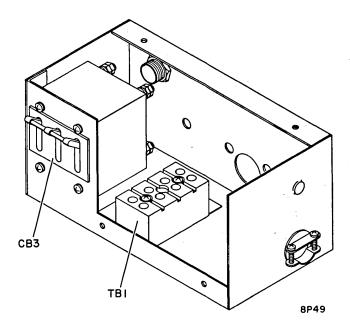


Figure 3-3. Circuit Breaker Box Locator

- a. Measure from +5v test point on maintenance panel to ground. If +5v present, proceed directly to step c; if absent, proceed to step b.
- b. Set +20v and -20v circuit breakers to ON. Measure these voltages from their respective test points on maintenance panel to ground. If +20v, -20v, and -5v are all absent, ac power panel Al and related rectifiers are not supplying dc voltages.
- c. This step applies if +5v is present in step a. Problem is caused by lack of operator panel lamp power or faulty logic. Measure from terminal A2TB1-5 to ground. If +20v, check lamp driver logic. If not +20v, sensing board A2A3 (+10v sense) is not supplying power to lamps on operator panel; perform Data Protection Sensing Check.
- d. This step applies if voltage other than +5v could be measured in step b. Problem is lack of +5v. Measure from terminal A2TB1-3 to ground. If +10v is not present at terminal A2TB1-3, check voltage at circuit breaker A2CB2-2. If voltage at circuit breaker A2CB2-2 is 10v, regulator A2A3 is faulty. If 10v is not present, check circuit breaker A2CB2, rectifier CR5-6+, and terminal A1T2.

13. Set remaining circuit breakers to ON.

#### NOTE

If any of the following conditions are not met, refer to Sequencing Safety Check for troubleshooting information.

- 14. Press START switch to start spindle drive motor. If START indicator does not light, check interlocks. Observe that spindle motor starts.
- 15. Wait 15 seconds (for load heads delay to time-out), then manually move actuator forward until heads loaded switch transfers. Bit 2 on maintenance panel lights when TAG LINE SELECT switch is set to INTERLOCK.
- 16. Check following ADDRESS & CONTROL BUS indicators on maintenance panel.

Bit	Correct State	Function	If wrong, check
0	on	Pack On	Switch (motor will not start)
1	on	Control Interlocks	Switch (motor will not start)
2	off off	Heads Loaded	Switch
3	off	Not Load Heads	Switch
4	on	START	Switch (lamp will not light)
5	on	LOCAL	Switch (dc voltages dis- abled)
6	on	Spindle Motor	Relay A2K3 and logic
7	on*	Logic Cooling Air	Switch/dirty filter
. 8	on*	Logic Temp	Switch/dirty filter

\*When on, indicate that temperature is normal.

- 17. Continue to move actuator forward until heads are fully loaded on pack, then retract actuator until head/arm cam surfaces begin to touch head cam. Stop retract motion at this position.
- 18. Reconnect yellow leadwire to voice coil. It should not retract. If it does perform Data Protection Sensing Check. (Retract relay A2K5 is de-energized, causing emergency retract condition.)

anny GET FAULT

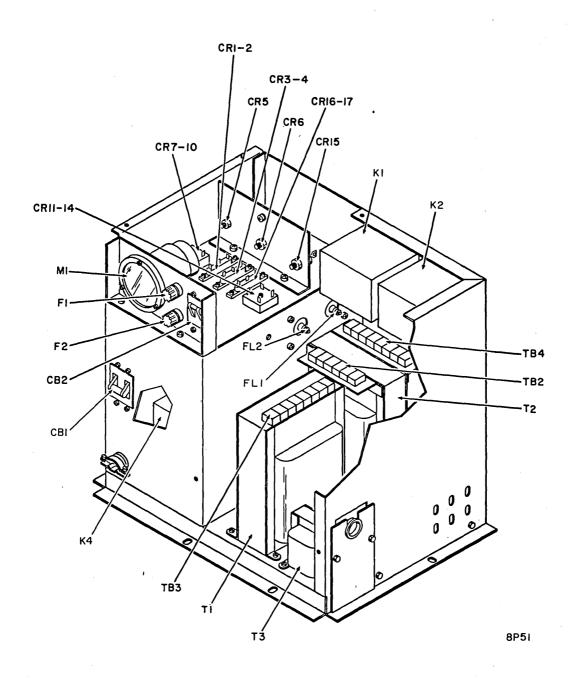


Figure 3-4. AC Power Supply Locator

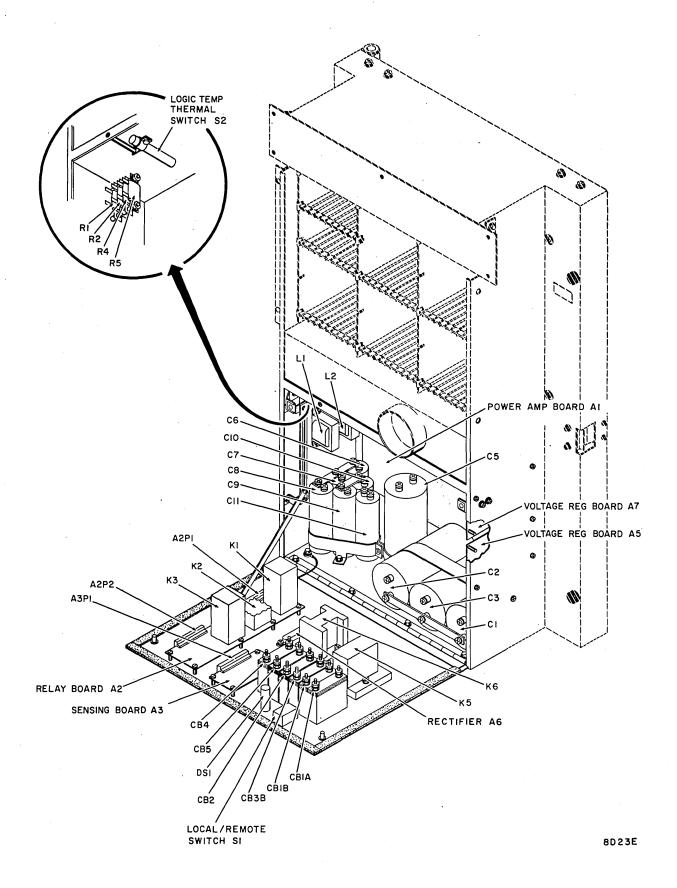


Figure 3-5. DC Power Supply Locator

7A

19. Set UNIT POWER circuit breaker ( 15A) to OFF. Carriage must immediately retract (simulated emergency retract condition). If not, immediately retract heads manually to prevent them from crashing as spindle motor slows. Check retract relay A2K5 for sticking and check actuator for open coil or broken straps.

#### Output Voltage's Check

Perform the following check with the drive performing continuous 256-track seeks. The +5v and -5v adjustment procedures are located in Check Power Supply Outputs of Section 2 in this manual. The other voltages are not adjustable. With the exception of the +46v, -46v, and +20Y power, all measurements should be made by connecting a voltmeter between the applicable test point and ground on the maintenance panel. The following voltages shall be present:

- 1. +20 (+2.4, -0.2) vdc.
- 2. -20 (-2.4, +0.2) vdc.
- 3. +5.10 (±0.05) vdc.
- 4. -5.10 (±0.05) vdc.
- 5. Measure +20Y by connecting positive 1 lead of meter to terminal A2TB1 and negative lead to ground. It must be +22 (±2.5) vdc. This terminal board is on the wire wrap side of the logic chassis.
- Measure +46v and -46v at terminal board A2TB2 on the back of the logic chassis. Ground is available on terminal A2TB2-3.
  - a. +46 (±2) vdc at terminal A2TB2-10.
  - b. -46 (±2) vdc at terminal A2TB2-11.

## Interlock Switches Check

This procedure verifies that the power interlocks are functioning. The pack need not be installed. Proceed as follows:

- Open cabinet rear door and set LOCAL/ REMOTE switch on power supply to REMOTE.
- 2. Set all circuit breakers to ON.
- 3. Close all covers.
- 4. Press START switch (to light indicator). Indicator must light; if not, check interlock test points specified in following step. If they are all at ground, remove lens and lamp; check socket for +20v and ground.

- 5. Check interlock circuit at three test points on terminal boards on wire wrap side of the logic chassis. The following test points will be at ground potential if the specified conditions are met:
  - a. Terminal A2TB2-15 is at ground if +10v and -10v circuit breakers auxiliary contacts are closed.
  - b. Terminal A2TB1-11 is at ground if condition a is met and if +46v, -46v and ±20v circuit breakers auxiliary contacts are closed.
  - c. Terminal A2TB1-10 is at ground if conditions a and b are met and if pack cover is closed.
  - d. Terminal A2TB1-14 is at ground if conditions a, b, and c are met and START switch is on.
- Open pack access cover. START indicator must go out; if not, pack cover interlock may be defective.
- Close pack access cover and note that START indicator lights again.
- Press START switch (to turn off indicator) and turn off all circuit breakers.

## Sequencing Safety Checks

This procedure verifies that the power sequencing interlocks and logic are functioning correctly. Start this procedure without a pack installed. Proceed as follows:

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- Open top cover from rear and remove deck cover.
- 3. Disconnect voice coil yellow leadwire.
- Open cabinet rear door and set all circuit breakers to ON.
- 5. Press (to light indicator) START switch.
- 6. Set LOCAL/REMOTE switch on power supply to LOCAL. Observe the following:
  - a. Drive motor does not start. If it does, check that bit 0 (Pack On) indicator of ADDRESS AND CONTROL BUS indicators is off. If it is on, pack on switch is misadjusted or defective, proceed to step b.

- b. Check that bit 6 (Spindle Motor) is off. If on, motor relay A2K3 is energized; logic is defective. (Motor should not start with pack off. Also, if motor does start, speed relay A2K2 should not pick: without pack installed, lack of sector pulses should inhibit speed enable.)
- c. Bit 1 indicator (Control Interlocks) should be on.
- Press (to turn off indicator) START switch.
- 8. Install a scratch disk pack: Open pack access cover, install scratch disk pack and close pack access cover. Verify that bit 0 lights.
- Press (to light) START switch. Observe effects specified in steps 10 and 11.
- 10. Spindle motor must start. If not:
  - a. Check for ground at logic pin Bl2-8A. If at +20v, logic is faulty. If at ground, wiring or +10v sense of sensing board A2A3 is faulty. (The +10v sense is required to pull speed relay A2K2 and motor relay A2K3.
  - b. Check if motor relay A2K3 is energized. If it is energized, check motor relays A1K1 and A1K2. If they are energized, check motor.

Normally, speed is attained before completion of load heads delay (15 sec). This energizes speed relay A2K2 which, in turn, energizes retract relay A2K5. If spindle motor is not up to speed before completion of load heads delay, speed detection enable circuit is disabled by Speed Enable FF and speed relay A2K2 remains de-energized. Heads cannot load during load heads delay.

- 11. When up to speed, and with TAG LINE SELECT switch set to INTERLOCK, manually move actuator forward until heads loaded switch transfers. Bit 2 on maintenance panel lights when TAG LINE SELECT switch is set to INTERLOCK. Holdback relay A2K6 must be energized. If not, heads loaded switch is faulty or misadjusted.
- 12. Press (to extinguish) START switch.
  Motor must not start to slow because
  heads are still loaded. If it does,
  immediately retract heads to prevent
  head crashing and check logic.
- 13. Move actuator to reverse stop. Observe that pack stops rotating.

- 14. Reconnect voice coil yellow leadwire.
- 15. Install deck cover and close cabinet top cover.
- 16. Remove scratch disk pack: Open pack access cover, remove scratch disk pack and close pack access cover.
- 17. Close cabinet rear door.

#### Data Protection Sensing Check

This procedure verifies that the sensing function of board A2A3 will prevent writing during an emergency retract. This procedure also checks voltage fault detection and generates an emergency retract condition.

- Install a scratch disk pack: Open pack access cover, install a scratch disk pack and close pack access cover.
- Open cabinet top cover and remove deck cover.
- 3. Disconnect voice coil yellow leadwire.
- 4. Set ON LINE/OFF LINE/WRITE DISABLE switch to ON LINE.
- Set TAG LINE SELECT switch on maintenance panel to INTERLOCK.
- 6. Set all circuit breakers to ON.
- If necessary, press (to turn off indicator START switch.

## NOTE

While performing steps 8 and 9 observe operator panel indicators.

- Set LOCAL/REMOTE switch to LOCAL.
   Indicators must not blink except for unit number indicator. Drive motor must not jerk.
- 9. Set LOCAL/REMOTE switch back to REMOTE. Indicators must not blink and drive motor must not jerk. If conditions of steps 8 and 9 are not met:
  - a. Check transistors A2A3Q4, Q5 and Q7 (along with their associated circuitry) on sensing board A2A3. This is +10v sense function. Lamp drivers and relays A2K2 and A2K3 also receive power from +10v sense circuit.
  - b. If +10v power drops, this sensing circuit should drop speed relay A2K2 to prevent write power during emergency retracts, before remainder of dc power decays.

- 10. Set LOCAL/REMOTE switch to LOCAL.
- 11. Set ON LINE/OFF LINE/WRITE DISABLE switch to OFF LINE.
- 12. Discharge emergency retract capacitor by temporarily touching voice coil yellow leadwire to voice coil terminal. Then make sure yellow leadwire is disconnected.

#### CAUTION

When performing step 13 move heads forward far enough to cause heads loaded switch to transfer, but not far enough so that heads contact each other; otherwise, heads will be damaged.

- 13. Move actuator forward until bit 2 (Heads Loaded) indicator lights.
- 14. Fully retract heads.
- 15. Set TAG LINE SELECT switch to FAULT.
  Observe that FAULT bit 2 (Current),
  and bit 4 (-Volt) indicators are on.
  If not:
  - a. Current fault is result of write driver circuitry sensing that heads loaded switch has transferred and that +20v write voltage is off because speed relay A2K2 is deenergized.
  - b. -Volt fault is sensed by transistor A2A3-Q1 because heads are loaded and -16v volt emergency retract voltage is inadequate when switch first closes.
- 16. Reconnect yellow leadwire to voice coil.
- 17. Press FAULT switch to clear error.
- 18. Install a scratch disk pack: Open pack access cover, install a scratch disk pack and close pack access cover.
- 19. Press START switch (to turn on indicator).
- 20. After heads load, set UNIT POWER circuit breakers to OFF. Observe that carriage immediately retracts. This is emergency retract function provided by capacitor A2C2 and normally closed contacts of retract relay A2K5.
- 21. Remove scratch disk pack: Open pack access cover, remove disk pack and close pack access cover.
- 22. Install deck cover and close cabinet top cover.
- 23. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

#### Normal Retract Check

This procedure verifies that the sensing function of board A2A3 allows the actuator to retract at the normal controlled velocity when system sequence power is dropped. A pack need not be installed. Proceed as follows:

- 1. Open cabinet rear door.
- 2. Set LOCAL/REMOTE switch to REMOTE.
- Open cabinet top cover and remove deck cover.
- Make sure voice coil yellow leadwire is connected to its proper terminal.
- Set TAG LINE SELECT switch on maintenance panel to INTERLOCK.

## CAUTION

While performing step 6, move heads forward far enough to cause heads loaded switch to transfer, but not far enough so that heads contact each other, other wise heads will be damaged.

- 6. Move actuator forward until bit 2 (Heads Loaded) indicator lights. An immediate hold back force should be encountered. If not:
  - a. Check for +5v at maintenance panel. If absent, proceed to step b; if present, proceed to step c.
  - b. Check transistor A2A3Q3 and its associated components on sensing board A2A3. This transistor holds 5v power on during a normal retract until the heads unload.
  - c. Fault is caused by relay A2K6 malfunctioning. When heads loaded switch transfers, relay A2K6 should be energized to connect retract capacitor A2C2 to -16v.

## Speed Backup Check

This procedure verifies that the heads cannot load until speed is attained. This function is normally under logic control; however, if the primary speed detection logic fails, the speed backup circuitry should also prevent the heads from loading onto a slow pack. Proceed as follows:

- Open cabinet rear door and set LOCAL/ REMOTE switch on power supply to REMOTE.
- 2. Verify that +20Y indicator is on.
- 3. Open dc power supply front panel.

4. Remove protective cover from speed relay A2K2.

## CAUTION

Perform step 5 gently to prevent damage to relay contacts.

- 5. Press relay A2K2 clapper. Verify that retract relay A2K5 does not energize. If it does:
  - a. Check pin A2A3P1-13 (drive motor interlock to sensing board A2A3). If not ground, motor centrifugal switch is malfunctioning. This switch should remain closed (providing ground) until motor speed exceeds about 2,000 rpm.
  - b. If test point in step a is ground, check transistors A2A3Q6 and Q2 and their associated circuitry on board A2A3.
- 6. Replace relay A2K2 relay cover.
- 7. Close dc power supply.
- Set LOCAL/REMOTE switch to LOCAL and close cabinet rear door.

## SERVO CIRCUIT CHECKS

Figure 3-6 is a simplified diagram of the servo circuit. This illustration indicates the primary test points used for checking and adjusting the servo loop along with a brief explanation of the various signals, their test points, and the applicable checkout procedure. Servo test point waveforms for various forward seek lengths are shown in Figure 3-7.

## General Checkout Criteria

Of the procedures listed in Figure 3-6, only the procedures listed below are adjustments, the remainder are checks to verify proper operation:

- Velocity Gain Adjustment
- Coarse Position Gain Adjustment
- Integrator Gain Adjustment
- Fine Position Offset Adjustment

Because the servo circuit is closed loop, all of the signals are interacting. Therefore, misadjustments may cause seek difficulties that appear to be hardware malfunctions. Check all adjustments before initiating detailed trouble analysis procedures. All adjustments should be checked if any servo loop cards have been replaced. All

adjustments must be made on a thermally stable unit with the deck cover installed. For thermal stabilization, perform 256-track repeated seeks for 15 minutes.

## Velocity Gain Adjustment

This procedure adjusts the gain of the velocity signal applied to the summing amplifier. The purpose of this procedure is to adjust the track following capability.

- Install a scratch disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove customer disk pack (if installed). Install a scratch disk pack and close pack access cover.
- 2. Connect Off Line Tester to drive: Open cabinet rear door and set UNIT POWER circuit breakers to OFF. Remove logic chassis card cover. Connect Off Line Tester to drive per installation instructions in the Reference manual.
- 3. Set oscilloscope control settings as follows:
  - CH 1 VOLTS/DIV: 100 mv
  - A TIME/DIV: 5 ms
  - A TRIGGERING: Positive/Internal
  - MODE TRIGGER: CHOP
- 4. Connect oscilloscope to drive as follows:
  - CH1 to test point D on card C30 (Fine Position Signal, A2405).
  - A Triggering to test point Y on card C30 (square wave generator, X2502).
- 5. Perform 15 minutes of 256-cylinder repeat seeks for thermal stabilization and stop heads at cylinder 000: Set UNIT POWER circuit breakers to ON. Press START switch to start spindle drive motor and to load heads. Using Off Line Tester, command drive to perform 256-cylinder repeat seeks for 15 minutes. Stop heads at cylinder 000.

#### NOTE

Perform test at cylinder 000 and then retest at cylinder 822.

- Enable square wave generator: Remove back panel from cabinet rear door. Connect a wire from C30-01A to C30-16B.
- 7. Adjust vertical position control on scope to move trace up until area "A" in Figure 3-8 is centered on the middle graduation of scope.

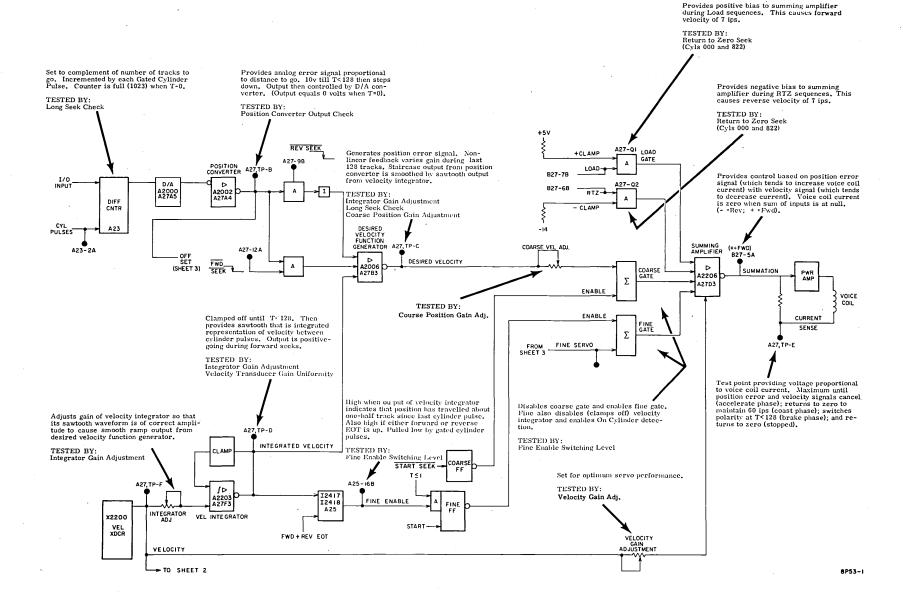


Figure 3-6. Servo System Test Points (Sheet 1 of 3)

UNLOAD HEADS . SPEED

A25,TP-G

SEEK

Figure 3-6. Servo System Test Points (Sheet 2 of 3)

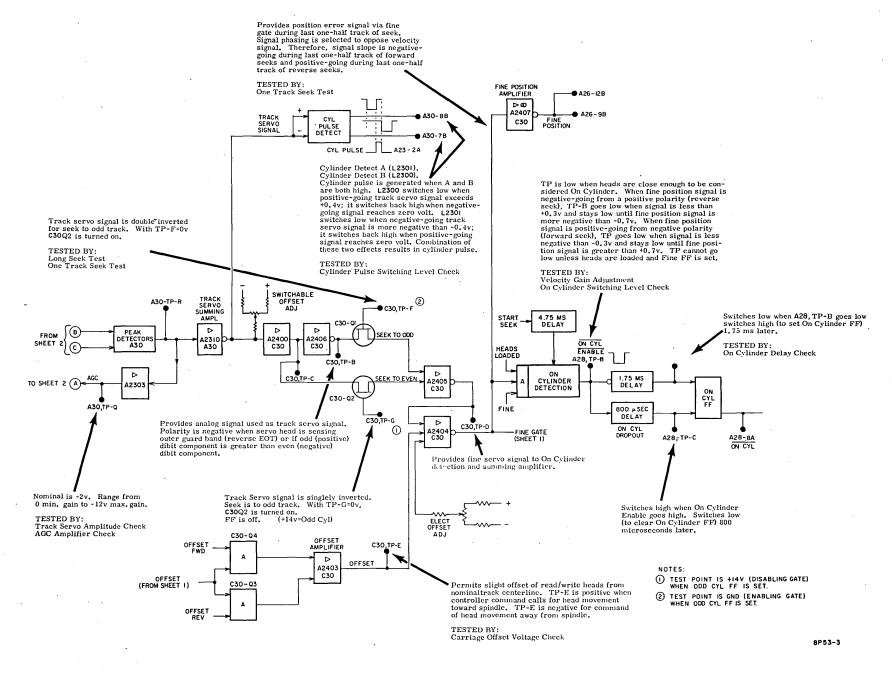


Figure 3-6. Servo System Test Points (Sheet 3 of 3)

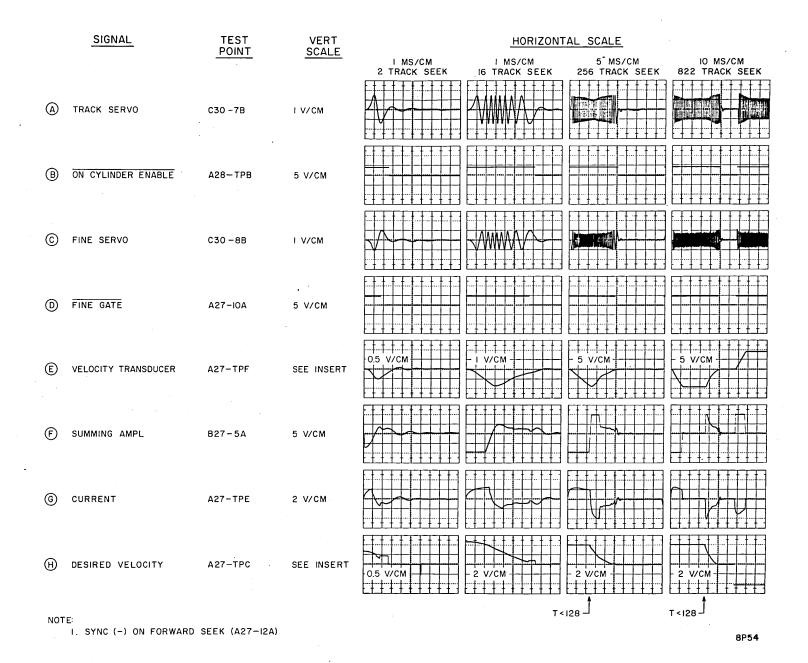


Figure 3-7. Forward Seek Waveforms

- Adjust velocity gain pot (middle pot) on A27 until first overshoot (point "B" on Figure 3-8) is between 200 to 300 mv (2 to 3 divisions) below center graduation of scope.
- 9. Adjust vertical position knob on scope to move trace until area "C" (of Figure 3-9) is centered on middle graduation of scope. The first overshoot (point "D" of Figure 3-9) must be between 200 to 300 mv (2 to 3 divisions) above the center graduation on scope. If overshoot is too high or too low, readjust velocity gain pot so that both positive (point "D", Figure 3-9) and negative (point "B", Figure 3-8) overshoots have at least an 80% occurrence within 200 to 300 mv.
- 10. When adjustment is complete, remove wire used to enable square wave generator.
- Perform Coarse Position Gain Adjustment immediately.

#### Coarse Position Gain Adjustment

This procedure must be done in conjunction with the Velocity Gain Adjustment and the Integrator Gain Check and Adjustment procedures. These procedures interact with each other and must be repeated to verify that both procedures meet their requirements.

## NOTE

The Course Position Gain Adjustment must be made when thermal stabilization exists. It is not an indication of malfunction if the requirements of this adjustment are not met during extreme limits of operation, such as prior to warmup or after several hours of continuous seeking.

- Install a scratch disk pack: Press START switch to stop spindle drive motor. Open pack access cover and remove customer disk pack if installed. Install scratch disk pack and close pack access cover.
- 2. Connect Off Line Tester to drive: Open cabinet rear door. Set UNIT POWER circuit breakers to OFF. Remove logic chassis card cover and cabinet rear door panel. Connect Off Line Tester to drive per installation instructions in Reference manual.
- 3. Set oscilloscope control settings as follows:

- CH 1 VOLTS/DIV: 0.5
- CH 2 VOLTS/DIV: 1
- A and B TIME/DIV: 10 ms
- A TRIGGERING: Negative/External
- 4. Connect oscilloscope to drive as follows:
  - CH 1 to test point D on card C30 (Fine Position Signal, A2405).
  - CH 2 to test point E on card A27 (Summing Amp Output, A2206).
  - A TRIGGERING to wirewrap pin A27-12A (Forward Seek, A2001).
- 5. Command drive to perform 256-cylinder repeat seeks with either a Read or Write operation after each seek: Set UNIT POWER circuit breakers to ON. Press START switch to start spindle drive motor and to load heads. Using Off Line Tester, command a 256-cylinder repeat seeks with a Read or Write operation after each seek.
- 6. Adjust coarse position gain (top pot)
  A27 on so that point A (Figure 3-10)
  lies between the 14th and 15th negative
  pulses. Allow the drive to access at
  this adjustment for 1 minute to allow
  temperature stabilization. Readjust
  if necessary.
  - 7. Proceed to Integrator Gain Adjustment and then return to step 6 of this procedure. Repeat until both adjustments meet their respective limits.
  - 8. If the requirements of steps 6 and 7 are met go to step 9. If requirements of steps 6 and 7 cannot be met, troubleshoot drive servo logic (refer to Servo Margin Test procedure).
  - Remove scratch disk pack: Press START switch to stop spindle drive motor.
     Open pack access cover, remove disk pack and close pack access cover.
- 10. Disconnect Off Line Tester: Set UNIT POWER circuit breakers to OFF. Disconnect Off Line Tester from drive. Install logic chassis card cover and cabinet rear door panel. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

Integrator Gain Check and Adjustment

This procedure must be done in conjunction with the Coarse Position Gain Adjustment

LOGIC GND TO SCOPE GND

VOLTS / DIV

CH I - IOO MV/DIV

CH 2 - NOT USED

TIME / DIV

A- 5 MS/DIV

B - NOT USED

TRIGGERING

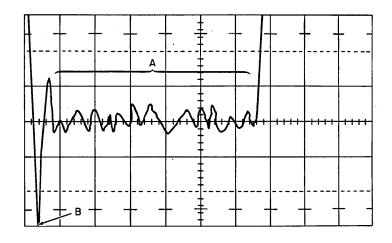
A- POS/EXT ON C30-TPY

B- NOT USED

PROBE CONNECTIONS

CHITO C30-TPD

CH 2 NOT USED



8P55

Figure 3-8. Velocity Gain Waveform (Preliminary)

# OSCILLOSCOPE SETTINGS

LOGIC GND TO SCOPE GND

VOLTS / DIV

CH I - IOO MV/DIV CH 2 - NOT USED

TIME / DIV

A - 5MS/DIV

B - NOT USED

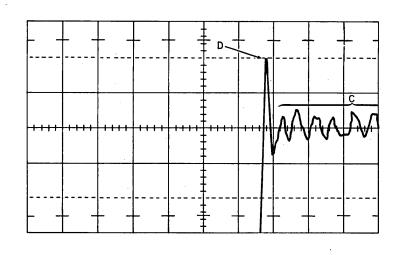
TRIGGERING

A- POS/EXT ON C30-TPY B- NOT USED

PROBE CONNECTIONS

CHITO C30-TPD

CH 2 NOT USED



8P56

Figure 3-9. Velocity Gain Waveform (Final)

LOGIC GND TO SCOPE GND

**VOLTS / DIV** 

CH I - 0.5V/DIV CH 2 - IV/DIV

TIME / DIV (MAGNIFY BY IO)

A- IOMS/DIV

B - IOMS/DIV

#### TRIGGERING

A- NEG/EXT ON A27-12A

**B-NOT USED** 

PROBE CONNECTIONS

CHITO C30-TPD

CH 2 TO A27-TPE

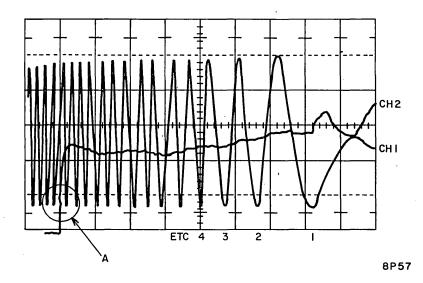
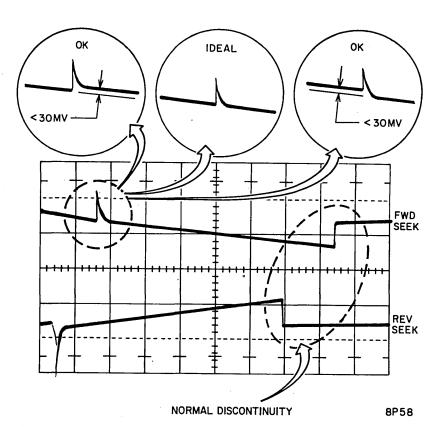


Figure 3-10. Coarse Position Gain Waveform

procedure. The adjustments in these procedures interact with each other and must be repeated until both procedures meet their requirements.

- Install a scratch disk pack: Press START switch to stop spindle drive motor. Open pack access cover and remove customer disk pack (if installed). Install a scratch disk pack and close pack access cover.
- 2. Connect Off Line Tester to drive: Open cabinet rear door and set UNIT POWER circuit breakers to OFF. Remove logic chassis card cover and rear door panel. Connect Off Line Tester to drive per installation instructions in Reference manual.
- 3. Set oscilloscope control settings as follows:
  - CH 1 VOLTS/DIV: 0.2
  - A TIME/DIV: 2 ms
  - A TRIGGERING: Negative/External
  - HORIZ DISPLAY MAG: X10
- 4. Connect oscilloscope to drive as follows:
  - CH 1 to test point C on card A27 (Desired Velocity, A2705)
  - A TRIGGERING TO wirewrap pin A27-11A (Coarse, K2201)

- 5. Command a continuous repeated seek between cylinders 000 and 032: Set UNIT POWER circuit breakers to ON. Press START switch to start spindle drive motor. Using Off Line Tester, command drive to continuously seek between cylinders 000 and 032.
- Adjust scope controls to display waveform shown in Figure 3-11.
- 7. Observe waveform on scope. Forward and reverse seek waveforms should have smooth slopes and contain no discontinuities other than 100 to 500 mv transient spikes (The last discontinuity, just before the waveform settles out to about 0.7 volt, is normal. This is the point that the integrator gain increases when the Fine FF sets).
- 8. Observe last transient spike (refer to Figure 3-11); it should be ≤30 mv. Ideally, there should be no step, only a transient spike (refer to ideal insert in Figure 3-11). If not within limits, go to step 9. If within limits go to step 10.
- 9. If required, adjust potentiometer on A27 to bring the step at the last transient spike to ≤30 mv.
- 10. Return to step 6 of Coarse Position Gain Adjustment. When the requirements of this procedure (Integrator Gain Check and Adjustment) and the Coarse



LOGIC GND TO SCOPE GND

**VOLTS / DIV** 

CH I - 0.2V/DIV CH 2 - NOT USED

TIME / DIV (MAGNIFY BY 10)

A- 2 MS/DIV

B - NOT USED

TRIGGERING

A- NEG/EXT ON A27-IIA

B- NOT USED

PROBE CONNECTIONS (USE IOX PROBES)

CHITO A28-TPC

CH 2 NOT USED

Figure 3-11. Velocity Integrator Waveform

Position Gain Adjustment are met, proceed to step 11.

- 11. Remove scratch disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- 12. Disconnect Field Test Unit from drive:
  Set UNIT POWER circuit breakers to OFF.
  Disconnect Off Line Tester from drive.
  Install logic chassis card cover and
  cabinet rear door panel. Set UNIT POWER
  circuit breakers to ON and close cabinet rear door.

# Servo Margin Test:

This procedure is intended to be a troubleshooting aid and not an adjustment procedure. Perform this test after adjusting the velocity gain, coarse position gain, and integrator gain.

- Perform steps 1 through 5 of the Coarse Position Gain Adjustment procedure and then return to step 2 of this procedure.
- Adjust coarse position gain (top pot on card A27) so that point A of Figure 3-10, lies on the 7th negative pulse.
- Perform five minutes of random access seeks (no read/write functions). No access errors should occur.
- 4. Access errors indicate:
  - a. Velocity gain misadjusted.
  - b. Velocity tranducer defective. Excessive velocity drift causes point A shown on Figure 3-10 to move towards first pulse.
  - c. Defective servo cards or servo head.

- Readjust coarse position gain (top pot on card A30) so that point A (Figure 3-10) lies between 14th and 15th negative pulses.
- 6. Remove scratch disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- 7. Disconnect Off Line Tester: Set UNIT POWER circuit breakers to OFF. Disconnect Off Line Tester from drive. Install logic chassis card cover and cabinet rear door panel. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

## On Cylinder Delay Check

This procedure is intended as a useful troubleshooting aid and is not an adjustment.

- Install a scratch disk pack: Press START switch to stop spindle motor. Open pack access cover and remove customer disk pack (if installed). Install scratch disk pack and close pack access cover.
- 2. Connect Off Line Tester to drive: Open cabinet rear door and set the UNIT POWER circuit breakers to OFF. Remove logic chassis card cover and cabinet rear door panel Connect Off Line Tester to drive per installation instructions in the Reference manual.
- 3. Set oscilloscope controls as follows:
  - CH 1 VOLTS/DIV: 1
  - CH 2 VOLTS/DIV: 1
  - A and B TIME/DIV: 2 ms A/定句/デメー
  - A TRIGGERING: Positive External
  - MODE TRIGGER: CHOP
- 4. Connect oscilloscope to drive as follows:
  - CH 1 to test point B on card A28 (On Cylinder Detection, I2101)
  - CH 2 to wirewrap pin A28-08B (On Cylinder I2104)
  - A TRIGGERING to test point B on card A28
- 5. Command drive to perform one-cylinder repeated seeks: Set UNIT POWER circuit breakers to ON. Press START switch to start spindle motor and to load heads. Off Line Tester, command drive to perform one-cylinder repeated seeks.

- 6. Observe scope and determine time channel 1 is a logical 1. It shall be a logical 1 for 4.75 (±0.5) ms.
- Observe scope and determine time channel 2 is a logical 0. It shall be a logical 0 for 7.0 (±1.0) ms.
- 8. If requirements of steps 6 and 7 are not within limits, check card A28. If requirements are met, go to step 9.
- 9. Disconnect Off Line Tester and scope:
  Press START switch to stop spindle
  motor. Set UNIT POWER circuit breakers to OFF. Disconnect Off Line Tester and scope connections. Install
  cabinet rear door panel and logic card
  cover. Close cabinet rear door.
- 10. Remove scratch disk pack: Open pack access cover, remove scratch disk pack and close pack access cover.

# Fine Position Offset Check and Adjustment (Servo Offset Null/DC Offset Adjustment)

The intent of this procedure is to check (and if required, to adjust) the odd-toeven servo track signals for a null and to check/adjust the track servo a signal null.

- Install a scratch disk pack: Press START switch to stop spindle drive motor. Open pack access cover and remove customer disk pack (if installed). Install a scratch disk pack and close pack access cover.
- 2. Install test equipment: Open cabinet rear door and set UNIT POWER circuit breakers to OFF. Remove logic chassis card cover. Install test equipment as follows:
  - a. Connect Off Line Tester to drive per installation instructions in the Reference manual.
  - b. Insert head alignment card in card location C23.
  - c. Connect null meter to test points  $\boldsymbol{X}$  and  $\boldsymbol{Z}$  of head alignment card.
- Set ON LINE/OFF LINE/WRITE DISABLE switch on maintenance panel to WRITE DISABLE.
- 4. Set switches on head alignment card as follows:

3-21

- R/W-SERVO switch to SERVO
- X1/X.1 switch to X1
- N/P switch to P

#### NOTE

Perform 15 minutes of 256-cylinder repeat seeks (access seeks only) for thermal stabilization.

- Command a direct seek (access only) to cylinder 490.
- 6. Steps 7, 8, and 9 adjust the odd-toeven servo track signals to a null (servo electrical offset null adjustment). If unable to perform any of these adjustments, refer to Servo Fine Position Maintenance Criteria.
- 7. Note null meter reading at cylinder 490.
- Command a direct seek to cylinder 491 and note meter reading.
- 9. If the meter reading at cylinder 491 is not equal to the meter reading at cylinder 490, adjust the bottom potentiometer on card C30 so the reading at cylinder 491 moves toward the reading at cylinder 490. Switch between cylinders 490 and 491 while adjusting potentiometer until readings are equal.
- 10. Steps 11 to 14 adjust the track servo signal to null. This is the switchable offset (dc offset) adjustment to signal derived from track servo preamp. If unable to perform adjustment, refer to Servo Fine Position Maintenance Criteria.
- Command a seek to cylinder 490 and note meter reading.
- 12. Toggle the N/P switch on the head alignment card and adjust the top potentiometer on card at C30 so that the positive and negative readings move towards each other. Repeat procedure until readings are equal to within 2 mv.
- 13. Command a seek to cylinder 491 and verify track servo signal null (using N/P switch). If meter reading is not nulled, repeat procedure starting at step 5. If reading is nulled, go to step 14.
- 14. Make note of N/P meter readings at cylinders 8 and 800. Do not readjust potentiometers. If P-N differences are greater than 20 mv at cylinders 8 and 800, refer to servo Fine Position Maintenance Criteria. If less than 20 mv go to step 15.
- 15. Disconnect test equipment: Press START switch to stop spindle motor. Set UNIT POWER circuit breakers to OFF. Disconnect Off Line Tester, head alignment card, and null meter. Install logic card cover.

SCRATCH

- 16. Remove fCE disk pack: Open pack access
  cover, remove CE disk pack and close
  pack access cover.
- 17. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

#### **Fine Position Test**

#### NOTE

The requirements of the Fine Position Offset Check and Adjustment must be met before performing this test.

This test checks the track following capability of the drive and runout of the spindle. Runout is the degree to which a rotating object rotates off center. Too much runout causes the object to wobble or vibrate. Runout of the pack and spindle are additive, therefore a pack with known characterisitcs must be used (preferably a CE pack).

- Install a disk pack: Press START switch to stop spindle motor. Open pack access cover and remove customer disk pack (if installed). Install CE disk pack and close pack access cover.
- 2. Connect Off Line Tester to drive: Open cabinet rear door and set UNIT POWER circuit breakers to OFF. Remove logic chassis card cover and cabinet rear door pack panel. Connect Off Line Tester to drive per installation instructions in Reference manual.
- 3. Set oscilloscope controls as follows:
  - CH 1 VOLTS/DIV: 10 mv
  - A TIME/DIV: 2 ms
  - A TRIGGERING: Positive/External
  - HORIZ DISPLAY MAG: X10
- 4. Connect oscilloscope to drive as follows:
  - CH 1 to wirewrap pin C30-09B (Fine Position Signal, A2407)
  - A TRIGGERING to wirewrap pin B21-10B (Index, X2701)
- 5. Command direct seek to cylinder 400: Set UNIT POWER circuit breakers to ON. Press START switch to start spindle drive motor and to load heads. Using Off Line Tester, command a direct seek to cylinder 400.

#### NOTE

The signal measured in step 6 is the 60 Hz component of the displayed waveform. The waveform in Figure 3-12 is typical and may vary from drive to drive.

- 6. Observe waveform on scope. The average peak-to-peak value of the observed waveform should not exceed +150 or -150 mv. If value is within requirements, go to step 7. If value exceeds requirements, go to step 9.
- 7. Rotate pack 90 degrees: Press START switch to stop spindle drive motor.

  Open pack access cover. Remove disk pack, rotate disk pack 90 degrees and install disk pack. Close pack access cover. Press START switch to start spindle drive motor and to load heads. Command direct seek to cylinder 400.
- 8. Observe waveform on scope. The average peak-to-peak value should not exceed requirements of Figure 3-12. If value exceeds requirements, go to step 11. If within requirements, go to step 9.
- 9. Observe waveform on scope to determine where Fine Position signal synchronizes with Index (Figure 3-12).
- 10. Rotate pack 90 degrees: Perform step 7 of this procedure and then go to step 11.

#### NOTE

The point at which Index and the Fine Position Signal synchronizes may be different from pack to pack. However, the sync point (Index) will be the same for the pack under test, no matter how many times the disk pack is removed, rotated, and installed on the spindle because Index is derived from a pre-recorded code that was written on the disk pack servo track surface.

- 11. Observe waveform on scope to determine where Fine Position Signal synchronizes with respect to Index.
  - a. If the waveform coincides with the sync point as observed in step 9, the probelm is disk pack runout. Replace pack with a known good pack and repeat procedure starting at step 5.
  - b. If the waveform does not coincide with the sync point as observed in step 9, the problem is a defective spindle or servo head. Replace spindle or servo head and repeat the procedure.

## OSCILLOSCOPE SETTINGS

LOGIC GND TO SCOPE GND

**VOLTS / DIV** 

CH I - 10 MV/DIV CH 2 - NOT USED

TIME / DIV

A-2 MS/DIV

B - NOT USED

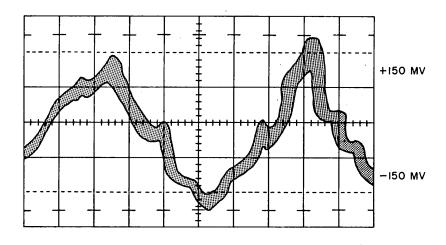
#### TRIGGERING

A- POS/EXT ON B21-10B

B- NOT USED

PROBE CONNECTIONS

CH I TO C30-09B CH 2 NOT USED



8P59

Figure 3-12. Fine Position Signal Modulation Waveform

#### Positioner Offset Check

- Install CE disk pack: Press START switch to stop spindle drive motor. Open pack access cover and remove customer disk pack (if installed). Install CE disk pack and close pack access cover.
- 2. Connect Off Line Tester to drive: Open cabinet rear door and set UNIT POWER circuit breakers to OFF. Remove logic chassis card cover. Connect Off Line Tester to drive per installation instructions in Reference manual.

#### CAUTION

The CE disk pack contains specially recorded tracks of data. Extreme care must be taken so that this data is not modified or destroyed.

- Open rear door and set ON LINE/OFF LINE/ WRITE DISABLE switch to OFF LINE.
- 4. Set UNIT POWER circuit breakers to ON.
- Load Heads: Press START switch to start spindle drive motor and to load heads.
- 6. Connect meter to test point E on card
- 7. Set CARRIAGE OFFSET switch to FWD.
- Measure the voltage test point E on card C30. It shall be -1.370 ±0.14 volts (200 microinch forward offset).
- 9. Set CARRIAGE OFFSET switch to REV.
- 10. Measure the voltage test point E card C30. It shall be +1.370 ±0.14 volts (200 microinch reverse offset).
- 11. Remove CE disk pack. Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.

#### Servo Fine Position Maintenance Criteria

Servo loop and servo data offset effects may be so large that the switchable offset (servo offset null) and electrical offset (dc offset) adjustments will not reduce error to acceptable limits. If unable to complete these adjustments, replace card at C30 or A27 for servo offset null, or replace card at A30 or servo head/arm assembly for the dc offset adjustments.

Dirty rails may affect null adjustments. If this seems to be a problem, seek to cylinders (460-461 instead of 490-491) and perform servo electrical offset null and do offset adjustment procedures. If requirements can be met at cylinders 460-461, clean rails and repeat adjustment procedure at cylinders 490-491.

P-N readings may deviate up to 20 mv at extreme cylinder positions (such as 8 and 800). This effect is normally due to variations in the disk pack air currents and head cable stresses at extreme positions. However, if mechanical parts have been changed (heads, carriage, head cable bracket, etc.), mechanical stresses may have developed which cause excessive deviation (P-N readings) at extreme cylinder positions. If P-N readings do not meet requirements at cylinders 8 and 800, check the following:

- Check head cables for binding, kinking, twisting, or oil canning.
- Check that head cables are properly clamped in clamping block, that cables have equal stress, and that none of the shields protrude from the rear of the clamping block.
- Check clamping block to see if it is twisted or bent.
- 4. Check for blockage that could affect air flow in pack area (clogged air filter, obstructions, etc.).

## Seek Timing Checks.

## Introduction

The seek timing checks verify correct overall servo loop operations. These tests are not necessarily requirements. Failure to pass any of these tests, however, indicates potential degraded performance that may cause difficulties at a later time. Steps 1, 2, and 3 immediately following prepare the drive for the seek timing checks. Steps 4 and 5 return drive to system operation.

- Install a scratch disk pack: Press START switch to stop spindle drive motor. Open pack access cover and remove customer disk pack (if installed). Install scratch disk pack and close pack access cover.
- 2. Install Off Line Tester: Open cabinet rear door and set UNIT POWER circuit breakers to OFF. Remove logic chassis card cover. Remove rear door panel. Connect Off Line Tester to drive per installation instructions in the Reference manual.

Perform all Seek Timing Checks; when complete go to step 4.

#### NOTE

If any problems exist, troubleshoot drive before proceeding. If drive meets all requirements of the Seek Timing Checks, perform the following steps:

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- 5. Disconnect Off Line Tester and oscilloscope: Set UNIT POWER circuit breakers to OFF. Disconnect Off Line Tester and scope from drive. Install logic chassis card cover and cabinet rear door panel. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

#### 256-Cylinder Seek

- 1. Set oscilloscope controls as follows:
  - CH 1 VOLTS/DIV: 1
  - A TIME/DIV: 10 ms
  - A TRIGGERING: Positive/Internal
- 2. Connect oscilloscope to drive as follows:
  - CH 1 to wirewrap pin A28-08A (On Cylinder, I2103)
- Command repeated seeks between cylinders 000 and 256: Press START switch to start spindle drive motor and to load heads. Using Off Line Tester, command repeated seeks between cylinders 000 and 256.
- 4. Observe scope waveform. Signal must be a logical 1 for 27 (+3,-2) ms. If not within requirement, perfrom Servo Margin Test procedure. If within limits, go to One-Cylinder Seek test. Do not change scope settings or connections until instructed to do so.

## One-Cylinder Seek

- Scope settings and connections same as for 256-Cylinder Seek test.
- 2. Command one-cylinder sequential seeks.
- 3. Observe waveform through at least 80 cylinders of seeks. Signal must be a logical 1 for 7 ±1 ms. If not within

requirements, perform Servo Margin Test Procedure. If within limits, go to Returnto-Zero Seek From Cylinder 000 test. Do not change scope settings or connections until instructed to do so.

#### Return-To-Zero Seek From Cylinder 000

- Scope settings and connections same as for 256-Cylinder Seek Test.
- 2. Command direct seek to cylinder 000.
- 3. Command an RTZ.
- 4. Observe scope waveform. Signal must be a logical 1 for 15 ±5 ms. If not within requirements, perform Servo Margin Test procedure. If within limits, go to Return-to-Zero Seek from Cylinder 822 test. Do not change scope settings or connections unless instructed to do so.

#### Return-To-Zero Seek From Cylinder 822

- Scope settings and connections same as for 256-Cylinder Seek test execpt set the A TIME/DIV to 100 MS/DIV.
- Command a single direct seek to cylinder 822.
- 3. Command an RTZ.
- 4. Observe scope waveform. Signal must be a logical 1 for 300 ±50 ms.
- 5. If not within requirements perform Servo Margin Test procedure. If within limits go to Seek Into Forward EOT test. Do not change scope settings or connections until instructed to do so.

## Seek Into Forward EOT

- Scope settings and connections same as 256-Cylinder Seek test except set the A TIME/DIV to 5 MS/DIV.
- 2. Command a direct seek to cylinder 822.
- Command a one-cylinder forward seek while observing scope.
- 4. Observe scope waveform. Signal must be a logical 1 for 20 ±5 ms. Command an RTZ to clear Seek Error status in drive logic.
- 5. If not within requirements perform Servo Margin Test procedure. If within limits, go to Velocity Transducer Linearity Test procedure.

## Velocity Transducer Linearity

- 1. Set oscilloscope controls as follows:
  - CH 1 VOLTS/DIV: 10 mv
  - CH 1 VOLTS/DIV: 10
  - A and B TIME/DIV: 2 ms
  - A TRIGGERING: Positive/External
  - MODE TRIGGER: ALT
- 2. Connect scope to drive as follows:
  - CH 1 to test point F on card A27 (Velocity Feedback, A2203)
  - CH 2 to wirewrap pin A27-10A (Fine Gate, K2200)
  - A TRIGGERING to wirewrap pin A22-07B (Forward Seek, I1532)
- 3. Command one-cylinder repeated seeks between cylinders 000 and 001.
- 4, Adjust scope controls to obtain waveform shown in Figure 3-13.
- 5. Observe waveform on scope. Signal on channel 1 (Velocity Feedback) should be 600 mv p-p and exhibits a double hump when channel 2 (Fine Gate) switches from a logical 1 to a logical 0.
- 6. Command one-cylinder repeated seeks between cylinders 821 and 822.

- 7. Observe waveform on scope. This waveform should be the same as the wavefrom observed when seeking between cylinder 000 and 001 (step 5).
- Perform an RTZ. Perform steps 4 and 5 listed in the introduction to Seek Timing Checks.

#### Track Servo Logic Checks

#### Introduction

These tests check the logic associated with the track servo. The tests are applicable only if servo adjustments could not be made or if troubleshooting a malfunctioning drive. Steps 1 and 2 immediately following prepare the drive for the Track Servo Logic Checks. Steps 4 and 5 return the drive to system operation. Perform whatever tests are deemed necessary at step 3.

- 1. Install a scratch disk pack: Press START switch to stop spindle motor. Open pack access cover and remove customer disk pack (if installed). Install a scratch disk pack and close pack access cover.
- 2. Connect Off Line Tester to drive: Open cabinet rear door and set UNIT POWER circuit breakers to OFF. Remove logic chassis card cover and cabinet rear door panel. Connect Off Line Tester to drive per installation instructions in Reference manual. Set UNIT POWER circuit breakers to ON.

# OSCILLOSCOPE SETTINGS

## LOGIC GND TO SCOPE GND

**VOLTS / DIV** 

CH I - 10 MV/DIV CH 2 - 20 V/DIV

TIME / DIV

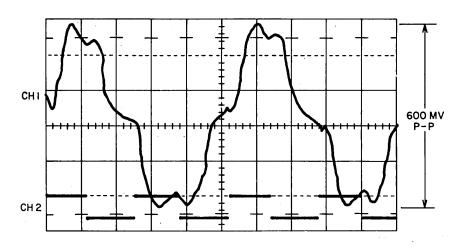
A-2 MS/DIV B-2 MS/DIV

## TRIGGERING

A- POS/EXT ON A22-07B B- NOT USED

PROBE CONNECTIONS (USE IOX PROBES)

CH I TO A27-TPF CH 2 TO A27-IOA



8P60

Figure 3-13. Velocity Linearity Waveform

- Perform any of the track servo logic checks as required.
- Remove scratch disk pack: Press START switch to stop spindle drive motor.
   Open pack access cover, remove scratch disk pack and close pack access cover.
- 5. Disconnect Off Line Tester from drive: Set UNIT POWER circuit breakers to OFF. Disconnect Off Line Tester from drive. Install logic card cover and cabinet rear door panel. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

## Track Servo Amplitude

This test checks the amplitude of the track servo signal output of the servo preamplifier. Perform steps 1 and 2 listed in the introduction to the Track Servo Logic Checks.

- 1. Set oscilloscope controls as follows:
  - CH 1 VOLTS/DIV: 0.5
  - CH 2 VOLTS/DIV: 0.5
  - A and B TIME/DIV: 20 ms /4522
  - A TRIGGERING: Positive/Internal
  - MODE TRIGGER: ADD
- 2. Connect oscilloscope to drive as
   follows:
  - CH 1 to wirewrap pin B30-03B (track servo preamp output)
  - CH 2 to wirewrap pin B30-05B (Track servo preamp output)
- Perform first six steps described in Manual Carriage Positioning With Power On.
- Manually move heads while observing scope. Monitor the maximum signal points (between cylinders) at cylinders 000 and 823.
- 5. The peak-to-peak amplitude of the observed signal must be between 0.36 and 2.1 volts. If not, check preamp card and servo head.
- Perform steps 8 and 9 of Manual Carriage Positioning With Power On.
- If drive maintenance or checkout is complete, perform steps 4 and 5 listed in the introduction of the Track Servo Logic Checks.

#### AGC Amplifier

This test verifies that the agc amplifier and the agc voltage are working correctly. Perform steps 1 and 2 listed in the introduction to the Track Servo Logic Checks.

- Remove logic card at location A30, install card on card extender and install extender and card in location A30.
- 2. Set oscilloscope controls as follows:
  - CH 1 VOLTS/DIV: 50 mv
  - CH 2 VOLTS/DIV: 50 mv
  - A and B TIME/DIV: -20 ms / 45
  - A TRIGGERING: Positive/Internal
  - MODE TRIGGER: ADD
- 3. Connect oscilloscope to drive as follows:
  - CH 1 to test point T on card A30 (Servo preamp output, A2508)
  - CH 1 to test point U on card A30 (Servo preamp output, A2508)
- Perform first six steps described in Manual Carriage Positioning With Power On.
- 5. Observe scope while manually moving heads near cylinder 000 so that horns of dibit waveform (one set positive, other set negative) are of equal amplitude (refer to Figure 3-14). Heads are now on cylinder.
- 6. The peak-to-peak amplitude of the observed signal must be 1 ±0.25 volt.
- Perform steps 8 and 9 of Manual Carriage Positioning With Power On.
- 8. If drive maintenance or check out is complete, perform steps 4 and 5 listed in the introduction of the Track Servo Logic Checks.

## Cylinder Pulse Switching Level

This test checks that the cylinder pulses are of uniform pulse width and amplitude over short and long seek lengths. Perform steps 1 and 2 listed in the introduction to the Track Servo Logic Checks.

1. Set oscilloscope controls as follows:

#### LOGIC GND TO SCOPE GND

**VOLTS/DIV** 

CH I - 50 MV/DIV CH 2 - 50 MV/DIV

TIME / DIV

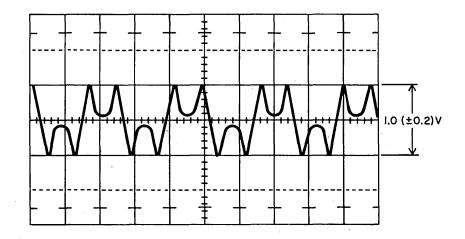
A-20-M5/DIV /4500 B-20-M5/DIV /4500

#### TRIGGERING

A- POS/INT B- POS/INT

# PROBE CONNECTIONS

CH | TO A30-TPT



8P61

Figure 3-14. AGC'ed Track Servo Amplitude

- CH 1 VOLTS/DIV: 0.1
- A TIME/DIV: 0.2 ms
- A TRIGGERING: Negative/External
- MODE TRIGGER: CH 1
- 2. Connect oscilloscope to drive as
   follows:
  - CH 1 to wirewrap pin A23-02A (Cylinder Pulses, I1810)
  - A TRIGGERING probe to wirewrap pin A22-07B (Forward Seek, I1532)
- Command repeated 4-cylinder seeks: Press START switch to start spindle drive motor and to load heads. Using Off Line Tester, command repeated 4cylinder seeks.
- 4. Observe waveform on scope. Check for a series of positive-going ΨΦ μsec pulses (cylinder pulses). Depending on system alignment the last pulse may be 1.2 μsec wide.
- 5. Command repeated seeks of varying lengths. Verify that cylinder pulses are consistently generated during long seek lengths. Press START switch to stop spindle drive motor. Go to step 6 if requirements are not met. Go to step 15 if within limits.
- 6. Connect oscilloscope to drive as follows:

- CH 1 to wirewrap pin A30-09B (Track Servo signal)
- A TRIGGERING to wirewrap pin A30-07B (Cylinder Detect A L2301)

#### NOTE

In the following steps the 3-cylinder seeks may be accomplished by manually positioning carriage or by using the Off Line Tester.

- 7. Command repeated 3-cylinder seeks: Press START switch to start spindle drive motor and to load heads. Using Off Line Tester, command repeated 3-cylinder seeks.
- 8. Observe waveform on scope. Check that servo signal is  $+0.4\ \pm0.1$  volt at beginning of the sweep.
- Set oscilloscope A TRIGGERING to positive.
- 10. Observe waveform on scope. Check that servo signal is 0  $\pm 0.1$  volt at beginning of sweep.
- 11. Change sync point to wirewrap pin
  A30-08B (Cylinder Detect B, L3200):
   Move A TRIGGERING probe to backpanel
   pin A30-08B (triggering is Positive/
  External).

- 12. Observe waveform on scope. Check that servo signal is 0  $\pm 0.1$  volt at beginning of sweep.
- Set oscilloscope A TRIGGERING to negative.
- 14. Observe waveform on scope: Check that servo signal at beginning of sweep is 0.4 ±0.2 volt.
- 15. If drive maintenance or check out is complete, perform steps 4 and 5 listed in introduction to the Track Servo Logic Checks.

## Velocity Logic Checks

## Introduction

These tests check the logic associated with the desired velocity logic. The tests are applicable only if the velocity adjustments could not be made or if troubleshooting a malfunctioning drive.

Steps 1 and 2 immediately following prepare the drive for the Velocity Logic Checks. Steps 4 and 5 return the drive to system operation. Perform whatever tests are deemed necessary.

- Install a scratch disk pack: Press START switch to stop spindle motor. Open pack access cover and remove customer disk pack (if installed). Install a scratch disk pack and close pack access cover.
- 2. Connect Off Line Tester to drive: Open cabinet rear door and set UNIT POWER circuit breakers to OFF. Remove logic chassis card cover and cabinet rear door panel. Connect Off Line Tester to drive per installation instructions in Reference manual. Set UNIT POWER circuit breakers to ON.
- Perform any of the velocity logic checks as required.
- Remove scratch disk pack: Press START switch to stop spindle drive motor.
   Open pack access cover, remove scratch disk pack and close pack access cover.
- 5. Disconnect Off Line Tester and oscilloscope from drive: Set UNIT POWER circuit breakers to OFF. Disconnect Off Line Tester from drive. Disconnect scope probes from drive. Install logic card cover and cabinet rear door panel. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

Fine Enable Switching Level

This procedure verifies that On Cylinder is enabled when the Fine Position Signal approaches null with the Fine FF set.

- Perform steps 1 and 2 listed in the introduction to the Velocity Logic Checks.
- 2. Set oscilloscope controls as follows:
  - CH 1 VOLTS/DIV: 5
  - CH 2 VOLTS/DIV: 0.5
  - A and B TIME/DIV: 1 ms
  - A TRIGGERING: Positive/External
  - MODE TRIGGER: ALT
- 3. Connect oscilloscope to drive as follows:
  - CH 1 to wirewrap pin A27-10A (Fine, K2200)
  - CH 2 to test point D on card A27 (Integrated Velocity, A2203)
  - A TRIGGERING to wirewrap pin A27-12A (Forward Seek, I1532)
- 4. Command continuous repeated seeks between cylinders 000 and 001: Press START switch to start spindle drive motor and to load heads. Using Off Line Tester, command repeated seeks between cylinders 000 and 001.
- Adjust scope controls to display waveform shown in Figure 3-15.
- 6. Scope waveform must be the same as waveform of Figure 1: Check that Fine signal switches to 0 volt when velocity signal is 0.90 ±0.10 volts (+0.90 for forward seeks and -0.90 for reverse seeks, see Figure 3-15).
- Perform steps 4 and 5 listed in the introduction to the Velocity Logic Checks.

Velocity Transducer Gain Uniformity

This procedure checks the output voltage and waveshape characteristics of the velocity transducer.

 Perform steps 1 and 2 listed in the introduction to the Velocity Logic Checks.

#### LOGIC GND TO SCOPE GND

**VOLTS / DIV** 

CH 1 - 5 VOLTS/DIV CH 2 - 0.5 VOLT/DIV

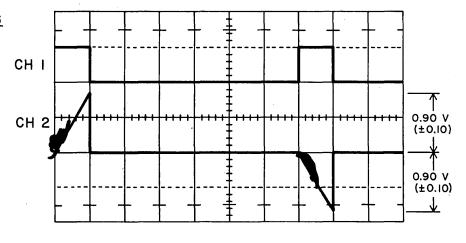
TIME / DIV

A- I MS/DIV B- I MS/DIV

## **TRIGGERING**

A-POS/EXT ON A27-TPD B-

PROBE CONNECTIONS
CH I TO A27-IOA
CH 2 TO A27-TPD



8P62

Figure 3-15. Fine Enable Switching Load

- 2. Set oscilloscope controls as follows:
  - CH 1 VOLTS/DIV: 1
  - A TIME/DIV: 2 ms
  - A TRIGGERING: Positive/External
- 3. Connect oscilloscope to drive as follows:
  - CH 1 to test point D on card A27 (Integrated Velocity, A2203)
  - A TRIGGERING probe to wirewrap pin B23-05B (T≤128, I1823)
- 4. Command continuous repeated seeks between cylinders 000 and 822: Press START switch to start spindle drive motor and to load heads. Using Off Line Tester, command continuous repeated seeks between cylinders 000 and 822.
- Adjust scope controls to display waveform shown in Figure 3-16.
- 6. Scope waveform must be the same as waveform of Figure 3-16. Ramps represent Integrated Velocity sawtooth waveform during last 127 cylinders of seek. Positive ramps are forward seek and negative ramps are reverse seek.

- 7. Voltage amplitude of next to last positive and last negative ramps shall be 2.0 ±0.2 volts (positive ramp is +2.0 volt and negative ramp is -2.0 volt). Also, these voltages shall be equal (the difference of the absolute values) within 0.3 volt. If not:
  - a. Perform Integrator Gain Adjustment.
  - b. Repeat this procedure. If it still fails, replace transducer rod assembly.
- Perform steps 4 and 5 listed in the introduction of the Velocity Logic Checks.

## Position Converter Output

The position converter output should be clamped at negative saturation until T<128. During the remaining cylinders of the seek, the converter output is under control of the D/A converter.

- Perform steps 1 and 2 listed in the introduction to the Velocity Logic Checks.
- 2. Set oscilloscope controls as follows:
  - CH 1 VOLTS/DIV: 2

# LOGIC GND TO SCOPE GND

**VOLTS / DIV** 

CHI- IV/DIV CH2- NOT USED

#### TIME / DIV

A-2 MS/DIV

B-NOT USED

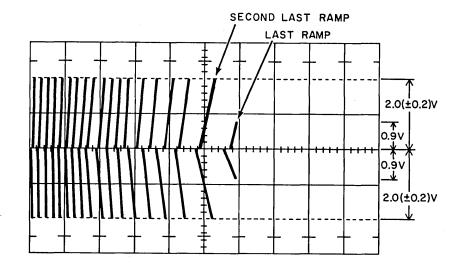
#### TRIGGERING

A- POS/EXT ON B23-05B

B- NOT USED

# PROBE CONNECTIONS

CH I TO A28-TPD CH 2 NOT USED



8P63

Figure 3-16. Velocity Transducer Gain Uniformity

- A TIME/DIV: 2 ms
- A TRIGGERING: Positive/External
- 3. Connect oscilloscope to drive as follows:
  - CH 1 to test point B of card A27 (D/A Converter Output, A2002)
  - A TRIGGERING to wirewrap pin A27-12A (Forward Seek, I1532)
- 4. Command continuous repeated seeks between cylinders 000 and 130: Press START switch to start spindle drive motor and to load heads. Using Off Line Tester command repeated seeks between cylinders 000 and 130.
- Adjust scope controls to display waveform shown in Figure 3-17.
- 6. Observe waveform on scope. The following events are occurring:
  - a. From cylinder 192 through cylinder 128, D/A converter output is 10 volts.
  - b. At cylinder 127, D/A converter output steps down (and continues to step down when each cylinder is crossed) to control position converter output.

- c. If requirements of step a and b are not met, check D/A converter circuitry on card at location A27.
- Perform steps 4 and 5 listed in the introduction to the Velocity Logic Checks.

## READ/WRITE SYSTEM CHECKS

Field-level tests of the read/write system require that signals with fast rise times be accurately measured. Make sure that the scope probe ground adapter is connected to ground (TPA or TPZ) of the card being tested. Connect secure ground lead between scope ground and GND jack on maintenance panel.

## Read Recovery Timing

The phase lock oscillator card at C24 and the data separator card at C25 require delay timing adjustments. These cards are aligned at the factory and must be considered as a matched set; if either card is replaced, both must be replaced.

Because of head variations, final data strobe timing cannot be determined until the cards are installed in the unit. This procedure determines the final setting. Cards must not be on extenders while performing this procedure.

LOGIC GND TO SCOPE GND

**VOLTS / DIV** 

CH I - 2 VOLTS/DIV CH 2 - NOT USED

TIME / DIV

A-2 MS/DIV

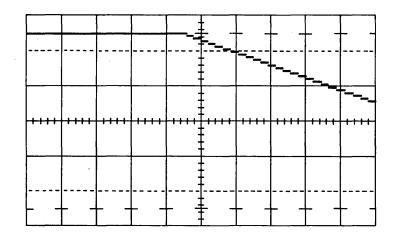
B-NOT USED

#### TRIGGERING

A-NEG/EXT ON A27-12A

B- NOT USED

PROBE CONNECTIONS
CH I TO A27-TPB
CH 2 NOT USED



8P64

Figure 3-17. Position Converter Output

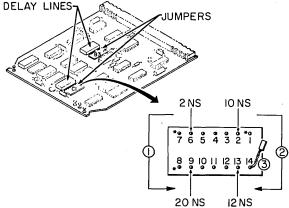
When a matched set of read recovery cards is installed in a unit, a verification test of the factory settings of the read recovery timing adjustment is required. In most cases, the unit will perform to specification with the factory setting and only requires wire wraping the delay line tap permanently into place.

In some units, the normal verification of read/write head parameters requires a read-justment of the factory alignment. The Read Recovery Timing Adjustment procedure should be performed only if unit did not meet Verification of Read Recovery Alignment Procedure.

Verification of Read Recovery Alignment

- Install a scratch disk pack: Press START switch to stop spindle drive motor. Open pack access cover and remove customer disk pack (if installed). Install a scratch disk pack and close pack access cover.
- 2. Install Off Line Tester: Open cabinet rear door and set the UNIT POWER circuit breakers to OFF. Remove logic chassis card cover. Connect Off Line Tester to drive per installation instructions in the Reference manual.
- Set jumper wires on delay lines C1 and B3 of the replacement data separator card (card that goes into location C25)

- per settings indicated on tag or label that came with card. Refer to Figure 3-18 for delay line locations on data separator card.
- 4. Remove old data separator card from logic card location C25 and install replacement card.
- 5. Seek to cylinder 822 and write an alternate data pattern (101010...) with all heads: Press START switch to start spindle drive motor and to load heads. Using Off Line Tester, (5) command a direct seek to cylinder 822 and write an alternate data pattern (101010...) with all heads.
- Read all heads sequentially at cylinder 822 for three minutes. Verify that no data errors have occurred.
- 7. Using Off Line Tester, set DATA WINDOW switch on maintenance panel to EARLY and perform a strobe early and read all heads sequentially at cylinder 822 for three minutes. Verify no read errors have occurred.
- 8. Using Off Line Tester, set DATA WINDOW switch on maintenance panel to LATE and perform a strobe late and read all heads sequentially at cylinder 822 for three minutes. Verify no read errors have occurred.



#### NOTES:

- ① CCW MOVEMENT OF TAP ON CI ADJUSTS STROBE EARLY BY 2 NS/TAP CW ON CI (②) DELAYS STROBE.
- ② CW MOVEMENT OF TAP ON B3 REQUIRED FOR CCW (⊕) MOVEMENT ON CI.
- 3 ONE END OF JUMPER WIRE IS ALWAYS CONNECTED TO PIN 14.
- 4. \*PINS 1, 7 AND 8 OF JUMPER ARE UNUSED.

7JI52A

Figure 3-18. Data Separator Card Delay Wiring

- 9. If no read errors occurred in steps 6, 7, or 8, no further testing is necessary, go to step 10. If read errors occurred in steps 6, 7, or 8, perform the Read Recovery Timing Adjustment procedure.
- 10. Remove data separator card from location C25: Press START switch to stop spindle drive motor and set UNIT POWER circuit breakers to OFF. Remove logic card from location C25.
- Remove and discard the plug-in jumpers from delay lines B3 and C1 on the data separator card.
- 12. Wirewrap the factory designated settings, or to the settings determined in test, on the delay line terminals.
- Install data separator card in location C25.
- 14. Remove scratch disk pack and Off Line Tester: Open pack access cover, remove disk pack and close pack access cover. Set UNIT POWER circuit breakers to OFF. Disconnect Off Line Tester from drive. Install logic chassis card cover. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

Read Recovery Timing Adjustment

The purpose of the adjustment is to center the strobe in the data window to achieve the optimum normal setting.

The procedure consists of three parts. First, the strobe is advanced in discrete steps by adjusting taps on a delay line until read errors occur. Second, the strobe is retarded in discrete steps until read errors occur. In the third step, the strobe is permanently set to a position half-way between the limits for advanced and retarded strobe.

Perform this procedure only after first performing the Verification of Read Recovery Alignment procedure and then only if read errors occurred in that procedure.

- Using Off Line Tester perform a strobe early read on all heads sequentially at cylinder 82\$ for one minute.
  - a. If errors occur, perform the Retard Read Clock procedure and proceed to step 2.
  - b. If errors do not occur, perform the Advance Read Clock procedure and proceed to step 3.
- 2. Using Off Line Tester, perform a strobe early read on all heads sequentially at cylinder 82 for one minute.
  - a. If errors occur, perform the Retard Read Clock procedure and repeat step 2.
  - b. If errors do not occur, make note of delay time in nsec for Jumper Cl and B3. (See Figure 3-17). Proceed to step 4.
- 3. Using Off Line Tester, perform a strobe early read on all heads sequentially at cylinder 822 for one minute.
  - a. If errors do not occur, perform the Advance Read Clock procedure and repeat step 3.
  - b. If errors do occur, proceed to step 2a.
- 4. Using Off Line Tester, perform a strobe late read on all heads sequentially at cylinder 821 for one minute.
  - a. If errors occur, perform the Advance Read Clock procedure and proceed to step 5.
  - b. If errors do not occur, perform the Retard Read Clock procedure and proceed to step 6.

- 5. Using Off Line Tester, perform a strobe late read on all heads sequentially at cylinder 822 for one minute.
  - a. If errors occur, perform the Advance Read Clock procedure and repeat step 5.
  - b. If errors do not occur, make note of delay time in nsec for Jumper C1 and B3. (See Figure 3-17) Proceed to step 7.
- Using Off Line Tester, perform a strobe late read on all heads sequentially at cylinder 822 for one minute.
  - a. If errors do not occur, perform the Retard Read Clock procedure and repeat step 6.
  - b. If errors occur, proceed to step 5a.
- 7. Calculate the new delay tap settings for C1 and B3 by subtracting the shortest delay time from the longest delay time for C1 and B3 respectively. (The delay times were determined in step 2b and 5b). Divide each result by two and add this to each respective shortest delay; the result is the new delay setting in nsec.

It is necessary to maintain the timing relationship between Cl and B3. For example, if final setting requires that Cl tap must be repositioned counterclockwise by two terminals from factory-recorded terminal, B3 tap must be repositioned clockwise by two terminals from factory-recorded terminal.

#### NOTE

If final delay time is odd, subtract 1 nsec from one delay time and add 1 nsec to the other delay time.

- 8. Remove data separator card from location C25: Press START switch to stop spindle drive motor and set UNIT POWER circuit breakers to OFF. Remove logic card from location C25.
- Remove and discard plug-in jumpers from delay lines B3 and Cl on the data separator card.
- 10. Wirewrap pin 14 of delay line C1 to the delay top setting determined in step 7.
- 11. Wirewrap pin 14 of delay line B3 to the delay top setting determined in step 7.

- 13. Perform Verification of Read Recovery Alignment procedure to make sure delay lines B3 and C1 are properly set.

#### Advance Read Clock

Adjust the data strobe for a more advanced setting by moving the jumper on selector plug Cl counterclockwise (shorter delay time) by one 2 nsec-tap and moving the jumper on selector plug B3 clockwise (longer delay time) by one 2 nsec-tap. These jumpers must both be moved to maintain the correct timing relationship between the two delay lines.

#### Retard Read Clock

Adjust the data strobe for a more retarded setting by moving the jumper on selector plug Cl clockwise (longer delay time) by one 2 nsec-tap and moving the jumper on selector plug B3 counterclockwise (shorter delay time) by one 2 nsec-tap. These jumpers must both be moved to maintain the correct timing relationship between the two delay lines.

#### Head Amplitude Test

This procedure verifies that the read signal has sufficient amplitude to be reliably processed by the read logic. Readback amplitude decreases as the recording frequency increases, thus the minimum amplitude in MFM recording is obtained when reading an all "0's" or all "1's" pattern. Maximum readback amplitude is obtained when reading a pattern of alternate "1010...".

Since read data is tested by the same heads that write the data pattern, head alignment is not verified by this test. If this test fails on all heads, replace card E00 (on main deck) and repeat test.

Perform this test on all heads as follows:

- Install a scratch disk pack: Press START switch to stop spindle drive motor. Open pack access cover and remove customer disk pack (if installed). Install scratch disk pack and close pack access cover.
- 2. Connect Off Line Tester to drive: Open cabinet rear door and remove logic chassis card cover. Set UNIT POWER circuit breakers to OFF. Connect Off Line Tester to drive per installation

instructions in Reference manual. Open cabinet top cover and remove deck cover. Remove cabinet rear door panel.

- 3. Set oscilloscope control settings as follows:
  - CH 1 VOLTS/DIV: 100 mv
  - CH 2 VOLTS/DIV: 100 mv
  - A and B TIME/DIV: 1 ms
  - A TRIGGERING: Positive/External
  - MODE TRIGGER: ADD
- 4. Connect oscilloscope to drive as follows:

#### NOTE

Card E00 is located in R/W chassis on deck.

- CH 1 to test point X on card E00 (Analog Read Data, A3219)
- CH 2 to test point on card E00 (Analog Read Data, A3219)
- A TRIGGERING to wirewrap pin B21-10B (Index, X2701)
- 5. Command a direct seek to cylinder 808: Set UNIT POWER circuit breakers to ON. Press START switch to start spindle drive motor and to load heads. Using Off Line Tester, command a direct seek to cylinder 808.
- Select head to be tested and write a data pattern of all "1's".

#### NOTE

The Off Line Tester syncs at Index and writes the following pattern in each sector until next index.

- a. Delay of 130  $\mu sec$  after leading edge of sector mark.
- b. 350  $\mu sec$  of bit pattern that was loaded into PATTERN display.
- 7. Read with head selected in step 6.
- 8. Observe waveform on scope and measure peak-to-peak amplitude of read signal. It shall be at least 74 mv, go to step 9.
- 9. Command a direct seek to cylinder 000.

- 10. Write an alternate data pattern
   (101010...) on head selected in
   step 6.
- 11. Read head selected in step 10.
- 12. Observe waveform on oscilloscope and measure peak-to-peak amplitude of read signal. It shall not exceed 800 mv, go to step 13.
- 13. If head is not within requirements of steps 8 and 12, replace only that head. If all heads were tested and all heads failed, replace logic card E00 (on deck) and repeat test. If heads are within limits, go to step 14.
- 14. Remove scratch disk pack: Press START switch to stop spindle drive motor. Disconnect oscilloscope probes. Install deck cover and close cabinet top cover. Open pack access cover, remove disk pack and close pack access cover.
- 15. Disconnect Off Line Tester: Set UNIT POWER circuit breakers to OFF. Disconnect Off Line Tester from drive. Install logic chassis card cover and rear door panel. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

#### MISCELLANEOUS LOGIC CHECKS

#### Clock Index Timing

This procedure verifies correct operation of the 806 kHz Clock and Index timing. Proceed as follows:

- 1. Install a scratch disk pack: Press START switch to stop spindle drive motor. Open pack access cover and remove customer disk pack (if installed). Install a scratch disk pack and close pack access cover.
- 2. Set oscilloscope controls as follows:
  - CH 1 VOLTS/DIV: 2
  - CH 1 VOLTS/DIV: 2
  - A and B TIME/DIV: 0.5 μsec
  - A TRIGGERING: Positive/Internal
  - MODE TRIGGER: ALT
- 3. Connect oscilloscope to drive as follows: Open cabinet rear door, remove logic chassis card cover and remove cabinet rear door panel. Set UNIT POWER circuit breakers to OFF. Connect oscilloscope probes to drive per steps listed below.

- CH 1 to wirewrap pin B21-11A (Odd and Even Dibits, I2700)
- CH 2 to wirewrap pin B21-10A (806 kHz Pulses, I2700)
- 4. Load heads: Set UNIT POWER circuit breakers to ON. Press START switch to start spindle drive motor and to load heads.
- Observe that oscilloscope waveforms are synchronous. If not check clock circuit on logic card at location B20.
- Disconnect CH 1 and connect it to wirewrap pin B21-10B (Index, X2701).
- 7. Observe that oscilloscope channel 1 waveform is a logical 1 for 2 ±0.5 µsec. If not, check index detection circuit on logic card at location A21.
- 8. Remove scratch disk pack: Press START switch to stop spindle motor. Open pack access cover, remove disk pack and close pack access cover.
- Disconnect oscilloscope: Remove oscilloscope probes from drive. Install logic chassis card cover and cabinet rear door panel. Close cabinet rear door.

#### Start/Stop Time

This procedure verifies correct operations of the spindle drive motor and hysteresis brake. Use a stopwatch or wristwatch with sweep second hand.

- Install a scratch disk pack: Press START switch to stop spindle drive motor. Open pack access cover and remove customer disk pack (if installed). Install scratch disk pack and close pack access cover.
- 2. Set oscilloscope controls as follows:
  - CH 1 VOLTS/DIV: 1
  - A TIME/DIV: 2 sec
- 3. Connect oscilloscope to backpanel pin A08-04A (Up to Speed, Y1000): Open cabinet rear door and remove logic chassis card cover. Remove rear door panel. Connect oscilloscope to backpanel pin A08-04A.
- 4. Press START switch and start timer. Observe the following:
  - a. Oscilloscope waveform should switch from a logical 0 to a logical 1 in 10 ±5 seconds.

- b. Heads should load in 15 ±2 seconds.
- Press START switch. Pack should come to complete stop in less than 20 seconds.
- 6. If requirements of steps 4 and 5 are not met, check drive belt and hysteresis brake. If requirements are within limits, go to step 7.
- Remove scratch disk pack: Open pack access cover, remove disk pack and close pack access cover.
- Disconnect oscilloscope probe from drive and install cabinet rear door panel.

## Speed Sensing

This procedure verifies correct operation of speed sensor and the speed detection circuitry.

- Install a scratch disk pack: Press START switch to stop spindle drive motor. Open pack access cover and remove customer disk pack (if installed). Install a scratch disk pack and close pack access cover.
- 2. Set oscilloscope controls as follows:
  - CH 1 VOLTS/DIV: 1
  - A TIME/DIV: 5 ms
  - A TRIGGERING: Negative/Internal
- 3. Connect oscilloscope to wirewrap A08-07B (Speed Transducer Output): Open cabinet rear door and remove logic chassis card cover. Remove rear door panel. Connect oscilloscope CH 1 to backpanel pin A08-07B.
- Load Heads: Press START switch to start spindle drive motor and to load heads.
- 5. Calibrate scope to ground. Observe waveform on oscilloscope. Signal should be 4 to 7 volts, peak-to-peak. If not, check speed sensor gap as directed in Speed Sensor Assembly Adjustment procedure. If within limits go to step 6.
- Disconnect CH 1 and connect it to wirewrap pin A08-3B (Speed Pulses, X2800).
- 7. Observe that signal is a logical 1 for 55 ±14 µsec and that time between positive leading edges (period between pulses) is approximately 16.6 psec: Switch oscilloscope A TIME/DIV control

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- first to 10  $\mu sec/DIV$  for first reading and then to 2  $\mu sec/DIV$  for second reading (period reading).
- 8. If requirements of step 7 are not met, troubleshoot speed logic circuitry on card A08. If within limits, go to step 9.
- Remove scratch pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- 10. Disconnect oscilloscope: Disconnect oscilloscope probe from drive. Install logic chassis card cover and cabinet rear door panel. Close cabinet rear door.

## Power Up Clear .

This procedure verifies that the internal Master Clear operation is operational during startup conditions. A disk pack need not be installed.

- Open cabinet rear door and set the UNIT POWER circuit breakers to OFF.
- 2. Set oscilloscope controls as follows:
  - CH 1 VOLTS/DIV: 1
  - A TIME/DIV: 50 ms
  - A TRIGGERING: Positive/Internal
  - MODE TRIGGER: CHOP
- Connect oscilloscope to drive as follows: Remove logic chassis card cover and remove rear door panel.
  - CH 1 to +5 test point jack on logic chassis maintenance panel.
  - CH 2 to wirewrap in Bl1-10B (Power Up Blanking, I1003)
- 4. Observe oscilloscope while turning 3A UNIT POWER circuit breaker to ON. 486 Hz
  - a. Channel 1 (+5v) should reach +4.5
     volts within 100 ms. If not, check
     +5 volt regulator and ac power
     supply.
  - b. Channel 2 should be a logical 1 for 200 ±100 ms. If not, check UBG delay B11 (D1000) and associated logic circuitry.

## MECHANICAL CORRECTIVE MAINTENANCE

#### **ACTUATOR REPLACEMENT**

#### NOTE

Replacement of the actuator is to be performed only by trained service personnel.

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Refer to Side Panel Removal/Installation procedure and remove right (viewed facing drive front) side panel.

## CAUTION

The magnetic field generated by the magnet assembly is very strong. Permanent watch damage will occur if brought near magnet.

- 4. Disconnect voice coil leadwire: Open cabinet top cover and remove deck cover. Make note of voice coil leadwire connect scheme and disconnect leadwires.
- 5. Disconnect velocity transducer plug P4 (refer to Figure 3-19).
- 6. Leadwires to heads loaded switch are fastened to actuator side with a cable tie. Cut cable tie to free leadwires.
- Loosen two screws attaching heads loaded switch and remove switch.
- 8. Open pack access cover.
- Remove two screws holding lower mounting bracket of gas cylinder to deck (one bracket on each side of pack access cover).
- Remove five screws securing parking brake cover to shroud and remove cover.
- 11. Remove two screws attaching access cover interlock switch to shroud. Take switch out of shroud area and let hang by its leadwires.
- 12. Remove five screws securing shroud side panels to shroud and deck (one panel on each side of shroud).

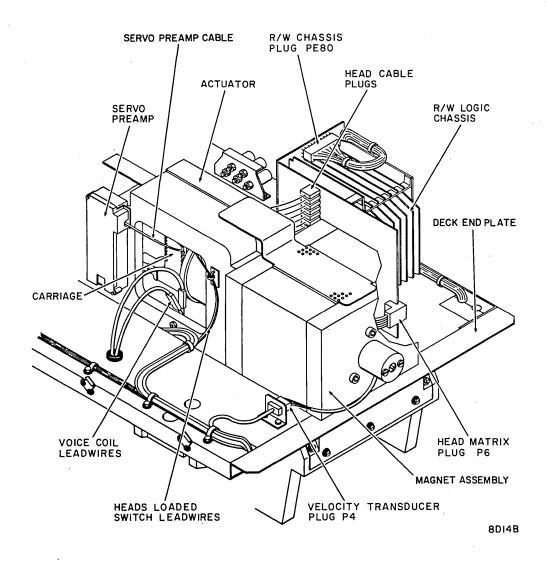


Figure 3-19. Main Deck Top View

- 13. Remove ground cable between shroud and operator control panel.
- 14. Remove 12 screws attaching shroud to deck.
- 15. Close pack access cover. Lift up on front of shroud/access cover to enable rear to clear operator panel and pull shroud forward to remove it.
- 16. Remove two screws securing servo preamp housing cover (Figure 3-19). Remove and set cover aside.
- 17. Disconnect servo head plug and servo output plug P8 from servo preamp circuit board. Write "SERVO" on servo head plug.
- 18. Remove head cable plugs from card E0 (mark each plug in sequence removed from top plug "0" to last plug "18").

# **CAUTION**

Remove one head/arm assembly at a time.

- 19. Remove head/arm assemblies starting at top of carriage (refer to Head/Arm Replacement procedure).
- 20. Remove logic card E0.
- 21. Loosen four screws securing read/write chassis to deck, slide chassis toward the rear, lift off deck and lay it aside.
- 22. Remove screw attaching head cable bracket to deck. Remove bracket.
- 23. Refer to Velocity Transducer Replacement procedure and remove velocity transducer.
- 24. Remove two screws securing forward stop plate to stop mount (Figure 3-20).
- 25. Remove 10 screws holding rear deck seal to deck. Remove rear deck seal.

- 26. Remove screw securing actuator to magnet assembly.
- 27. Remove three screws (under deck) securing magnet assembly to deck (screw above motor mounting plate cannot be completely removed, allow screw to rest on motor mounting plate).
- 28. Fully extend carriage.

## CAUTION

When removing magnet assembly, use care not to damage voice coil. Do not place magnet on or near may metal because it will be almost impossible to separate the two. Preferably place magnet on a wooden table, free of any metal filings or metallic objects.

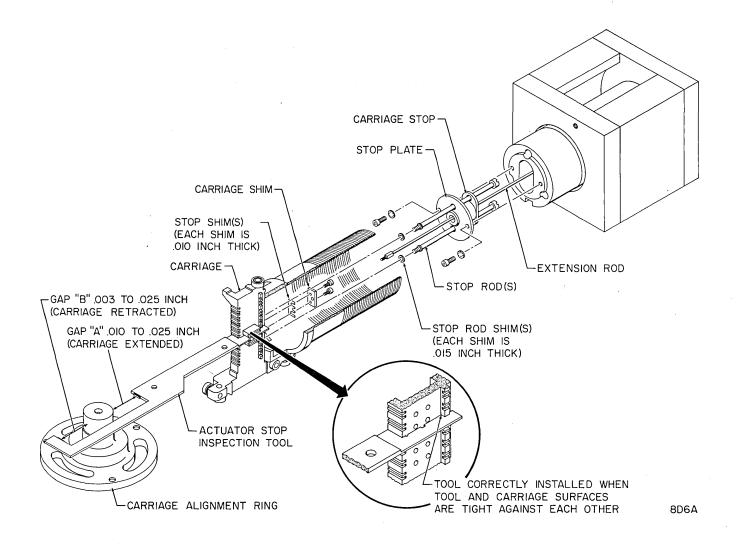


Figure 3-20. Carriage Stop Adjustment

- 29. Remove magnet assembly from deck by sliding assembly straight back from voice coil.
- 30. Remove two screws securing servo preamp housing assembly to actuator. Remove servo preamp housing.
- 31. Remove nut, screw, and clip holding flexible conductor to actuator housing. Back carriage out of actuator housing.
- 32. Using a 3/16 inch ball ended hex driver remove five screws and washers securing actuator to deck.
- 33. The actuator is mounted on a dowel pin. Lift actuator off dowel pin, and pull back to remove.
- 34. Remove actuator assembly to a clean work area.
- 35. Prepare to install replacement actuator by removing screw, clip and nut securing flexible conductor to replacement actuator housing. Then back carriage out of housing.
- 36. Install replacement actuator housing on deck. Use five screws to loosely secure actuator to deck. Visually center front screw in its hole by rotating housing on its dowel pin.
- 37. Remove air supply according to Air Supply Removal Installation procedure to allow access to spindle mount screws.
- 38. Loosen spindle mounting screws. Use spindle adjusting tool (refer to Figure 3-24) to adjust spindle so the two locating pins are centered in the spindle flange slots. Then tighten spindle mounting screws until they are snug.
- 39. Slide carriage into actuator housing.
- 40. Install carriage alignment arm on carriage at head 9 position (Figure 3-24), torque head/arm clamp screw to 4 inchpounds.
- Install carriage alignment ring on spindle.
- 42. Slowly extend carriage until carriage alignment arm and ring are approximately as shown in Figure 3-20.

# NOTE

Initial alignment of carriage to spindle is performed by moving actuator housing with reference to spindle.

- 43. Rotate the actuator housing on its dowel pin to obtain correct clearance between alignment ring and arm as specified in Figure 3-20.
- 44. Carefully remove carriage alignment arm and carriage.
- 45. Torque five screws securing the actuator assembly to deck to 60 inch-pounds.

## CAUTION

Do not loosen any of the socket head screws securing rails to actuator housing. Rails are adjusted forcibly by turning the eccentric screws without loosening the securing socket head screws.

- 46. Clean feet of rail adjustment tool and pads of deck. Place rail adjustment tool on deck (Figure 3-21) and measure flatness of top of lower rail as follows:
  - a. Move indicator from 0.38 inch in front of front screw back to front eccentric (Figure 3-22). Total deviation must not exceed three small divisions (0.000060 inch).
  - b. Move indicator from 1.25 inch in front of rear eccentric to 1.0 inch in back of rear eccentric. Total deviation must not exceed three small divisions (0.000060 inch). If requirements are met, proceed to step 48. If not, proceed to step 47.

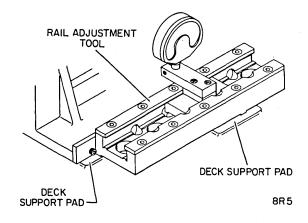
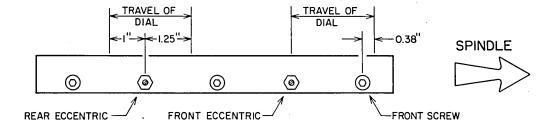


Figure 3-21. Rail Adjustment Tool



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Figure 3-22. Lower Rail Adjustment Eccentrics

- 47. If either or both requirements are not met adjust as follows:
  - a. Remove rail adjustment tool and loosen lock nut on eccentric screw that requires adjustment (both if necessary).
  - b. Replace rail adjustment tool and turn eccentric screw with a screwdriver to adjust flatness. Repeat for other eccentric screw if required.
  - c. When rail is adjusted to meet requirements of step 46, remove rail adjustment tool and tighten lock nut to 28 inch-pounds. Recheck flatness (repeat step 45a and 45b).
- 48. Clean actuator rails and carriage bearings per Section 2.
- 49. Install carriage into actuator housing from rear and attach flexible conductor to housing with insulated screw, clip, and nut (nut on outside of housing).
- 50. Install three carriage stop shims and tighten.
- 51. Insert a 1/16 inch allen wrench through hole in stop rod and use wrench as lever to unscrew stop rod.
- 52. Install two stop rod shims on each stop rod and lightly tighten stop rods.
- 53. Extend carriage forward, slide magnet assembly into position, and loosely secure magnet to deck using three screws.
- 54. Install two screws to secure stop plate. to magnet assembly and tighten securely.
- 55. Move carriage back and forth to assure that stop rods do not rub on stop plate.

- 56. Loosely install screw through top of actuator into magnet assembly. Move voice coil in and out of magnet making sure voice coil is not contacting magnet assembly, then tighten screw to 60 ±3 inch-pounds. Insert 0.005 inch non-metallic feeler gage between coil and magnet to ensure 0.005 inch gap around coil. Then tighten three screws securing magnet to deck to 30±1 inch-pounds. Recheck 0.005 inch gap around coil.
- 57. Install actuator stop inspection tool in head position 9, hold tight against back carriage reference surface, and secure with head clamping hardware.
- 58. Fully extend carriage and hold firmly in place.
- 59. Using plastic feeler gage, measure gap "A" shown in Figure 3-20.

#### NOTE

Each stop rod shim is 0.015 inch thick. Refer to Table 3-2 and determine quantity of shims to be added or removed before removing stop rods. Add or remove an equal number of shims on each stop rod.

- 60. Unscrew stop rod using a 1/16 inch allen wrench through hole in stop rod.
- 61. Add or remove stop rod shims as required for each stop rod.
- 62. Apply one drop of Loctite, Grade C, to threads of each stop rod.
- 63. Install stop rods and tighten rods firmly.
- 64. Fully retract carriage and hold carriage firmly in place.

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TABLE 3-2. SHIMS FOR FORWARD ADJUSTMENT

Measurement at Gap "A"	Shims Added per Stop Rod
0.010 - 0.025	0
0.026 - 0.039	1
0.040 - 0.055	2
0.056 - 0.069	3

- 65. Using plastic feeler gage, measure gap "B" shown in Figure 3-20.
- 66. If the requirements are met, apply one drop of Loctite, Grade C, to the threads of each carriage shim screw and retighten. If the requirements are not met, add or remove carriage stop shims as required (each carriage stop shim is 0.010 inch thick). Refer to Table 3-3.
- 67. Remove actuator stop inspection tool and install carriage alignment arm in head 9 position. Secure with head clamping hardware and torque head/arm clamp screw to 4 inch-pounds.
- 68. Using spindle adjustment tool, adjust spindle to obtain clearance specified in Figure 3-24.
- 69. Tighten three spindle mounting screws and recheck clearance.
- Remove carriage alignment arm and carriage alignment ring.
- 71. Attach rear deck seal to deck.
- 72. Replace air supply.
- 73. Replace heads loaded switch.
- 74. Secure heads loaded switch leadwires to actuator side with cable tie.
- 75. Perform Heads Loaded Switch Adjustment procedure.
- 76. Install velocity transducer per Velocity Transducer Replacement procedure.
- Connect velocity transducer cable plug P4.
- 78. Attach cable post to deck.
- 79. Slip read/write chassis into position under four screws and tighten screws.
- 80. Install logic card E0.

- 81. Install all heads per Head/Arm Replacement procedure.
- 82. Attach head cable plugs to card E0 in reverse of sequence removed.
- 83. Connect servo head plug and servo output plug P8 to servo preamp circuit board.
- 84. Install servo preamp housing cover.
- 85. Connect voice coil leadwires.
- 86. Install shroud and attach to deck.
- 87. Replace ground cable between shroud and operator control panel.
- 88. Replace both shroud side panels.
- 89. Replace access cover interlock switch and attach with two screws.
- 90. Replace parking brake access cover.
- 91. Attach both lower mounting brackets of gas cylinders to deck.
- 92. Perform Servo System Checks and Adjustments.
- 93. Perform Head/Arm Adjustment procedure.
- 94. Replace deck cover.
- 95. Close cabinet top cover.
- 96. Replace right side panel.
- 97. Close cabinet rear door.

# AIR SUPPLY REMOVAL / INSTALLATION

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.

TABLE 3-3. SHIMS FOR REVERSE ADJUSTMENT

Measurement at Gap "B"	Stop Shims Required
0.003 - 0.025	. 0
0.026 - 0.035	1
0.036 - 0.045	2
0.046 - 0.055	3

- Release two turnlock fasteners securing front panel to drive, reach behind front panel to disconnect ground lead, then remove panel.
- Loosen hose clamp securing rubber boot to top outlet of air supply. Remove rubber boot.
- Remove air supply primary filter by pressing clips away from primary filter frame (refer to Figure 1-1).
- Remove two screws (located behind primary filter) that attach air supply to frame.
- Reach behind air supply and pull the two inch hose from air supply with a twisting motion.
- Loosen hose clamp holding three inch hose to upper rear of air supply. Remove hose.
- Pull air supply forward sufficiently to disconnect power cable connector P2 from lower rear of air supply. Then pull out air supply.
- 10. After performing desired maintenance, install air supply by reversing the above procedure.

# **BRAKE PLATE ASSEMBLY**

## Replacement

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack (leave cover open).
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Remove parking brake cover: Remove five screws securing parking brake cover to shroud. (Figure 3-23). Remove parking brake cover from shroud.
- 4. Remove defective brake plate assembly: Remove two screws securing brake plate assembly and springs to deck casting. Remove brake plate from deck observing how screws, springs and plate are assembled.
- 5. Install replacement brake plate assembly: Assemble two screws, two springs and replacement brake plate assembly. Position assembly on deck and tighten the two screws.
- Perform Brake Plate Check and Adjustment procedure.

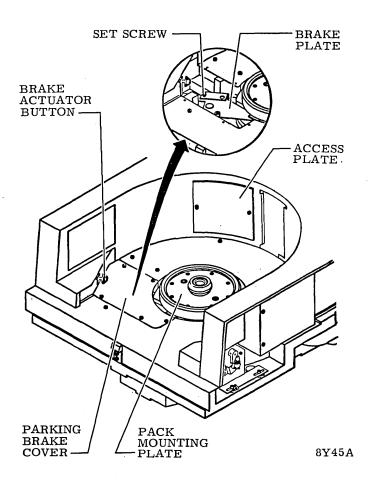


Figure 3-23. Brake Plate Replacement

#### Check And Adjustment

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover and remove disk pack (leave pack access cover open).
- 2. Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- 3. Measured clearance between brake tooth and pack mounting plate should be 0.015 ±0.005 inch: With parking brake cover in place (Figure 3-23), use feeler gauge to check that clearance between brake tooth and flat surface on underside of pack mounting plate is 0.015 ±0.005 inch (measured distance is where tooth is not engaged or under a notch in pack mounting plate).
- 4. If requirement of step 3 is within limits, go to step 5. If not within limits, adjust as follows:

- a. Remove disk pack.
- b. Remove parking brake cover: Remove five screws securing parking brake to shroud. Remove parking brake cover from shroud.
- c. Rotate spindle to a position where the brake tooth is not under a notch in the pack mounting plate.
- d. Adjust setscrew (Figure 3-23) until distance between brake tooth and pack mounting plate is 0.015 ±0.005 inch. Turning setscrew clockwise decreases distance and turning setscrew counterclockwise increases distance.
- e. Install parking brake cover: Position parking brake cover on shroud. Secure parking brake cover to shroud using five screws.
- Close pack access cover. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

## CARRIAGE/SPINDLE ALIGNMENT /

The carriage assembly is properly aligned when carriage motion is along a radial line from the axis of rotation of the spindle assembly. The following adjustment is required whenever the six screws securing the actuator housing and magnet to the deck casting are loosened, or if the spindle assembly is loosened from the deck casting.

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover and remove disk pack (leave cover open).
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Remove head number 10: Refer to Head/ Arm Replacement procedure and remove head number 10.
- 4. Install carriage alignment arm on carriage at head 10 position. Torque head/arm clamp screw, clamp plate, washers, and alignment arm to 4 inchpounds.
- Install carriage alignment ring on spindle.
- 6. Install head cam tool: Refer to Manual Carriage Positioning With Power Off and install head cam tool at head number 10 position.
- Slowly extend carriage until carriage alignment arm and ring are approximately aligned as shown in Figure 3-24.

## CAUTION

The carriage is aligned by moving the spindle. The six bolts securing the actuator and magnet to the deck are not to be loosened unless alignment cannot be attained by moving the spindle.

- Check that clearance between ring and arm tools is a specified in Figure 3-24. If correct proceed to step 19.
- If clearance is incorrect, loosen three screws securing the spindle assembly to deck.

#### NOTE

On units having cutouts in shroud (see Figure 3-23) proceed to step 10. On units not having cutouts proceed to step 11.

- 10. Using spindle adjustment tool, move the spindle to obtain the clearance specified in Figure 3-24. If this clearance is obtained proceed to step 11. However, if it is too far out of adjustment to be corrected in this manner proceed to step 12.
- 11. Tighten the three spindle screws and recheck clearance. If incorrect, repeat step 10. When the clearance is correct proceed to step 19.
- 12. Move the spindle until the dowel pins (Figure 3-24) are centered in the spindle slots. Tighten the three spindle screws.
- 13. Loosen the three screws securing the actuator housing to the deck.

## NOTE

The servo preamp housing must be removed to gain access to one of the actuator mounting screws.

14. Loosen the three screws securing the magnet to the deck.

#### NOTE

The actuator housing pivots on a pin located in its base and just forward of the magnet assembly. Pivoting motion is tangential to spindle.

15. Rotate the actuator and magnet as one assembly to obtain the clearance specified in Figure 3-24.

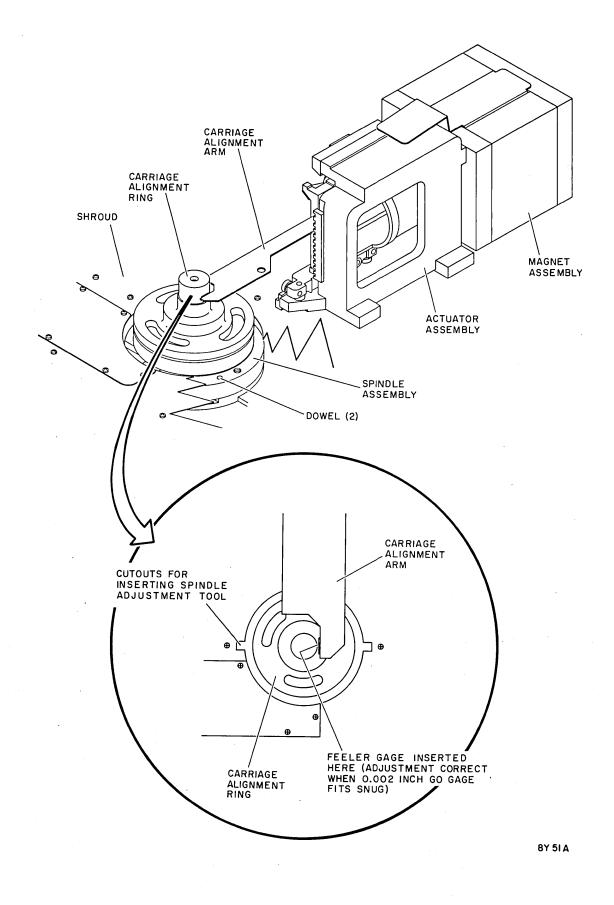


Figure 3-24. Carriage/Spindle Alignment

- 16. Torque (using 55 to 60 in-lbs.) the three screws securing the actuator housing.
- Tighten the three screws securing the magnet.
- 18. Recheck the clearance. If incorrect proceed to step 9 to fine adjust the alignment.
- Retract carriage, remove head cam tool and carriage alignment arm.
- 20. Remove carriage alignment ring.
- 21. Install head removed in step 2: Refer to Head/Arm Replacement procedure and install head removed in step 2.
- 22. Inspect read/write heads per the Head/ Arm Replacement Criteria in this section.
- Perform the Head/Arm Alignment procedure on all heads.

#### DRIVE BELT

#### Adjustment

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Remove cabinet front panel: Release two turnlock fasteners securing front panel to drive, reach behind front panel to disconnect ground lead, then remove panel.
- Push motor forward to insure free lateral movement of motor mounting plate.
- Inspect drive belt for cracks or worn spots. If required, replace belt per Drive Belt Replacement procedure.

#### NOTE

Units having two idler springs, repeat steps 7, 8 and 9 for each idler spring.

- Locate drive belt tension idler springs (Figure 3-25). Check for correct adjustment as explained in step 7.
- 7. Length between idler spring posts must be 5.42 ±.12 inch. If adjustment is required, proceed to step 8, if not, proceed to step 10.

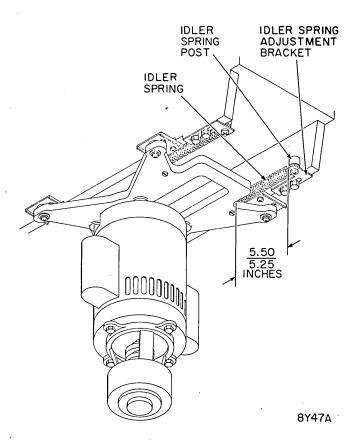


Figure 3-25. Drive Belt Adjustment

- Loosen two screws securing idler spring adjustment bracket to deck.
- Reposition idler spring bracket and spring until requirements are met.
   Tighten screws and recheck requirements.
- 10. Install cabinet front panel.
- 11. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

## Replacement

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- 3. Remove cabinet front panel: Release two turnlock fasteners securing front panel to drive, reach behind front panel to disconnect ground lead, then remove panel.

- 4. Remove static ground spring leadwire from deck casting.
- 5. Disconnect speed sensor plug P3.
- Disconnect pack on switch leadwires: Make note of pack sensor switch leadwire connection scheme and disconnect leadwires at switch.

Use care when removing drive belt to prevent damage to the pack sensor switch and static ground spring.

- 7. Remove drive belt from unit as follows:
  - a. Remove idler springs (Figure 3-25).

#### CAUTION

Use care when removing drive belt to prevent damage to the pack sensor switch and static ground spring.

- b. Move drive motor toward spindle assembly and remove drive belt from drive motor pulley and from spindle pulley. Remove belt from unit.
- 8. Install replacement drive belt: Install replacement drive belt as follows:
  - a. Position replacement drive belt around drive motor pulley.
  - b. Move drive motor toward spindle assembly and slip drive belt around spindle pulley.
  - c. Install idler springs (Figure 3-25).
  - d. Push drive motor to rear of cabinet to insure motor is properly seated.
  - e. Manually rotate spindle to align drive belt on pulleys.
- Connect speed sensor plug P3 and static ground spring leadwire.
- 10. Perform Drive Belt Adjustment procedure, steps 6 through 10.

#### DRIVE MOTOR REPLACEMENT

 Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.

- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Remove cabinet front panel: Release two turnlock fasteners securing front panel to drive, reach behind front panel to disconnect ground lead, then remove panel.
- 4. Disconnect the following plugs and leadwires:
  - a. Drive motor cable plug P7.
  - b. Hysteresis brake cable plug P2.
  - c. Speed sensor cable plug P3.
  - d. Pack sensor switch leadwires (make note of leadwire connection scheme before disconnecting leadwires); disconnect wires at switch.
- Refer to Drive Belt Replacement procedure, step 7, and remove drive belt.

## CAUTION

Do not support motor and brake assembly on hysteresis brake cup.

- 6. Support drive motor and brake assembly from below and remove four screws holding drive motor to motor mount. Note that there are two long and two short screws. Refer to Figure 3-26).
- Loosen both setscrews in drive motor pulley. Remove pulley.
- Remove hysteresis brake assembly as described in Hysteresis Brake Replacement procedure.
- Install hysteresis brake assembly on replacement drive motor as described in Hysteresis Brake Replacement procedure.
- 10. Slide drive motor pulley on replacement drive motor shaft until it is 0.56 ±0.02 inch from drive motor end bell. Tighten both setscrews.
- 11. Support replacement drive motor from below and install on motor mount casting (orient air exhaust openings towards air supply). Secure drive motor to motor mount casting using two long and two short screws in their respective locations.
- 12. Position drive belt around spindle pulley, and slip other end of belt around drive motor pulley. Visually confirm that drive motor pulley is aligned with spindle pulley.

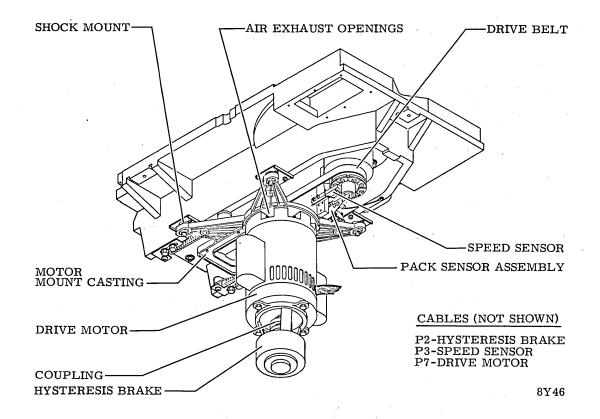


Figure 3-26. Deck Assembly Bottom View

- 13. Install drive belt: Refer to Drive Belt Replacement procedure, step 8, and install drive belt.
- 14. Connect the following plugs and leadwires:
  - a. Drive motor cable plug P7.
  - b. Hysteresis brake cable plug P2.
  - c. Speed sensor cable plug P3.
  - d. Pack sensor switch leadwires.
- 15. Install a scratch disk pack: Open pack access cover, install a scratch disk pack and close pack access cover.
- 16. Start spindle drive motor, observe drive motor for proper operation: Set UNIT POWER circuit breakers to ON. Press START switch to start spindle drive motor. Observe drive motor for proper operation.
- 17. Press START switch to stop spindle drive motor.

18. Close cabinet rear door and install cabinet front panel.

## HEAD/ARM ASSEMBLIES

#### **Head Inspection and Cleaning**

The drive has a positive pressure filtration system that eliminates the need for periodic inspection and cleaning of heads, except where extreme environmental conditions exist. The heads should be inspected for the following reasons only:

- A problem is associated with a specific head or heads; for example, excessive data errors.
- Head to disk contact is suspected.
- Contamination of pack is suspected (possibly due to improper storage of the pack).
- Concentric scratches are observed on pack surface.

Do not smoke when inspecting or cleaning heads. Use extreme care not to damage head. If gimbal spring (holds head on end of arm) is permanently bent, entire head/arm assembly must be replaced. Do not touch head pad or gimbal with fingers or tools. If heads must be laid down, do not allow pad or gimbal to touch anything.

# Head Inspection

Prior to removing head for inspection, use a bright directional light to inspect pack while it is mounted on drive spindle. If pack shows signs of concentric scratches or any surface damage in data zone, reject pack. (Small tick marks in the head loading zone are not cause for pack rejection).

- Remove suspected head per Read/Write or Servo Head/Arm Replacement procedure.
- Inspect head for reddish-brown oxide deposits.
- 3. If oxide deposits exist, clean head per Head Cleaning procedure.
- If head appears scratched, or damaged, refer to Head/Arm Replacement Criteria.

#### Head Cleaning

If cleaning of head is required, refer to Figure 3-27 and perform the following procedure. Use care not to damage the head pad, gimbal, and arm.

 Clean a smooth, flat working surface (for example, glass or Formica) with a soft tissue. Then wipe surface with palm of hand to remove all traces of dust or lint.

#### CAUTION

Do not use shiny or coated paper because they contain fine clay dust and other polishing fillers that could be deposited on head flying surface.

 Place a sheet of clean bond paper on the flat surface in manner that allows head/arm to be held parallel to paper surface.

#### CAUTION

Do not use isopropyl alcohol, acetone, or other solvents.
Use CDC media cleaning solution only. Refer to Table 3-1.

Moisten a small area of the paper with media cleaning solution.

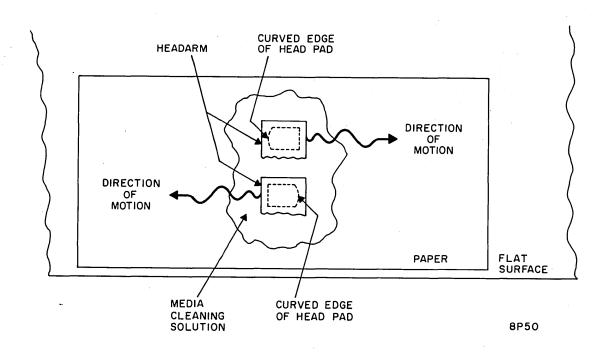


Figure 3-27. Head Cleaning Motion

In the following step, move the head/arm in a direction away from curved edge of head pad.

- 4. Gently place head pad flying surface on moistened area and lightly move head along paper in a zig-zag buffing motion (as shown in Figure 3-27) from the moistened area to the dry area.
- 5. Inspect head to determine that oxide deposits were removed. If deposits remain but show signs of being removed, repeat step 4 until deposits are removed. If oxide deposits cannot be removed, replace head with a new one.
- If oxide deposits were removed and head passes inspection criteria (refer to Head/Arm Replacement Criteria), reinstall head.
- Follow Read/Write or Servo Head/Arm Replacement procedure to install cleaned head or a replacement head as required.

#### Head/Arm Replacement Criteria

A head/arm requires replacement if any of the following conditions exist:

- Consistent oxide buildup on head indicating repeated head/disk impact.
- Appreciable oxide buildup located primarily on edge of ferrite insert.
- 3. Scratches over 1/2 of head face surface.
- 4. Imbedded particles in head.
- Audible ping while operating with heads over disk area, indicating that head is hitting disk surface.
- Oxide deposits cannot be cleaned from head.
- 7. Head or head/arm is damaged.

# Read-Write Head/Arm Replacement

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Open cabinet top cover and remove deck cover.

- Remove five screws securing left (as viewed from front) shroud side panel.
   Remove shroud side panel by sliding forward and swinging out.
- 5. Open pack access cover.
- 6. Using a 3/32 inch hex driver through opening created by removing left shroud side panel, remove four of the five screws securing head cable plate (top two screws and bottom two screws). Refer to Figure 3-27.
- 7. Loosen (but do not remove) center screw securing head cable plate, Remove head cable plate by pulling forward and unhooking from loosened screw.

#### NOTE

To facilitate replacement of the bottom heads, the voice coil leads may be removed.

- 8. To determine location of faulty head, refer to either the head identification label on the actuator assembly or to Figure 3-29.
- Remove clamp plate securing faulty head/ arm to carriage (Figure 3-28) and set aside.

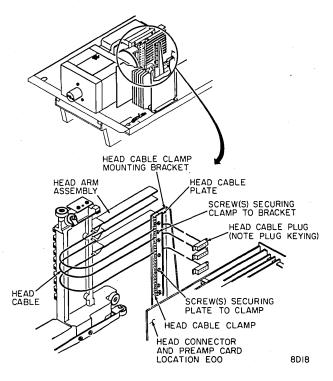


Figure 3-28. Head Cable Clamping/Connecting

Observe the following precautions during remainder of procedure:

- a. Do not touch head pad. Damage to the gimbal spring may result. Also, finger prints on flying surface of head will cause head crashes.
- b. Use care when installing or removing a head/arm assembly. If assembly is allowed to unflex and contact the adjacent head, damage to itself and/ or to an adjacent assembly may result.
- 10. With the left hand reaching into the shroud area, grasp front of head/arm firmly between index finger and thumb (avoiding head pad) and force head/arm in one of the following directions (Figure 3-30):
  - a. Down if head pad is facing up.
  - b. Up if head pad is facing down.

This prevents head pad from contacting adjacent head/arm.

- 11. Move front of head/arm towards left side
   of drive (refer to Figure 3-31). Head/
   arm pivots to free rear notch of head/
   arm from slot in carriage rib.
- 12. While holding front of head/arm with left hand, grasp rear with right hand and wiggle head/arm back and forth (in a sideways motion) constantly pulling forward to disengage head from front slot of carriage.
- Lay head/arm in shroud area and disconnect head cable from logic card E0.
- 14. Remove cable spring from head cable clamp. Remove head/arm from drive taking care not to snag head cable connector.
- 15. Plug replacement head/arm cable connector onto proper pins of logic card E0.
- 16. Slide head/arm between existing head/ arm cables at approximate place. Tip head/arm on its side and slide into shroud.

# CAUTION

Head/arm must be kept straight (see Figure 3-30) while inserting until it is completely in place to avoid damage to itself and adjacent head/arms.

- 17. Manually straighten head/arm as shown in Figure 3-30 and guide it into proper front slot of carriage (Figure 3-31).
- 18. Wiggle head/arm back and forth (in a sideways motion) constantly pushing toward the rear until the head/arm is firmly seated in the front slot of the carriage.
- 19. Push rear notch of head/arm tight against the carriage rib while guiding front of arm over cam surface. Visually check lateral alignment of head/arm with other head/arms as viewed from front of drive to determine that it is properly seated. Reseat if necessary.
- 20. Install clamp plate removed in step 9 and torque to 4 inch-pounds.
- 21. Press end of head cable spring into proper slot of head cable clamp.

#### NOTE

Before installing head cable plate make sure all head cables are properly placed. Also ensure that washer of screw loosened in step 7 is toward head of screw.

- 22. Place head cable plate into position. While pushing head cable plate toward rear of drive, tighten screw loosened in step 7.
- 23. Install remaining screws attaching head cable plate to head cable bracket.
- 24. Close pack access cover.
- 25. Install left shroud side panel.
- 26. Perform Head/Arm Alignment procedure on replaced head/arm.

#### Servo Head, Arm Replacement

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Open cabinet top cover and remove deck cover.
- Remove five screws securing right (as viewed from front) shroud side panel. Remove shroud side panel by sliding forward and swinging out.

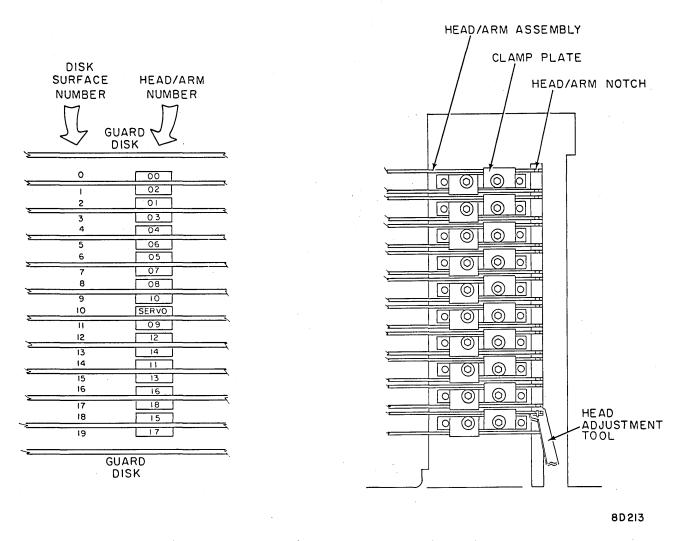


Figure 3-29. Head/Arm Assembly Identification

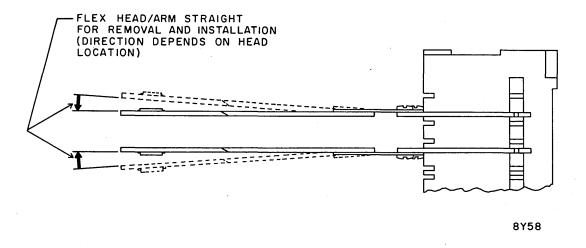


Figure 3-30. Head/Arm Installation and Removal Profile

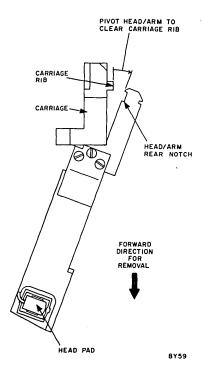


Figure 3-31. Head/Arm Installation and Removal Position

- 5. Open pack access cover.
- 6. Using a 1/4 inch nut driver through the opening created by removing right shroud side panel, remove two screws securing servo preamp housing cover.
- 7. Remove servo preamp housing cover.

## NOTE

To facilitate replacement of servo head, the voice coil leads may be removed.

B. To determine location of servo head, refer to either the head identification label on the actuator assembly or to Figure 3-29.

# CAUTION

Observe the following precautions during remainder of procedure:

a. Do not touch head pad. Damage to the gimbal spring may result. Also, finger prints on flying surface of head will cause head crashes.

- b. Use care when installing or removing a head/arm assembly. If assembly is allowed to unflex and contact the adjacent head, damage to itself and/or to an adjacent assembly may result.
- Remove clamp plate securing servo head/ arm to carriage (Figure 3-29) and set aside.
- Disconnect servo head/arm cable connector from servo preamp.
- 11. With the left hand reaching into the shroud area, grasp front of head/arm firmly between index finger and thumb (avoiding head pad) and force head/arm in an upward direction. This prevents head pad from contacting adjacent head/ arm.
- 12. Move front of head/arm towards left
   side of drive (refer to Figure 3-31).
   Head/arm pivots to force rear notch of
   head/arm from slot in carriage rib.
- 13. While holding front of head/arm with left hand, grasp rear with right hand and wiggle head/arm back and forth (in a sideways motion) constantly pulling forward to disengage head/arm from front slot of carriage.
- 14. Move freed head/arm into shroud area. Guide head/arm cable and connector carefully into shroud area and remove head/arm from drive.

## CAUTION

Head/arm must be kept straight (see Figure 3-30) while inserting until it is completely in place to avoid damage to itself and adjacent head/arms.

- 15. Guide head/arm cable and connector between existing head/arms.
- 16. Manually straighten head/arm as shown in Figure 3-30 and guide it into proper front slot of the carriage (Figure 3-31).
- 17. Wiggle head/arm back and forth (in a sideways motion) constantly pushing toward the rear until the head/arm is firmly seated in the front slot of the carriage.
- 18. Push rear notch of head/arm tight against the carriage rib while guiding front of arm over cam surface. Visually check lateral alignment of head/arm with other head/arms as viewed from front of drive to determine that it is properly seated. Reseat if necessary.

- 19. Install clamp plate removed in step 9 and torque to 4 inch-pounds.
- 20. Connect servo head/arm cable connector to servo preamp.
- 21. Replace servo preamp housing cover.
- 22. Close pack access cover.
- 23. Install right shroud side panel.
- 24. Perform Head/Arm Alignment procedure on all head/arms.

## Head/Arm Alignment Check

Head/arm alignment check is performed by using the Off Line Tester or by using microprogram diagnostic routines and a controller. The following procedure uses the Off Line Tester for alignment operation. Refer to the Reference manual for installation and familiarization of tester operation.

Refer to Controller manual for head alignment procedure using microprogram diagnostics.

The CE disk pack and Off Line Tester must be temperature stabilized before the following procedure is performed. Pack, drive, and Off Line Tester must be in the same temperature environment for a minimum 60 minute period immediately preceding head alignment. In addition, the CE pack must be purged on the drive a minimum of 30 minutes and the Off Line Tester must be plugged into the drive a minimum of 10 minutes before performing head alignment procedure.

## NOTE

If head alignment is being performed on more than one drive, the CE pack needs only a 15 minute purge per drive after head alignment has been performed on the preceding drive.

- Install CE disk pack: Press START switch to stop spindle drive motor.
   Open pack access cover and remove customer disk pack. Install CE disk pack and close pack access cover.
- 2. Connect Off Line Tester and head alignment card to drive: Open cabinet rear door and set UNIT POWER circuit breakers to OFF. Remove logic chassis card cover. Connect Off Line Tester to drive per installation instructions in Reference manual. Install head alignment card in location C23.

## CAUTION

The CE disk pack contains specially recorded tracks of data. Extreme care must be taken so that this data is not modified or destroyed.

- Open rear door and set ON LINE/OFF LINE/ WRITE DISABLE switch to WRITE DISABLE.
- 4. Set UNIT POWER circuit breakers to ON.
- Load Heads: Press START switch to start spindle drive motor and allow heads to load.
- Connect null meter to test points X and Z of head alignment card.
- Set R/W SERVO switch S2 on head alignment card to SERVO position.
- Check that CARRIAGE OFFSET switch on Maintenance panel is set to NORMAL position.
- 9. Command a seek to cylinder 491.

#### NOTE

If the readings obtained in the following three steps are incorrect, the problem must be diagnosed and corrected before this procedure can be completed. Refer to Servo System Checks procedure.

- 10. Set N/P switch Sl on head alignment card first to P position (note null meter reading) then to N position (note null meter reading). Algebraically subtract N from P and record reading. P-N reading should be 0 ±15 mv. If requirements are met proceed to step 11, if not, perform Servo Fine Position Offset Check/Adjustments.
- 11. Set R/W SERVO switch S2 on head alignment card to R/W position. Check that
  MODE light on card is off.
- 12. Select head to be checked per instructions in Reference manual.
- 13. Record null meter reading with head alignment card switch Sl first in P position; then to N position. Algebraically subtract P minus N and record result. P-N should be less than ±200 mv.
- 14. If P-N exceeds ±200 mv, perform Head/ Arm Adjustment procedure.
- 15. Repeat steps 13, 14, and 15 for all heads to be checked.

16. If all requirements are met, disconnect test equipment: Set UNIT POWER circuit breakers to OFF. Disconnect Off Line Tester and head alignment card from drive. Install logic chassis card cover and rear door panel. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

#### Head/Arm Adjustment

Perform this procedure only if the head clamping screws were loosened, after installation of a replacement head/arm, or if head fails the Head/Arm Alignment Check procedure.

- Perform steps 1 through 13 of the Head/ Arm Alignment Check procedure.
- 2. Raise drive top cover.
- 3. Remove deck cover.
- Command a continuous repeat seek between cylinders 486 and 491 for 30 seconds minimum.
- 5. Command a seek to cylinder 491.
- 6. Install Carriage Blocking tool.

#### CAUTION

If power is lost with heads loaded damage to heads and/or disk pack will occur if heads are not retracted before pack rotation stops.

- 7. Connect oscilloscope channel A to TPY of head alignment card. Set controls as follows:
  - CH 1: 2V/DIV
  - A TIME DIV: 1 μSEC/DIV
  - A TRIGGERING: Positive/Internal
- 8. Check that R/W SERVO switch S2 on head alignment card is set to R/W position and that MODE light on card is off.
- Loosen clamp screw of selected head and torque screw to 4 inch-pounds.
- 10. Refer to Figure 3-29 and position head adjustment tool so that tips of tool straddle carriage ridge and tool pin engages head/arm notch.
- 11. Adjust head to obtain a dibit pattern as shown in Figure 3-32 on the oscilloscope.

- 12. Set switch Sl on head alignment card to position P.
- 13. Position head (using head alignment tool) until the meter reading is 20 mv or less.
- 14. Re-torque the head clamp screw to 4 inchpounds.
- 15. Record P reading.
- 16. Set switch S1 on head alignment card to position N.
- 17. Record null meter reading of N.
- 18. Algebraically subtract recorded reading N from P.
- 19. If P-N result exceeds ±20 mv, repeat steps 12 through 18 until result is ±20 mv or less.
- 20. Repeat steps 9 through 19 for all heads requiring alignment adjustment.
- 21. Remove Carriage Blocking tool.
- 22. Unload heads a minimum of two times by stopping spindle.
- 23. Perform continuous seeks between tracks 486 and 491 for 30 seconds minimum.
- 24. Repeat steps 12,16,17,18,19. Record P-N readings at track 491.
- 25. If P-N result is ±150 mv or greater for any head, repeat steps 12 through 19 for that head.
- 26. Stop spindle motor.
- 27. Install deck cover and close top cover.
- 28. Remove disk pack.
- 29. Disconnect test equipment: Set UNIT POWER MAIN POWER circuit breakers to OFF. Disconnect null meter, oscilloscope and Off Line Tester.
- 30. Set UNIT MAIN POWER circuit breakers to ON and close cabinet rear door.

# **HEADS LOADED SWITCH**

#### Adjustment

 Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.

#### OSCILLOSCOPE SETTINGS

LOGIC GND TO SCOPE GND

**VOLTS / DIV** 

CH I - 2V/DIV CH 2 - NOT USED

TIME / DIV

A - 20 MS/DIV B - NOT USED

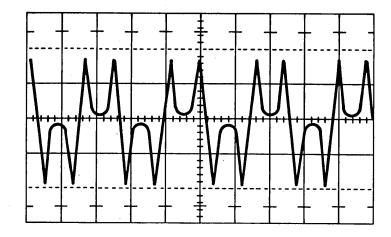
TRIGGERING

A-POS/INT

B- NOT USED

PROBE CONNECTIONS (USE XIO PROBE)

CH I TO C23 - TPY CH 2 NOT USED



8P65

Figure 3-32. Balanced Dibit Pattern

- 2. Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Open cabinet top cover and remove deck cover.
- Make note of heads loaded switch leadwire connection scheme and disconnect leadwires.
- Connect a multimeter (set to Rxl) across switch leadwire terminals.

## CAUTION

Do not move carriage so far as to cause heads to load. Switch transfer will occur before head loading.

- Carefully move carriage about one-half inch forward from retracted stop.
- Slowly retract carriage. Stop carriage at point where switch transfer occurs.
- 8. Using a steel scale, measure distance that carriage travels before contacting retracted stop. Switch transfer must occur when carriage is between 0.100 and 0.180 inch of encountering retracted stop.
- 9. If requirement is not met, loosen two screws securing switch mounting bracket to actuator housing. Reposition switch and bracket until requirement is met and tighten screws.

- Remove multimeter and connect heads loaded switch leadwires.
- 11. Install deck cover.
- 12. Close cabinet top cover.
- 13. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

#### Replacement -

No special instructions are required for removal and replacement except, when replacing switch, use one drop of Loctite, Grade C, on threads of each screw securing switch to mounting bracket. Perform Heads Loaded Switch Adjustment procedure following switch replacement.

#### HYSTERESIS BRAKE REPLACEMENT

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Remove side panel, or if drive is in line, remove front panel and air supply.
- 4. Disconnect hysteresis brake cable P2.

- Remove four screws attaching brake motor mount (and hysteresis brake assembly) to drive motor.
- Remove hysteresis brake assembly, observing orientation of brake power cable.
- Remove rubber coupling sleeve. Refer to Figure 3-33.
- Loosen two setscrews securing coupling flange to hysteresis brake shaft. Remove flange.
- Remove three screws attaching hysteresis brake to brake motor mount and remove brake.
- 10. Install replacement hysteresis brake on brake motor mount with three screws. Torque each screw to 28 to 32 inchpounds.
- 11. Install coupling flange on hysteresis brake shaft so that one setscrew is on flat of brake shaft. Do not tighten setscrews, only loosely secure coupling flange to brake shaft.

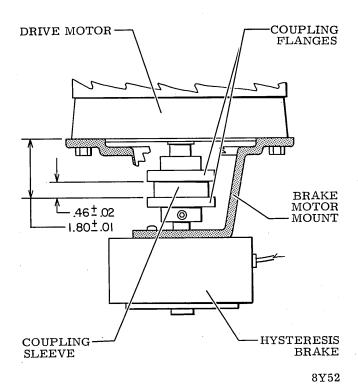


Figure 3-33. Hysteresis Brake Assembly

- Install rubber coupling sleeve on brake coupling flange.
- 13. Position brake motor mount (and replacement hysteresis brake) on bottom of drive motor. Make sure rubber coupling sleeve engages the motor coupling flange. Orient brake power cable to connect to P2.
- 14. Secure brake motor mount to the drive motor using four screws and washers. Torque each screw to 110 to 135 inchpounds.
- 15. Position coupling flange on hysteresis brake shaft to meet the requirements of Figure 3-33. Torque each setscrew in coupling flange to 20-25 inch-pounds.
- 16. Connect hysteresis brake cable to P2.
- 17. Install side panel or air supply and front panel, as required.
- 18. Perform Start/Stop time procedure.

#### PACK SENSOR SWITCH

#### Check

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover and remove disk pack.
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- 3. Disconnect pack sensor switch leadwires: Remove cabinet front panel. Identify and make note of pack sensor switch (Figure 3-34) leadwires. Disconnect leadwires at switch terminals.
- 4. Connect multimeter across pack sensor switch terminals: Connect a multimeter (set to Rx1) across pack sensor switch terminals as follows:

Meter Terminal	Pack Sensor Switch
BLK (GND)	С
RED (POS)	NC

- 5. Observe meter scale: Meter should indicate infinity. Go to step 6.
- 6. Install a scratch disk pack.
- Observe meter scale. Meter should indicate 0 ohms. Go to step 8.
- 8. If requirements of steps 5 and 7 are met go to step 9. If not within requirements, perform Pack Sensor Switch Adjustment procedure.

- Reconnect pack sensor leadwires: Remove multimeter probes from switch terminals. Connect pack sensor switch leadwires to switch terminals.
- Remove scratch disk pack and close pack access cover.
- 11. Install cabinet front panel.
- 12. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

#### Adjustment:

- Perform steps 1 through 4 of Pack Sensor Switch Check procedure.
- 2. Install a scratch disk pack.
- 3. Dimension between actuator arm and lockshaft must be as specified in Figure 3-34. If dimension is as specified go to step 10. If adjustment is required go to step 7.

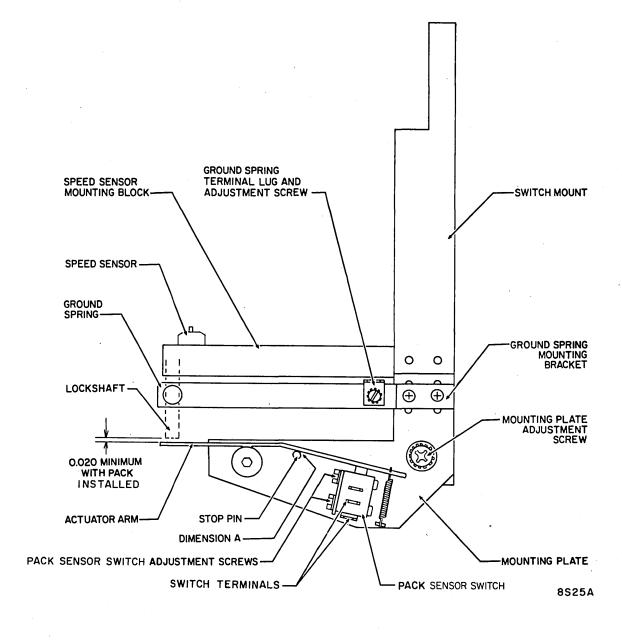


Figure 3-34. Pack Sensor Assembly

- Loosen mounting plate adjustment screw (Figure 3-34).
- Loosen two screws securing ground spring mounting bracket to switch mount.
- Position mounting plate until dimension between actuator arm and lockshaft is as specified in Figure 3-34. Tighten screws.
- 7. Connect a multimeter (set to Rx1) to pack on switch terminals (refer to step 4 of Pack Sensor Switch Check procedure). Meter must indicate 0 ohms. If correct go to step 19, if not go to step 8.
- Loosen pack sensor switch adjustment screws and position switch until multimeter just indicates 0 ofms. Tighten screws.
- Insert an 0.011 inch feeler gage between actuator arm and stop pin (dimension A of Figure 3-34).
- 10. Multimeter must indicate infinity. If not, go to step 11. If correct, remove feeler gage and go to step 13.
- 11. Loosen pack sensor switch adjustment screws and position switch until multimeter just indicates infinity. Tighten screws.
- 12. Remove feeler gage. Multimeter must indicate 0 ohms. If correct, go to step 13. If not, repeat procedure starting at step 8.
- 13. If pack sensor switch was repositioned, perform step 3 and if further adjustments are required repeat entire adjustment procedure. If requirements of step 3 are met, go to step 14.
- 14. Reconnect pack sensor leadwires: Remove multimeter probes from switch terminals. Connect pack sensor switch leadwires to switch terminals.
- 15. Remove scratch disk pack and close pack access cover.
- 16. Perform Ground Spring Adjustment procedure if mounting plate screws were loosened. If not, go to step 17.
- 17. Install cabinet front panel .
- 18. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

# Replacement

 Perform steps 1, 2 and 3 of the Pack Sensor Switch Check procedure.

- Remove two screws, washers and nuts securing pack sensor switch to the pack sensor mounting plate bracket (Figure 3-34). Remove faulty switch.
- Install replacement switch to mounting plate bracket using two screws, washers, and nuts. Do not tighten screws.
- 4. Perform Pack Sensor Switch Adjustment procedure starting at step 2.

## SERVO PREAMP PC BOARD REPLACEMENT

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Open cabinet top cover and remove deck cover.
- Remove two screws securing servo preamp cover (Figure 3-19). Remove cover.
- Disconnect servo head cable plug and output plug P8 from servo preamp board.
- Remove two socket head screws inside preamp housing. Remove preamp housing from unit.
- Remove two screws securing faulty preamp circuit board to preamp housing and remove circuit board.
- 8. Install replacement preamp circuit board to preamp housing, with two pan head screws. Tighten screws.
- Install preamp housing on actuator using two socket head screws. Tighten screws.
- 10. Connect servo head cable plug and output plug P8 to preamp circuit board.
- Using two screws, secure preamp housing cover to preamp housing. Tighten screws.
- 12. Install deck cover and close top cover.
- 13. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

#### SIDE PANEL REMOVAL/REPLACEMENT

1. Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.

- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Turn two leveling jackscrews in rear base of cabinet until casters contact floor. Close cabinet rear door.
- Release two turnlock fasteners securing cabinet front panel. Remove and set panel aside.
- Turn two leveling jackscrews in front base of cabinet until casters contact floor.

Use care when wheeling drive cabinet out of line so that input/output cables and connectors are not damaged.

- 6. Roll drive clear of adjacent units.
- 7. Open cabinet rear door.
- Release two quarter-turn fasteners securing panel side cover. Disconnect side panel ground wire. Remove and set panel aside.
- Install side panel and return unit to normal operating position by reversing steps 1 through 8.
- 10. Level unit per Installation procedures.

# SPEED SENSOR ASSEMBLY!

#### Adjustment

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Remove cabinet front panel: Release two turnlock fasteners securing front panel to drive, reach behind front panel to disconnect ground lead, then remove panel.
- 4. Use feeler gage to check that gap between sensor tip and pin is 0.023 ±0.002 inch (Figure 3-35).
- 5. If requirements of step 4 is not met, adjust speed sensor as follows:
  - a. Check speed sensor lateral alignment per requirements of Figure 3-35. If required, loosen mounting block adjustment screws and position assembly. Tighten screws.

- b. Loosen jam nut on speed sensor assembly.
- c. Adjust sensor assembly (clockwise rotation closes gap, counterclockwise rotation widens gap) as required.

#### NOTE

Tightening jam nut more than 15 inch-pounds can cause damage to speed sensor assembly.

- d. Torque jam nut to 5 ±1 inch-pounds.
- e. Recheck dimension of gap.
- Perform Speed Sensing procedure of Miscellaneous Logic Checkout.
- Replace cabinet front panel by reversing step 3.

# Replacement

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Remove cabinet front panel: Release two turnlock fasteners securing front panel to drive, reach behind front panel to disconnect ground lead, then remove panel.
- 4. Disconnect speed sensor cable plug P3.
- Cut cable tie securing speed sensor leadwires to speed sensor mounting bracket.
- Loosen locknut on faulty speed sensor assembly (Figure 3-34). Remove assembly from unit.

#### NOTE

Tightening jam nut more than 15 inch-pounds can cause damage to speed sensor assembly.

- Install replacement speed sensor on speed sensor mounting bracket. Torque jam nut to 5 ±1 inch-pounds.
- Perform Speed Sensor Adjustment procedure.

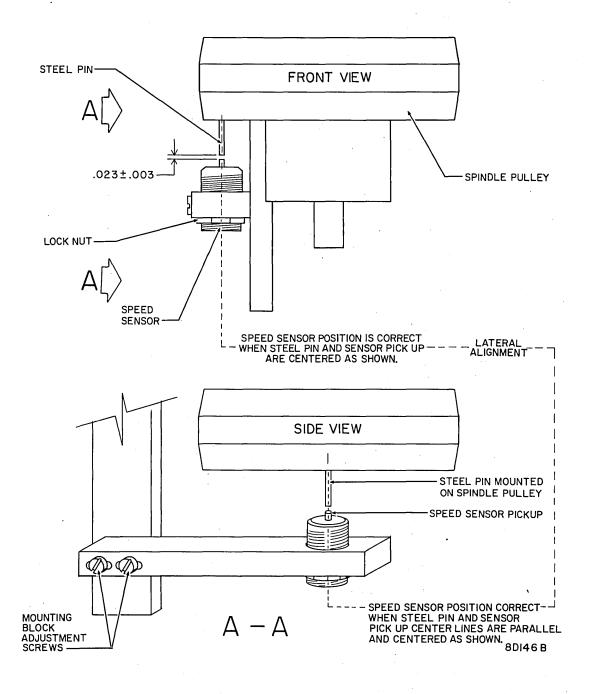


Figure 3-35. Speed Sensor Adjustment

#### SPINDLE AND LOCKSHAFT ASSEMBLY

Field repair of this assembly is limited to replacing the lockshaft. If replacing lockshaft does not correct problem, replace entire spindle assembly. Return faulty assembly to factory.

#### Lockshaft Replacement

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover and remove disk pack.
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Remove cabinet front panel: Release two turnlock fasteners securing front panel to drive, reach behind front panel to disconnect ground lead, then remove panel.
- Remove absolute air filter and air plenum: Refer to Replace Absolute Filter procedure (Section 2) and remove absolute air filter and air plenum.
- Remove two screws securing ground spring mounting block to switch mounting block.

#### NOTE

In the following step do not remove retaining ring securing springs in spindle assembly (this is retaining ring located behind flat washer removed in next step).

- Remove retaining ring and flat washer from lower end of lockshaft.
- Carefully raise faulty lockshaft out of top of spindle assembly.
- Lower replacement lockshaft into top of spindle assembly.

#### Caution

Before proceeding, make certain that lockshaft is free to move downward against internal spring force. Lockshaft must be free and not bind.

 Push lockshaft down 1/8 inch below top of spindle and install flat washer and retaining ring on lower end of lockshaft.

#### NOTE

Position ground spring mounting bracket so that contact on end of spring is contacting lockshaft.

- 10. Position ground spring mounting block on switch mounting block (Figure 3-34) and loosely secure block with two screws.
- Perform Pack On Switch Adjustment procedure.
- 12. Perform Ground Spring Adjustment procedure.
- 13. Replace absolute air filter and plenum:
  Refer to Replace Absolute Filter
  procedure (Section 2) and replace
  absolute air filter and air plenum.
- 14. Replace cabinet front panel by reversing step 3.

#### NOTE

Allow blower to purge unit for two minutes before installing a disk pack.

15. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

#### Spindle And Lockshaft Replacement

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover and remove disk pack.
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Remove cabinet front panel: Release two turnlock fasteners securing front panel to drive, reach behind front panel to disconnect ground lead, then remove panel.
- Refer to Side Panel Removal/Installation procedure and remove either side panel.
- Identify leadwires to pack on switch and ground spring. Disconnect leadwires.
- 6. Disconnect speed sensor cable plug P3.
- Remove idler springs (Figure 3-25) and move motor mounting plate towards spindle to relieve drive belt tension. Remove belt from drive motor pulley and spindle pulley.

- Remove pack sensor assembly from rear of spindle by removing two 3/16 allen screws
- 9. Open pack access cover.
- Remove five screws securing parking brake cover to shroud (Figure 3-23). Remove brake cover.

#### NOTE

While removing assembly in next step observe mounting technique used to secure brake plate assembly to deck.

- 11. Remove two screws securing brake plate assembly to deck casting (Figure 3-23). Remove and set assembly aside.
- 12. Remove three screws (under deck) securing spindle assembly to deck.
- 13. Grasp spindle drive pulley and alternately push and pull on assembly while applying upward force to free spindle assembly from two round pins driven through spindle flange and into deck.

#### NOTE

Spindle base may have to be rotated to clear shroud because of irregularities in casting.

14. Lift spindle assembly up away from deck being careful not to damage shroud.

#### NOTE

Insure mating surfaces of spindle and deck are clean.

15. Place replacement spindle assembly on deck (orient flat surface on side of spindle assembly towards drive motor). Position spindle assembly on pins protruding from deck and press down on spindle so that pins begin entering spindle.

# NOTE

Tighten spindle down evenly over pins, keeping spindle bottom surface parallel to deck surface.

- 16. Install three screws and washers to secure spindle to deck. Tighten screws so that lateral movement of the spindle is possible for spindle alignment.
- 17. Position pack sensor assembly on spindle assembly as shown in Figure 3-34.

#### NOTE

Before tightening screws in next step, position pack sensor assembly as close as possible to the dimensions shown in Figure 3-34. Doing this will minimize adjustment required after assembly is secured to the spindle:

- 18. Secure pack sensor assembly to spindle assembly with two 3/16 allen screws. Tighten screws.
- 19. Install drive belt on motor pulley.
- 20. Move drive motor mounting plate towards spindle assembly and slip drive belt around spindle pulley. Install idler springs, manually rotate spindle and push motor forward to seat belt.
- 21. Secure brake plate assembly to deck using two screws and related brake plate hardware. Perform Brake Plate Assembly Check and Adjustment.
- 22. Install brake plate cover to shroud using five screws. Tighten screws.
- 23. Connect ground spring and pack sensor switch leadwires.
- 24. Connect speed sensor cable plug P3.
- 25. Perform the following procedures:
  - a. Pack Sensor Switch Adjustment
  - b. Static Ground Spring Adjustment
  - c. Speed Sensor Adjustment
  - d. Carriage/Spindle Alignment
  - e. Head/Arm Alignment Check

## STATIC GROUND SPRING

# Adjustment

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Remove cabinet front panel: Release two turnlock fasteners securing front panel to drive, reach behind front panel to disconnect ground lead, then remove panel.
- Visually check that ground spring is approximately centered vertically and horizontally on lockshaft (Figure 3-34).

- If required, loosen screw securing ground spring to mounting bracket and center spring as required. Tighten screw.
- Place a 0.002-0.005 inch non-metallic feeler gage between ground spring and lockshaft.
- Hook a push-pull gage to outer end of ground spring.
- Force (applied perpendicular to spring) required to allow feeler gage to fall free should be 125 (±25) grams.
- If required, carefully bend spring to adjust spring tension.
- 10. Install cabinet front panel.
- Set UNIT POWER circuit breakers to ON and close cabinet rear door.

#### Replacement

- Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.
- Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Remove cabinet front panel: Release two turnlock fasteners securing front panel to drive, reach behind front panel to disconnect ground lead, then remove panel.
- 4. Remove static ground spring leadwire.
- Remove screw, nut, three washers, terminal lug and ground spring from contact mounting bracket (Figure 3-34).
- Install replacement ground spring on contact mounting bracket using one screw, one nut, three washers, and terminal lug.
- Perform Static Ground Spring Adjustment procedure.
- 8. Connect ground spring leadwire.
- 9. Install cabinet front panel by reversing step 3.
- 10. Set UNIT POWER circuit breakers to ON and close cabinet rear door.

# VELOCITY TRANSDUCER REPLACEMENT

 Remove disk pack: Press START switch to stop spindle drive motor. Open pack access cover, remove disk pack and close pack access cover.

- 2. Open cabinet rear door and set UNIT POWER circuit breakers to OFF.
- Open cabinet top cover and remove deck cover.
- 4. Disconnect velocity transducer cable plug P4 (Figure 3-36).
- Remove two screws and washers securing velocity transducer end cap to magnet assembly. Retain cap, screws, and spring (located inside cap).

## **CAUTION**

Use care in the following steps so that extension rod is not damaged.

- Extend carriage 1/2 inch and unthread extension rod at point where it enters rear of head/arm receiver.
- Carefully pull transducer magnet and extension rod out of cap end of transducer coil/housing.

#### CAUTION

Replacement velocity transducer magnet can be rendered unuseable if it comes in contact with a ferro magnetic object.

- Carefully remove replacement transducer magnet from shipping container.
- Determine polarity of replacement transducer magnet by placing near magnet just removed. Like poles repel.
- 10. Carefully unthread extension rod from transducer magnet. Moderate force may be required since Loctite is on rod threads.

# NOTE

Extension rod must be grasped at end nearest magnet while removing and replacing magnet.

- 11. Apply one drop of Loctite, Grade C, to extension rod threads that mate with transducer magnet. Thread rod into end of transducer magnet with same polarity as old transducer magnet.
- 12. Remove old transducer coil/housing from magnet assembly and slide replacement transducer coil/housing into magnet assembly
- 13. Install head cam tool and fully extend carriage.
- 14. Insert free end of extension rod into bore of coil/housing. Slide assembly

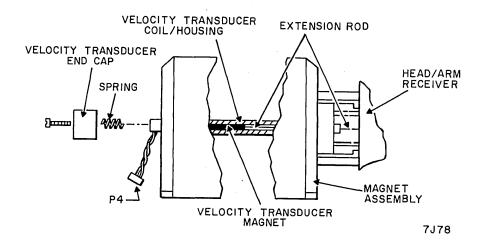


Figure 3-36. Velocity Transducer Replacement

into coil/housing until threads of extension rod are visible behind head/arm receiver.

- 15. Apply one drop of Loctite, Grade C, to extension rod threads. Using a pliers and only moderate force, install extension rod in head/arm receiver.
- 16. Assemble spring and transducer end cap to magnet assembly using two screws and washers. Remove voice coil yellow leadwire.
- 17. Connect velocity transducer plug P4. Set UNIT POWER circuit breakers to ON. Verify that card test point A28-TPC swings in negative direction while actuator is manually moved in forward direction.

#### NOTE

If A28-TPC swings in the wrong direction, magnet is installed backwards.

- 18. Retract carriage and remove head cam too.
- 19. Perform Velocity Gain Adjustment procedure.
- 20. Perform Velocity Transducer Gain Uniformity procedure.
- 21. Perform Integtator Gain Adjustment procedure.

# SECTION 4

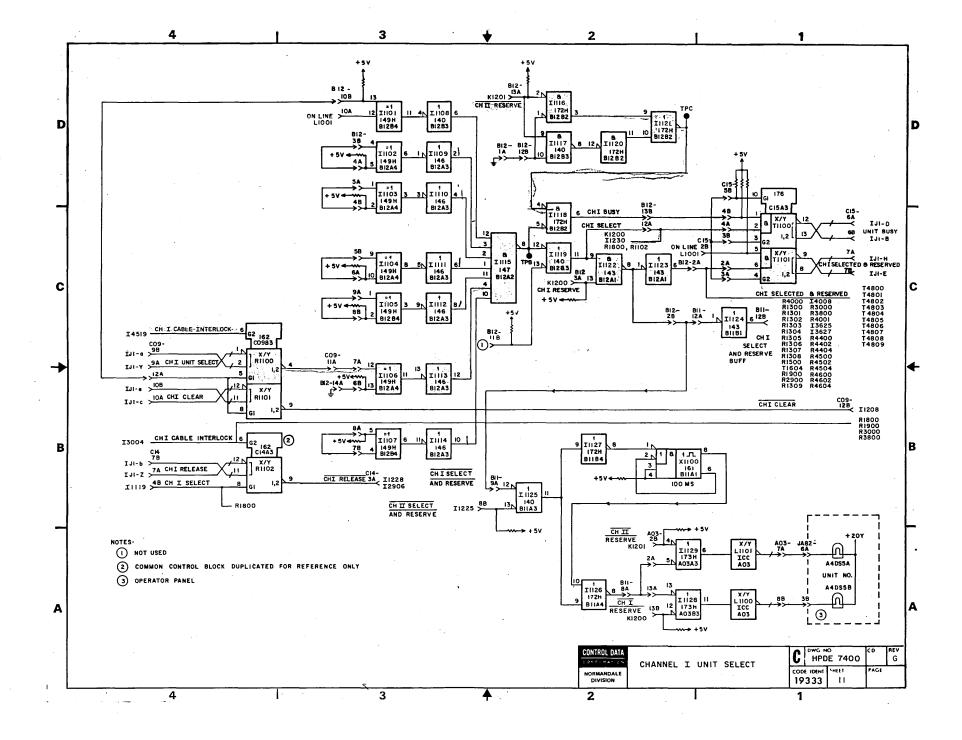
# **DIAGRAMS**

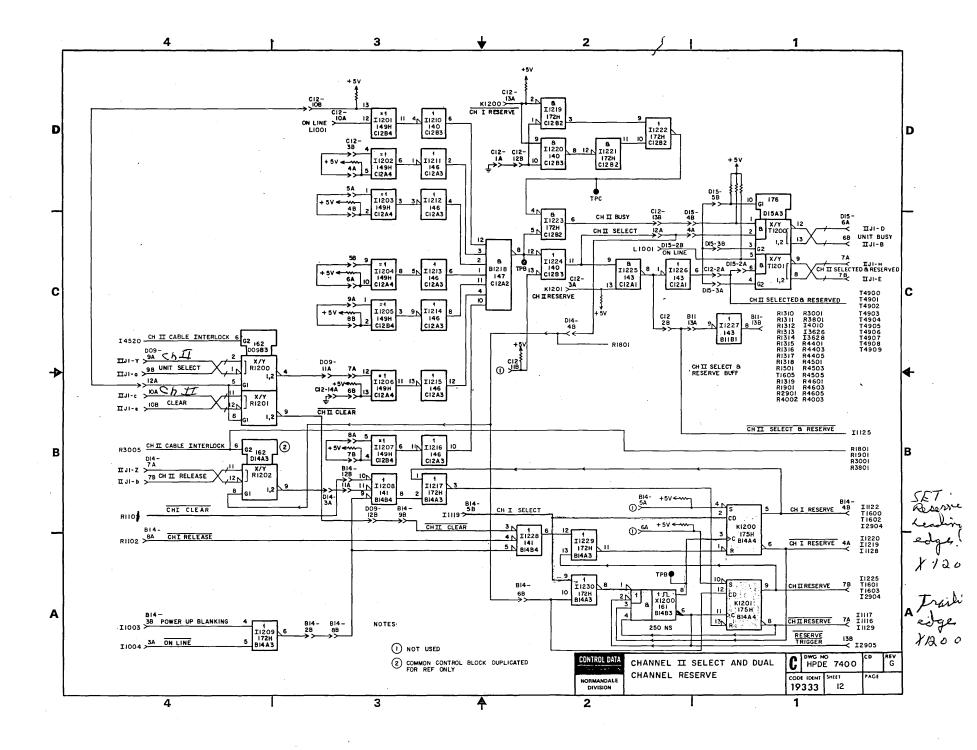
# **INTRODUCTION**

This section contains diagrams that logically describe the drive in terms of the functions which the unit performs and schematics that show the wiring of the various assemblies. Descriptive material for integrated and discrete component circuits is located in Sections 4, 5, and 6 of the Reference manual (Publication No. 83308200). Flow charts,

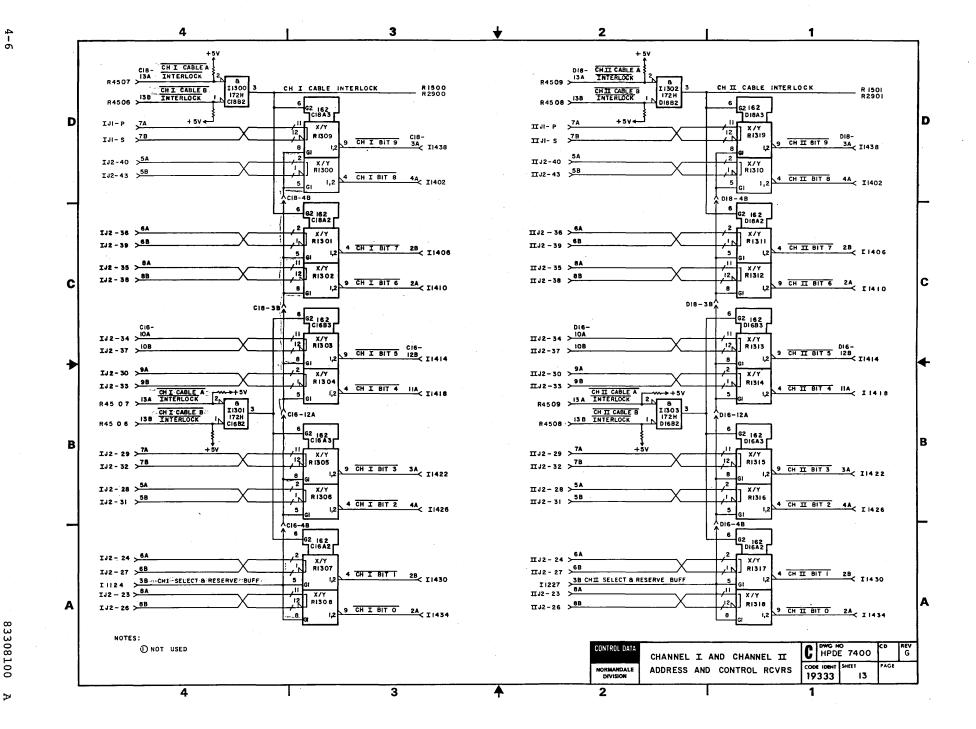
simplified circuits, and timing diagrams are located in the same manual.  $% \left( \frac{1}{2}\right) =\frac{1}{2}\left( \frac{1}{2}\right) +\frac{1}{2}\left( \frac{1}{2}\right) +\frac{$ 

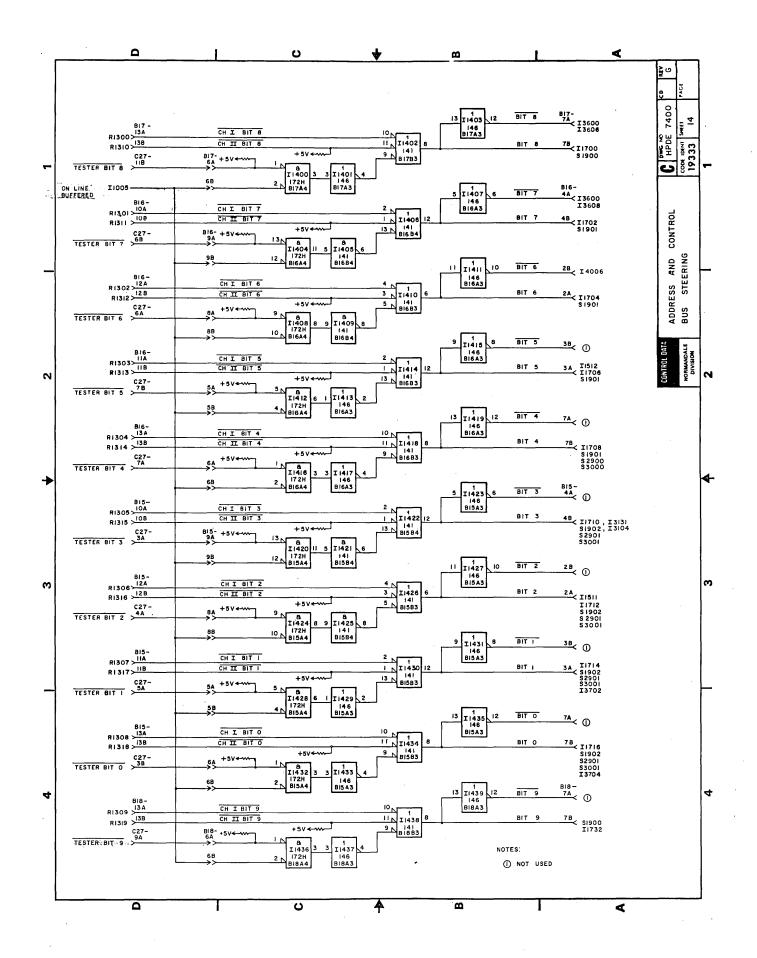
Logic sheets 1 through 9 and sheet 1 of all assembly schematics (located at end of section) are not included in this manual. They are for factory use only.

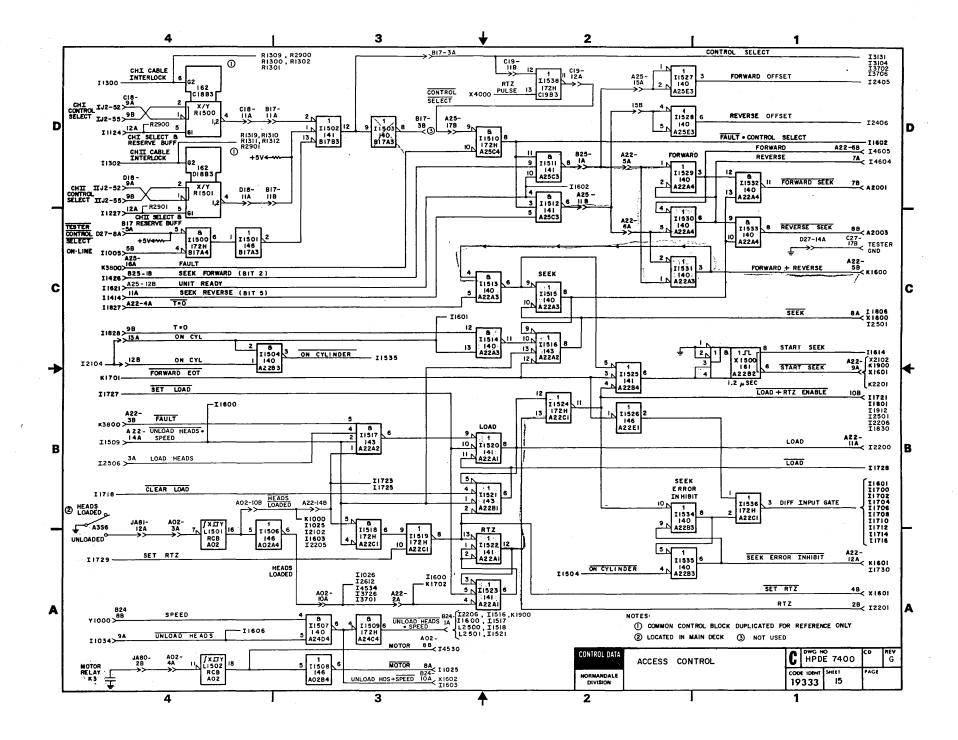


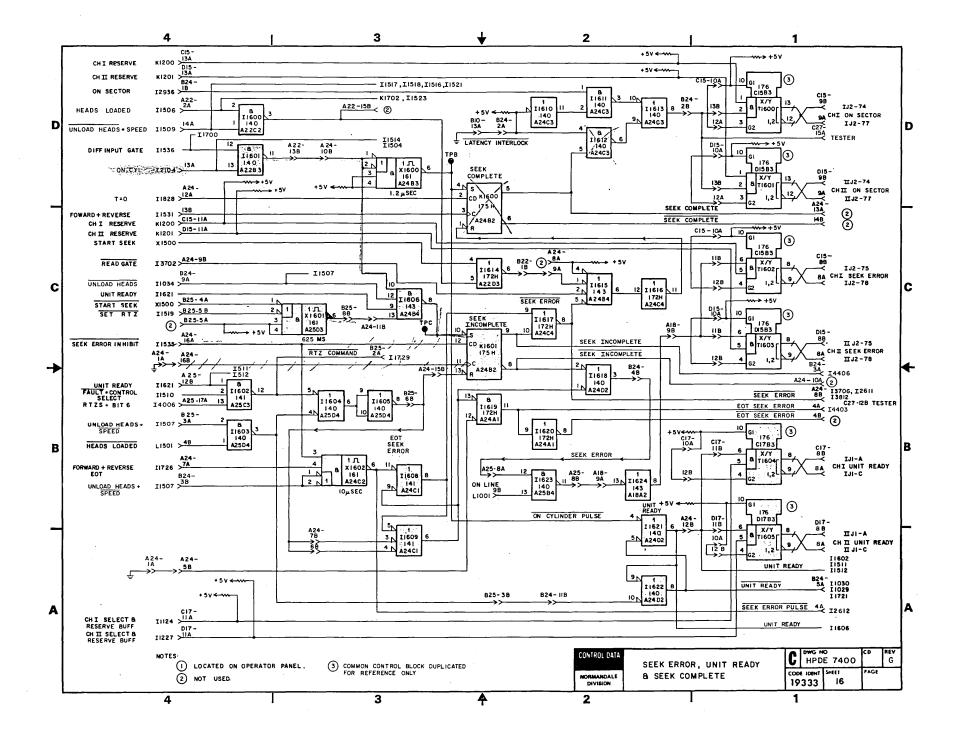


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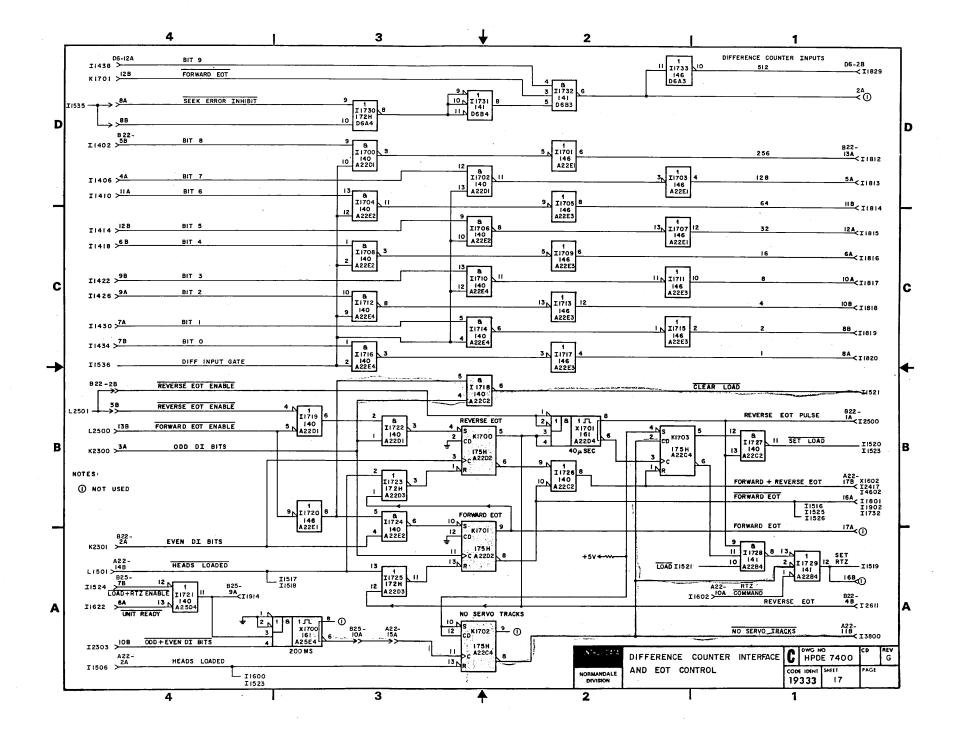


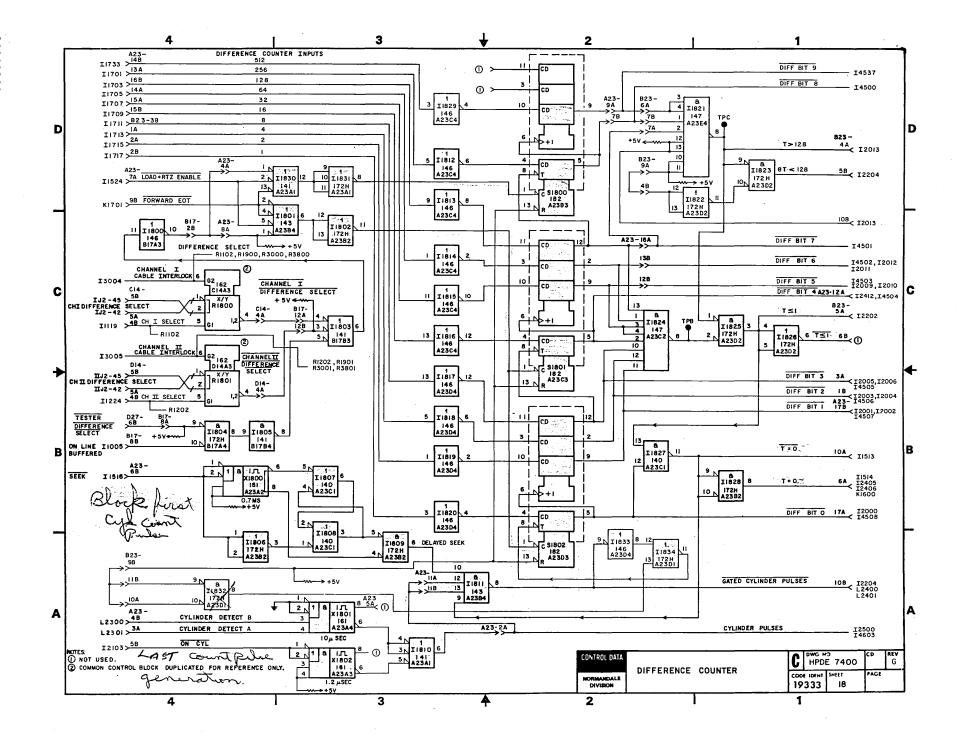


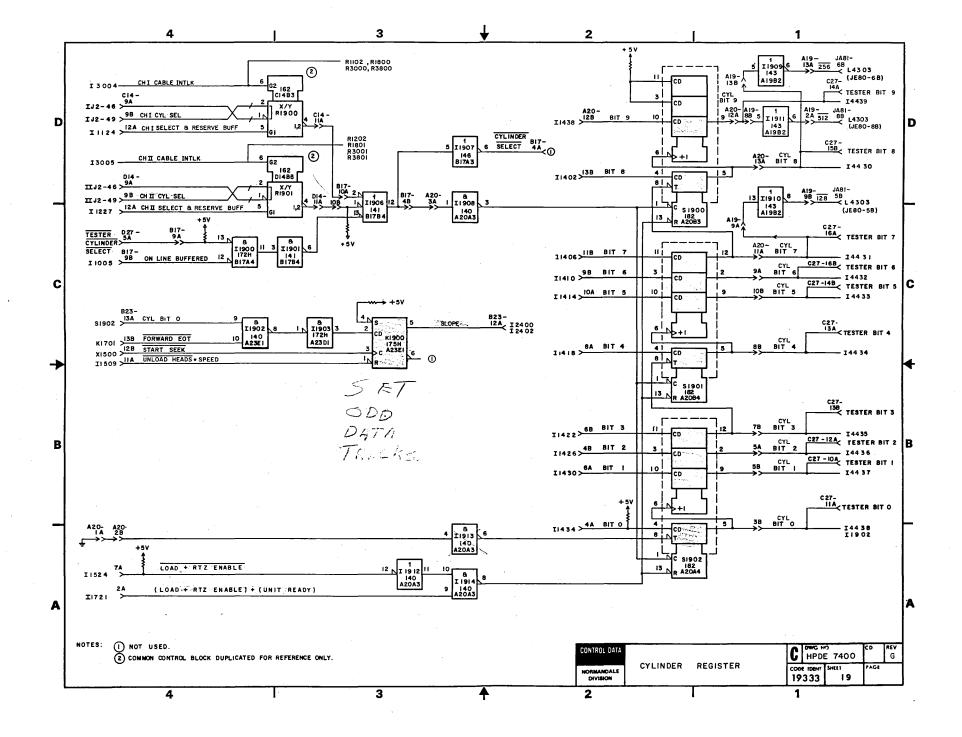


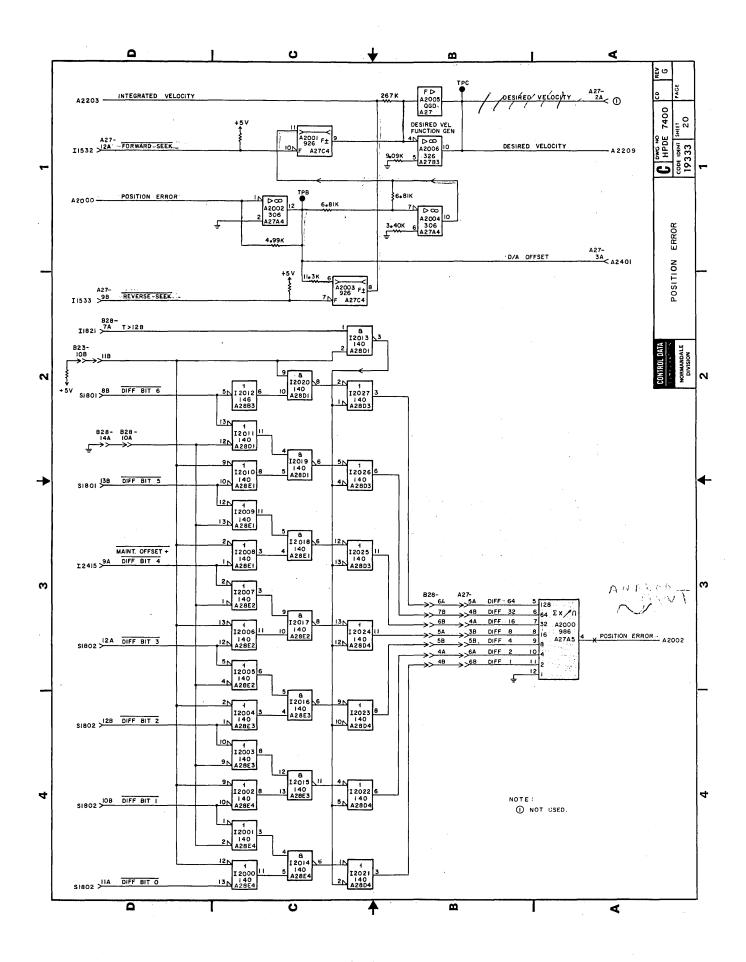


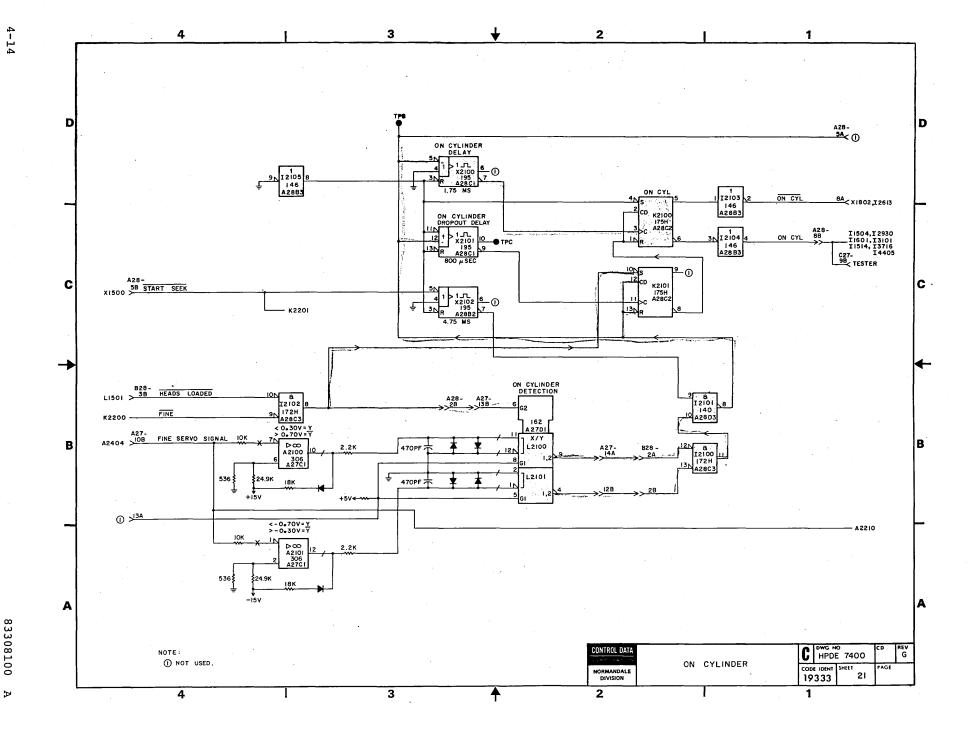
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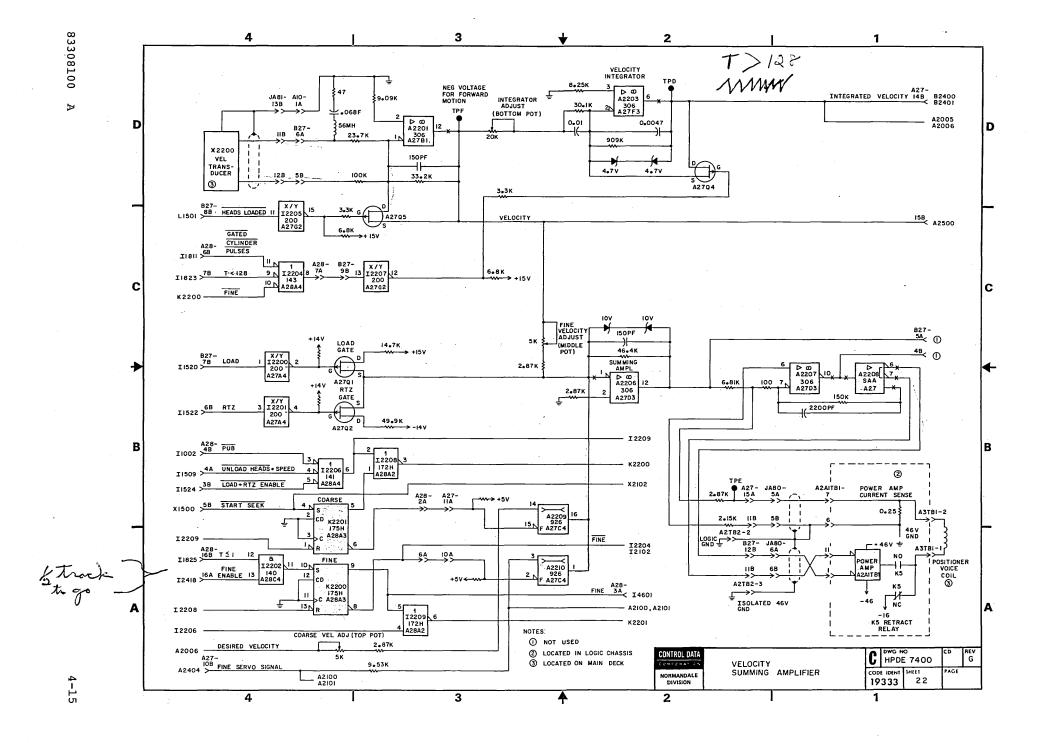


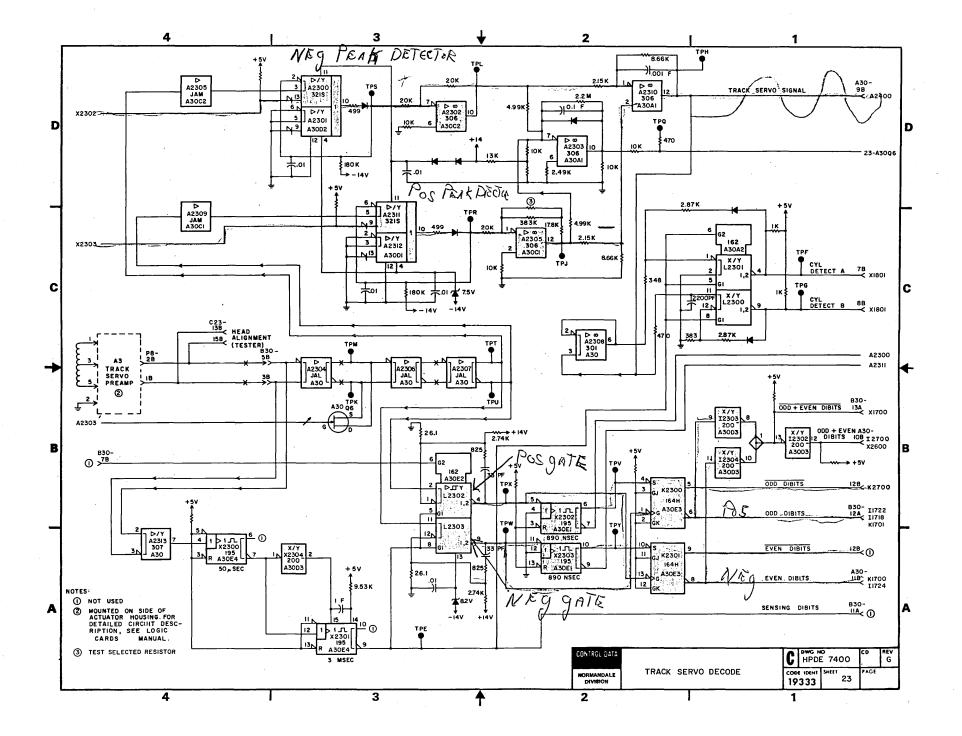


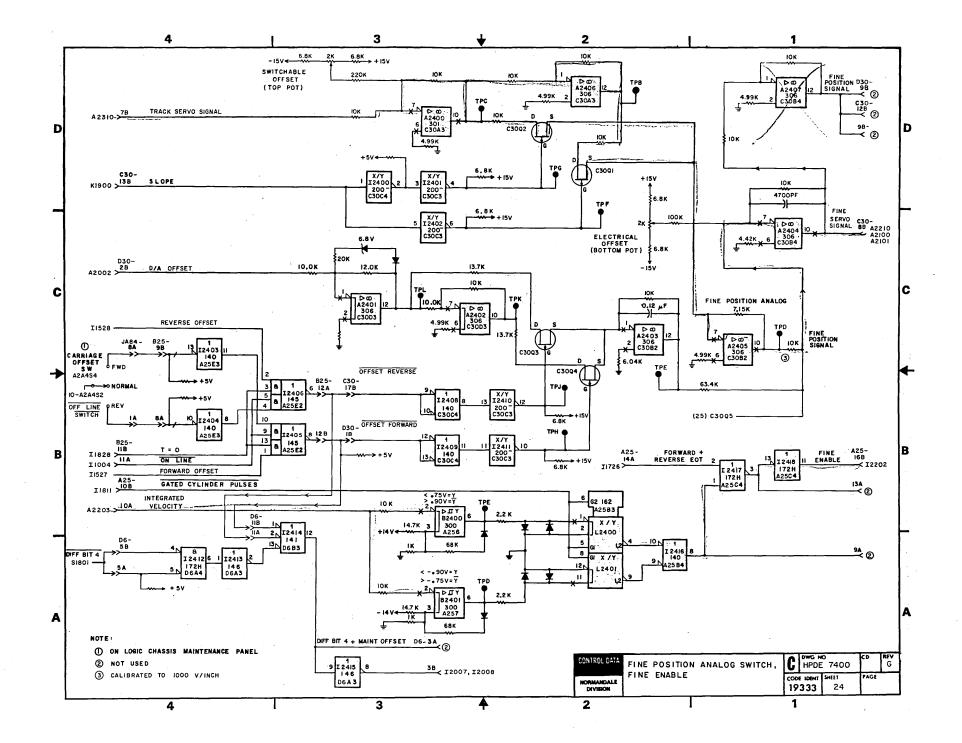




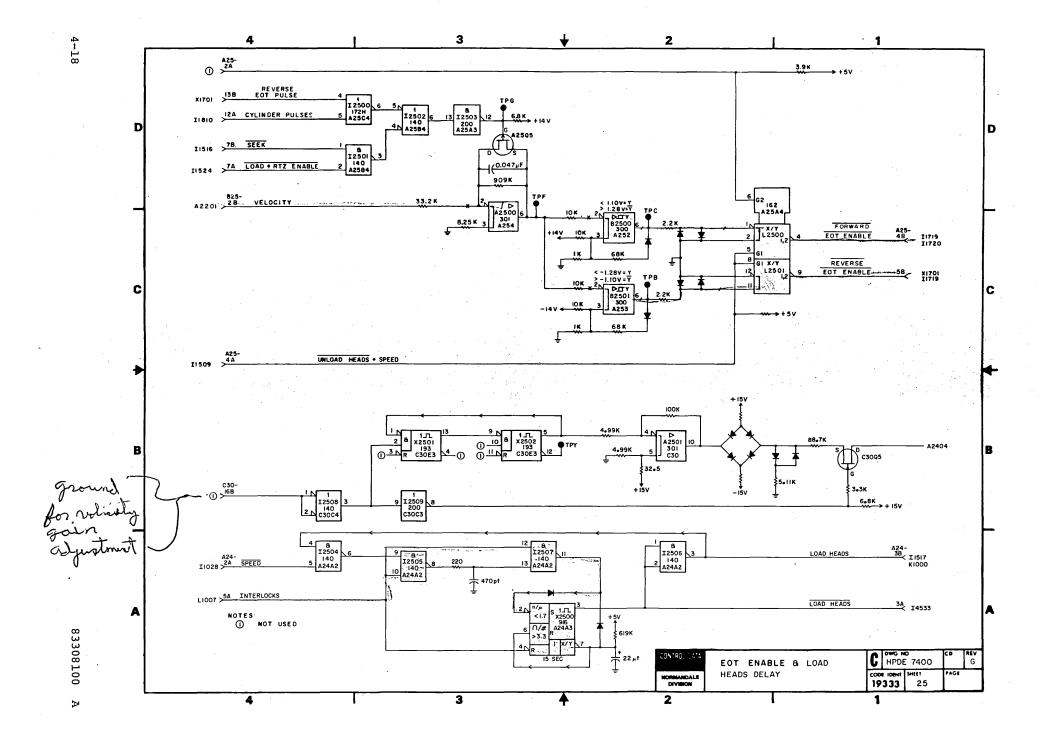


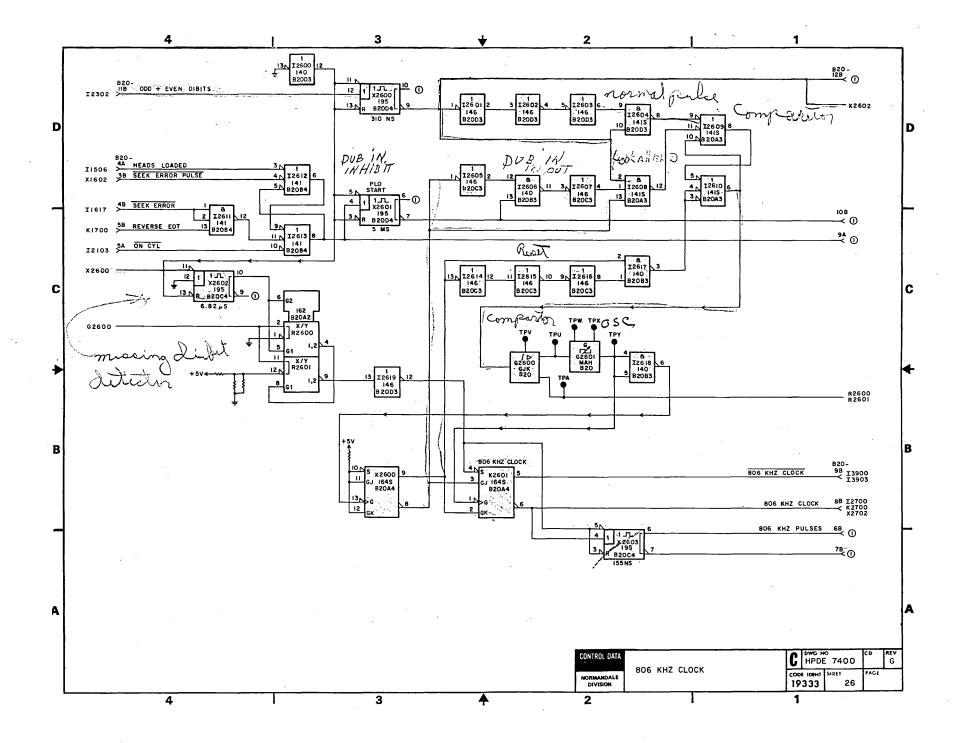


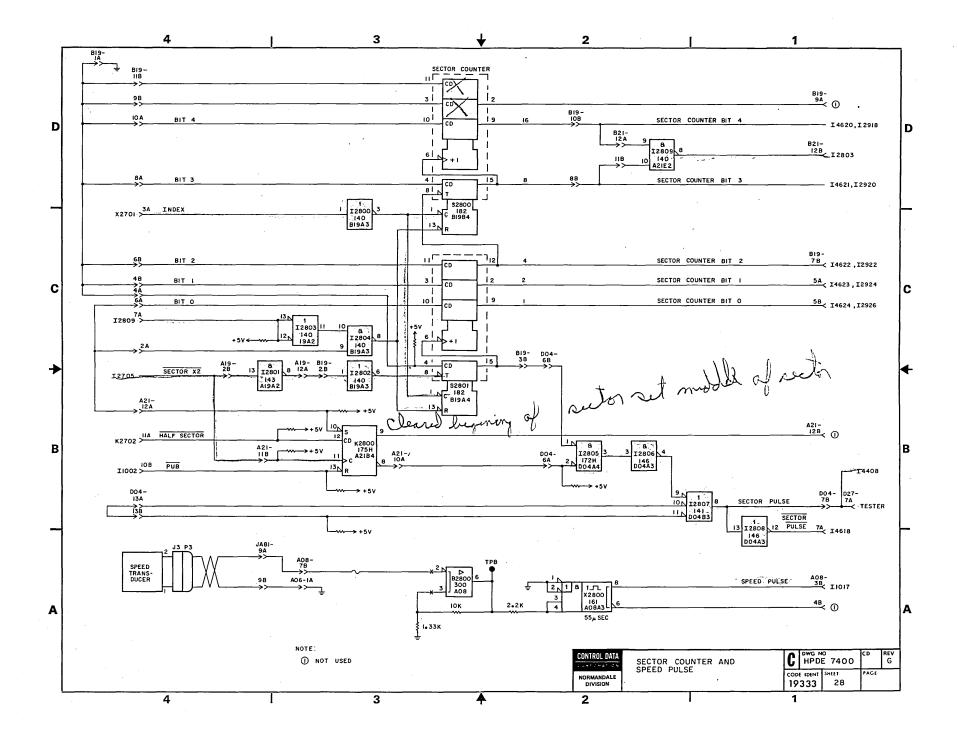




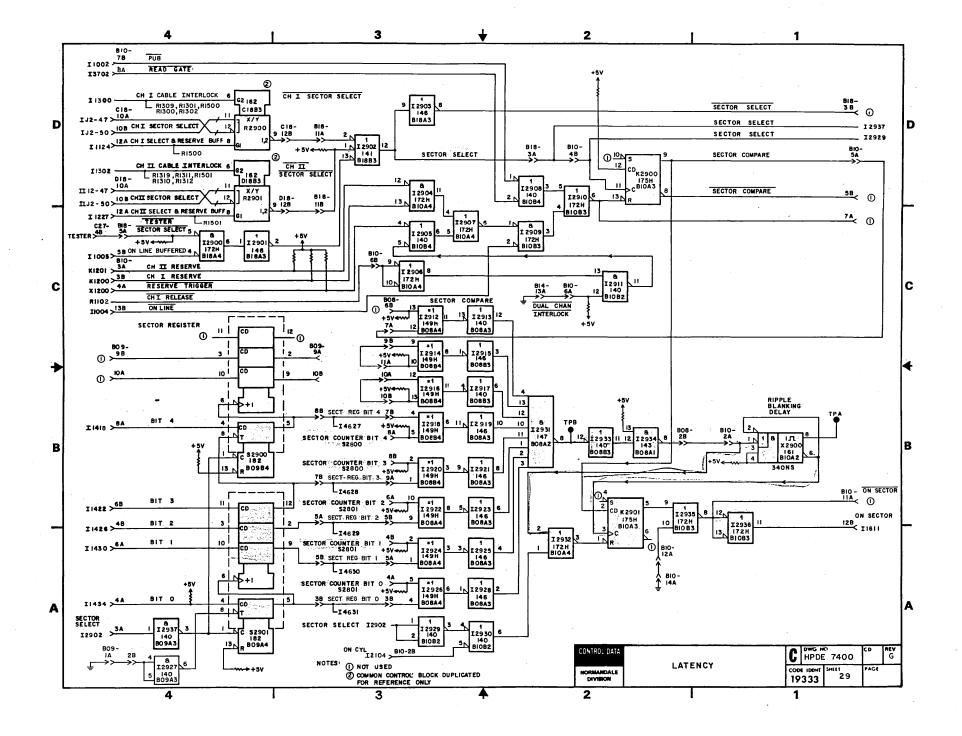
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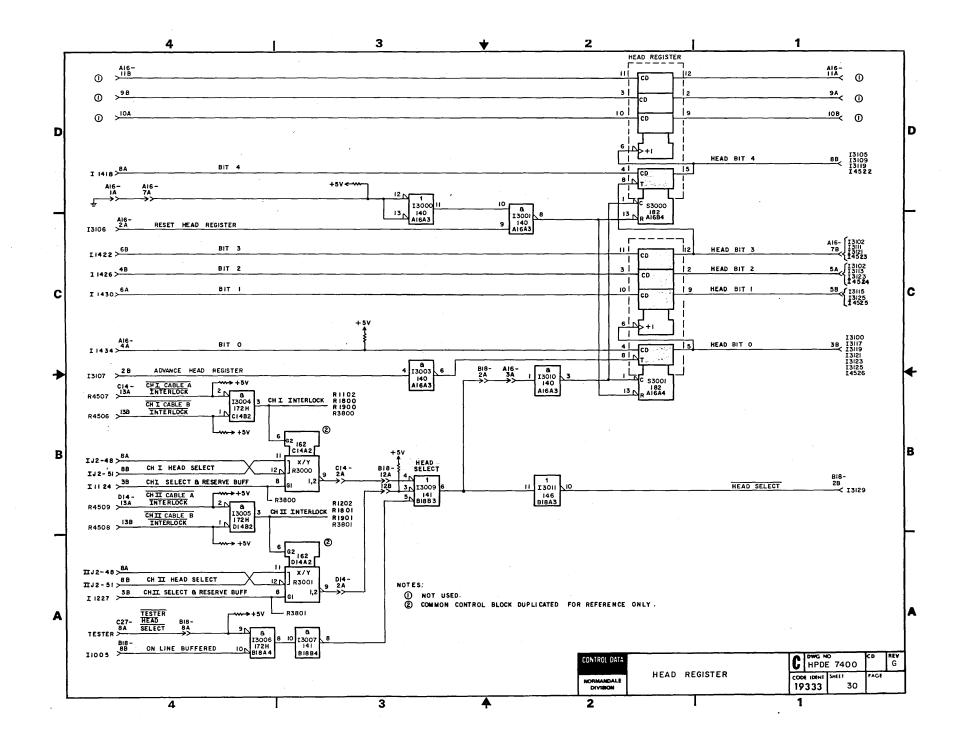


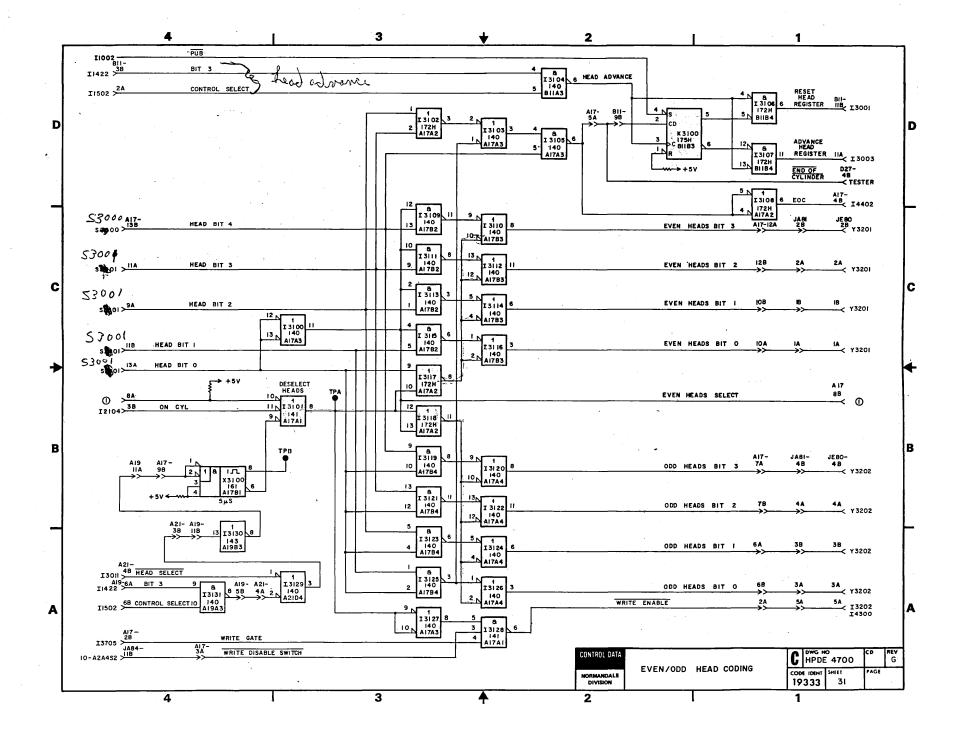


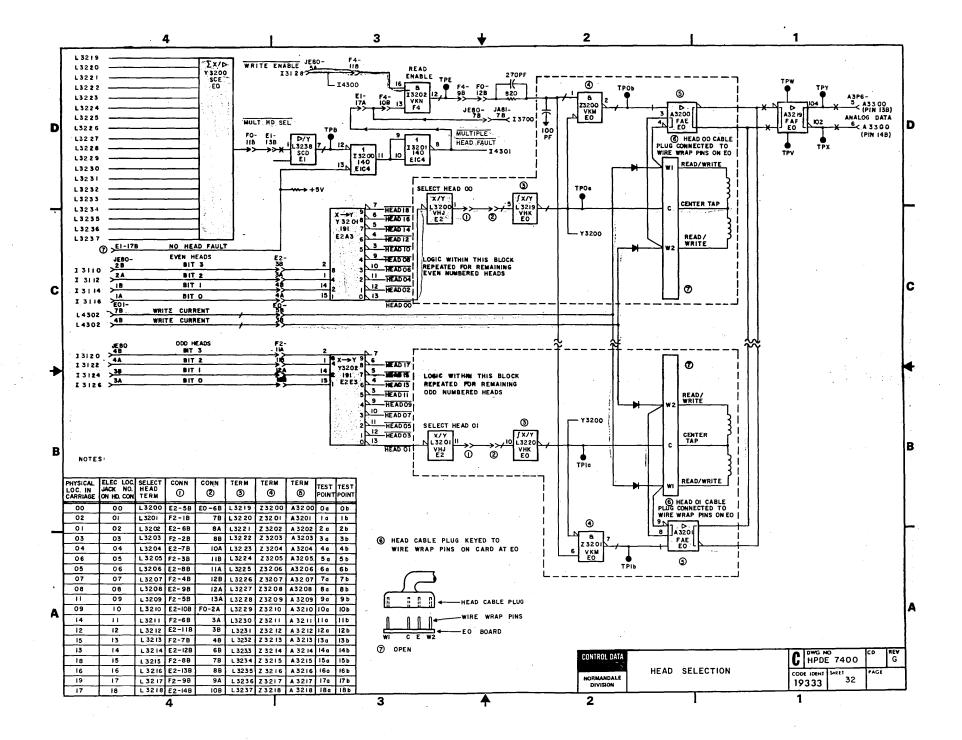


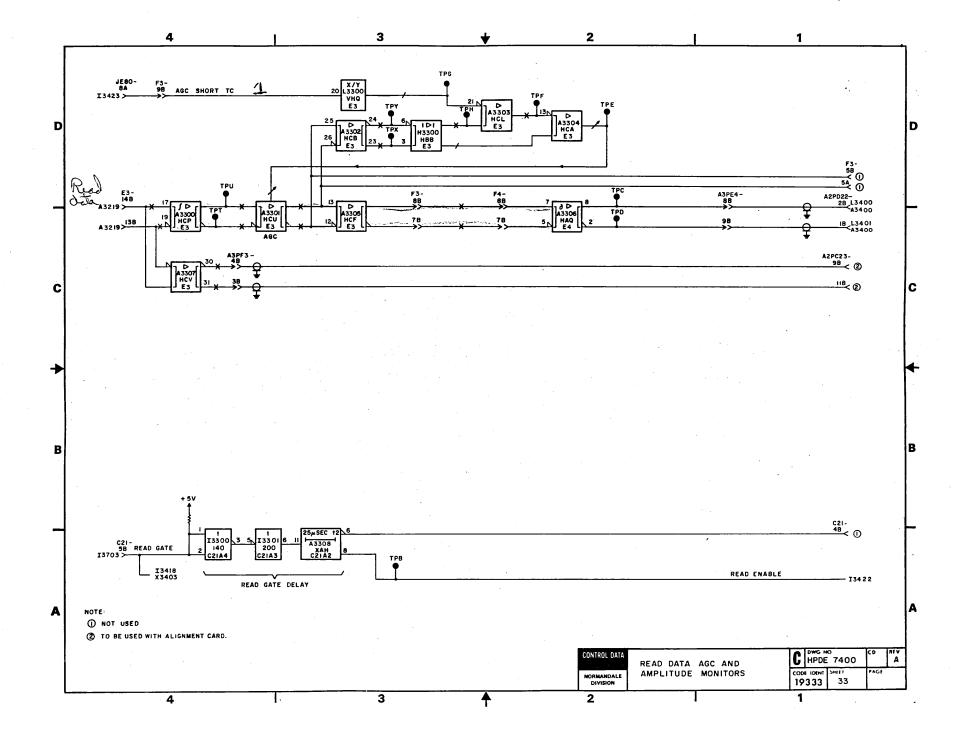
4 - 21

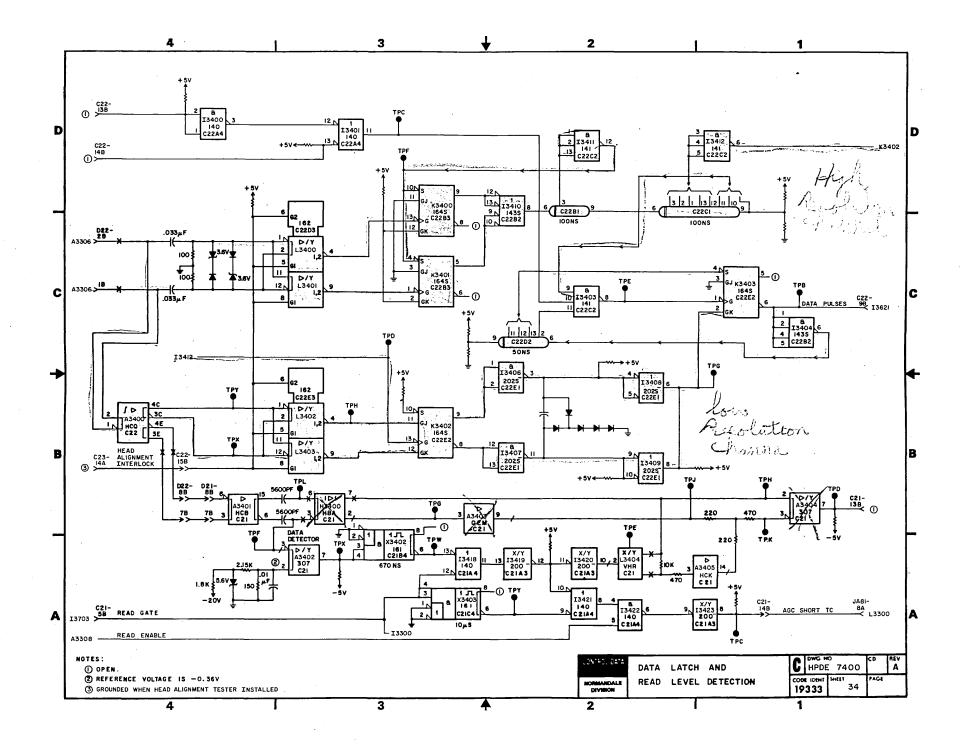




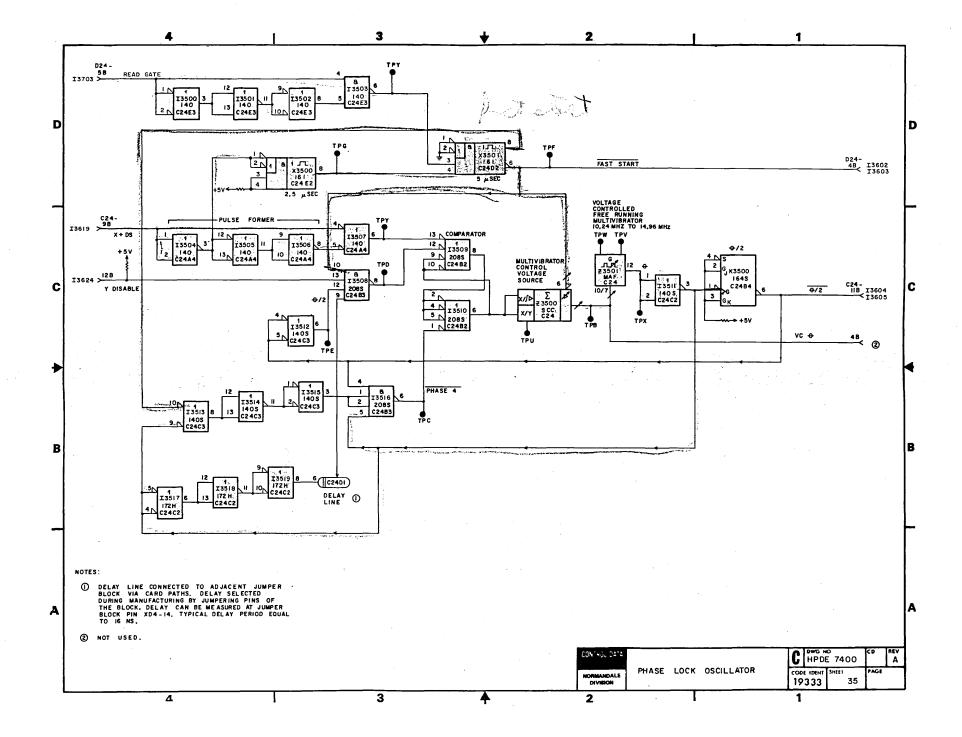


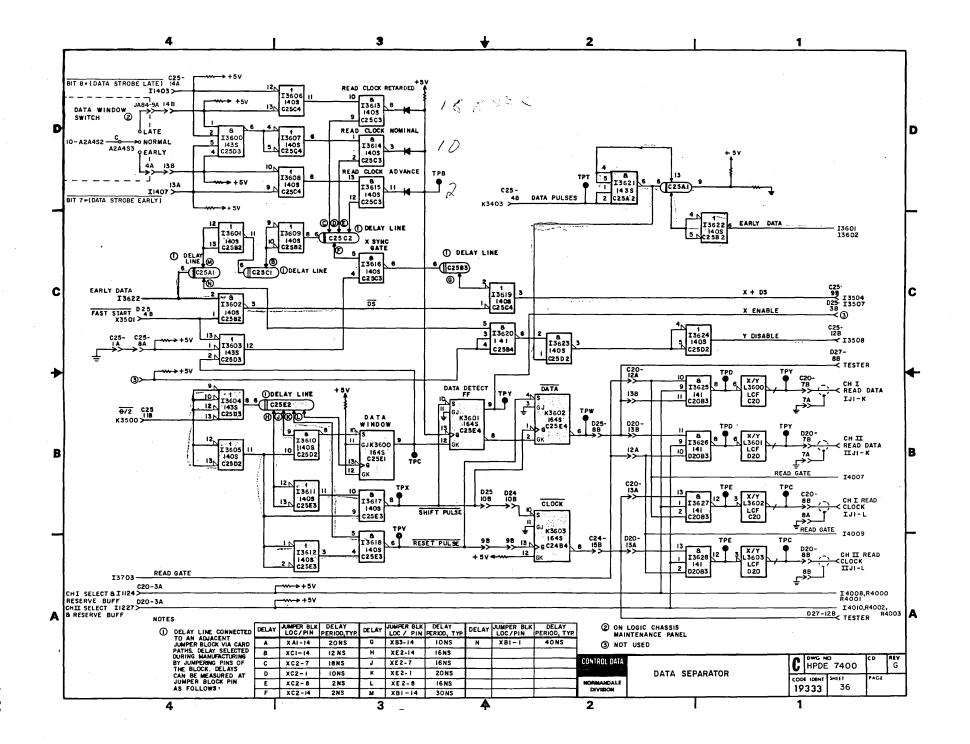


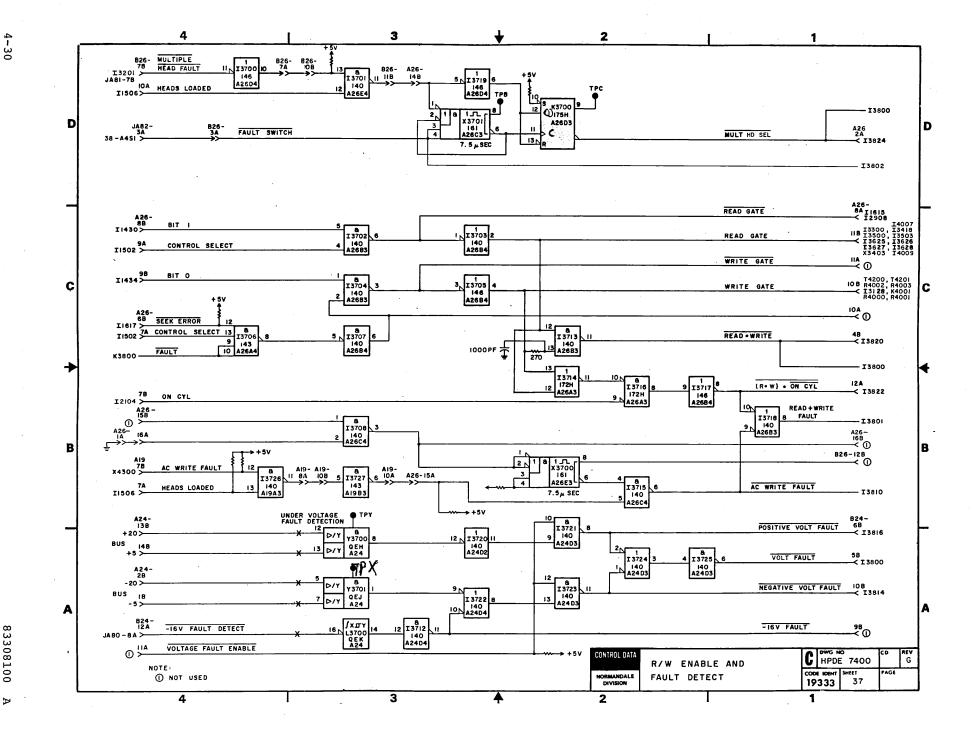


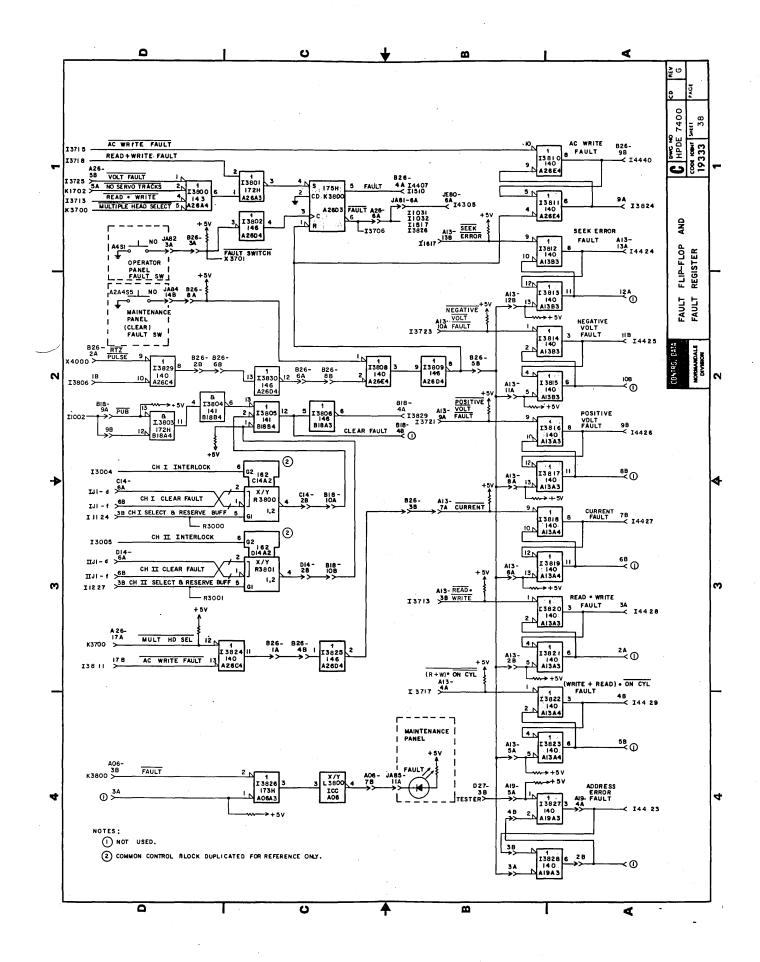


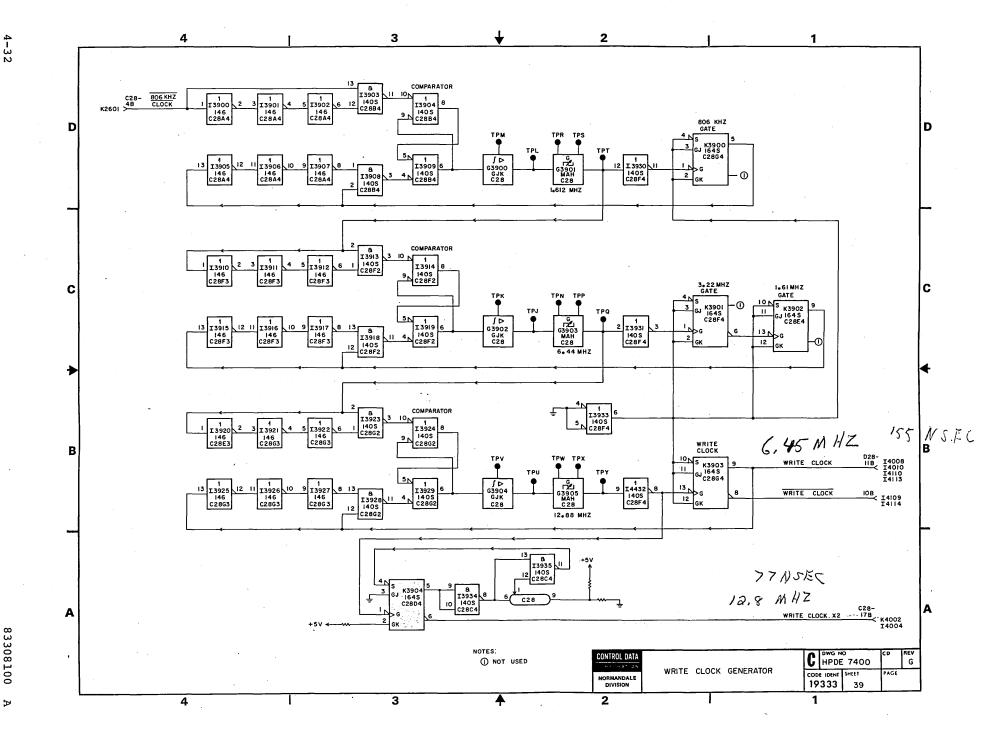
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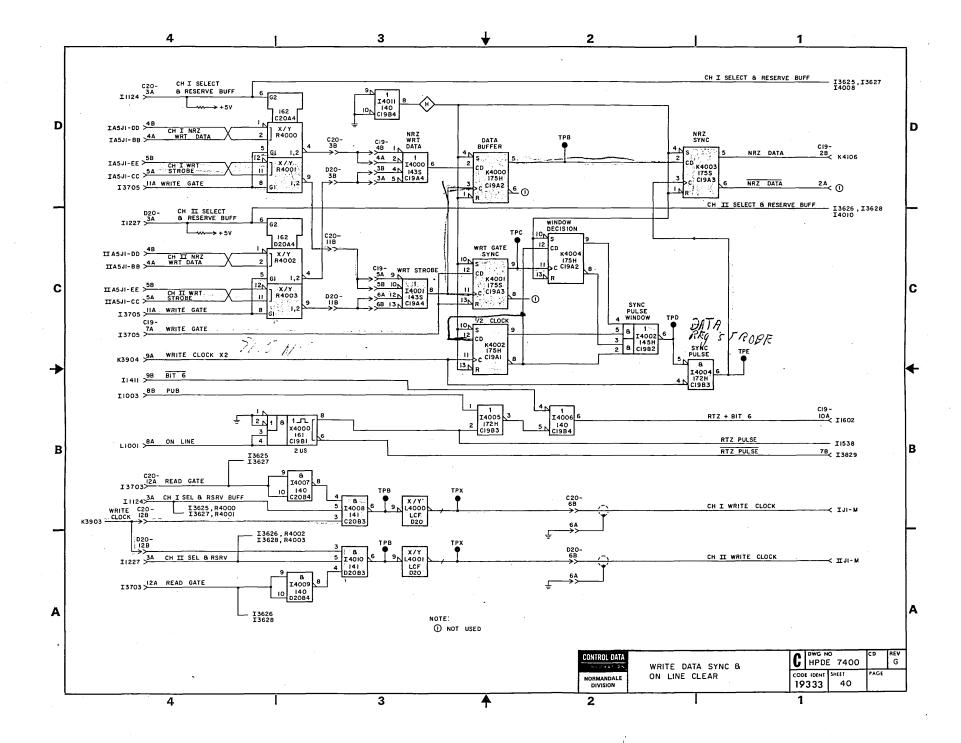




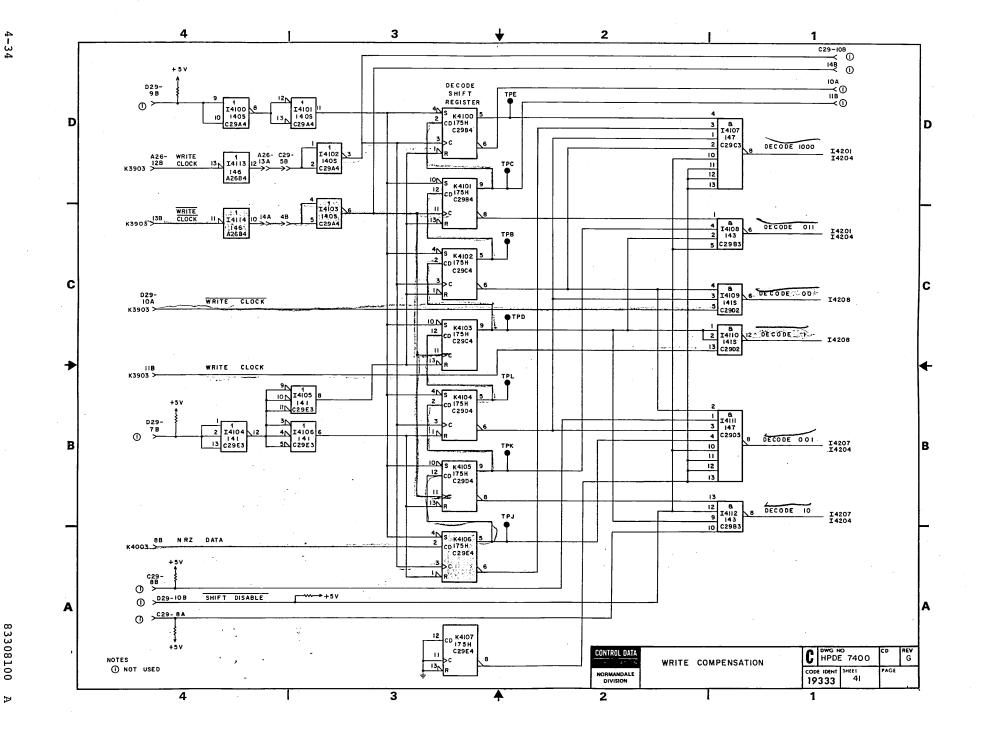


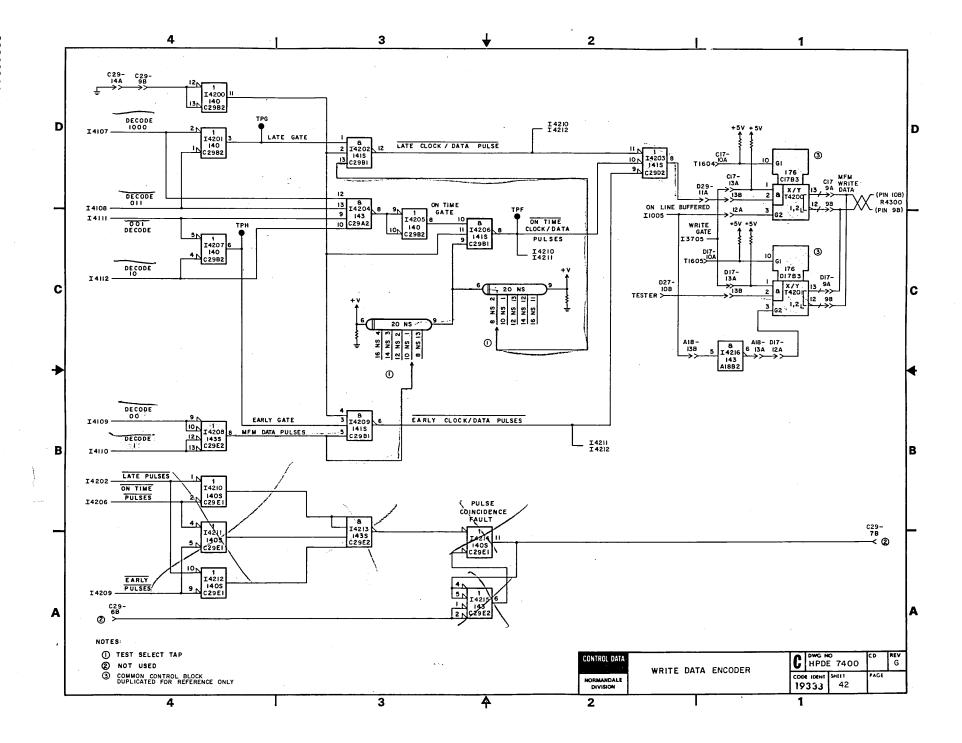




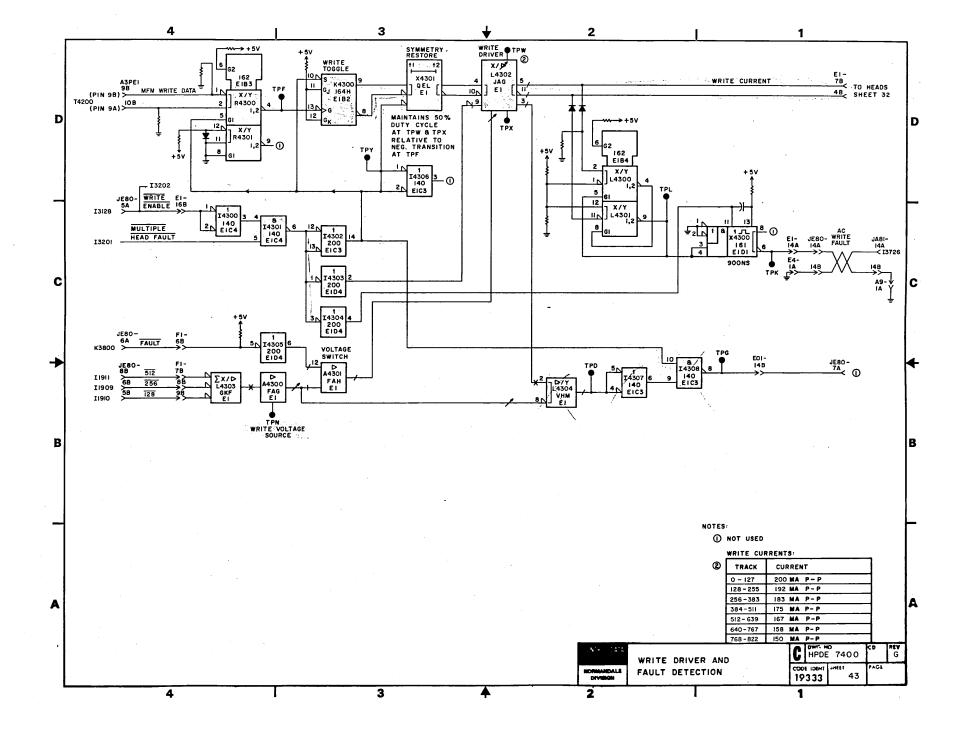


4-3

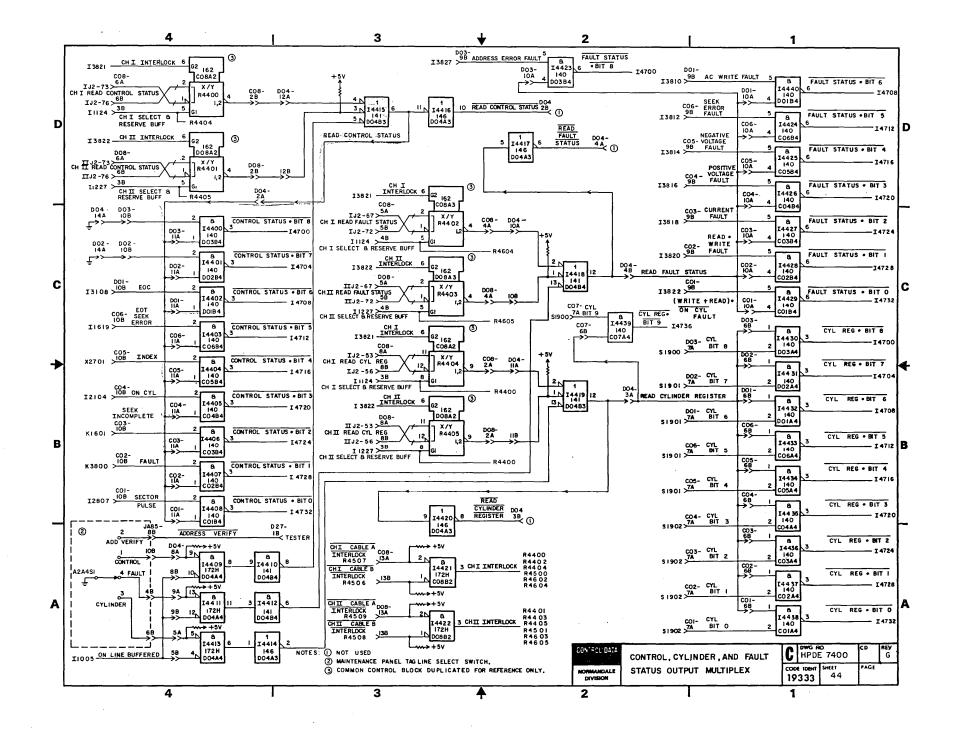


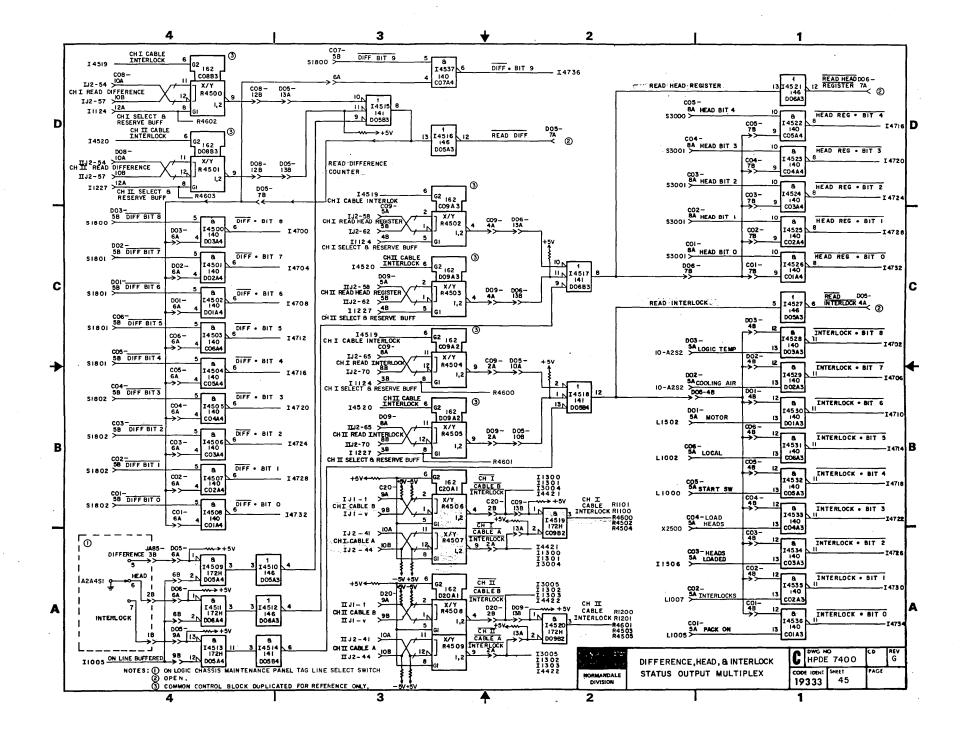


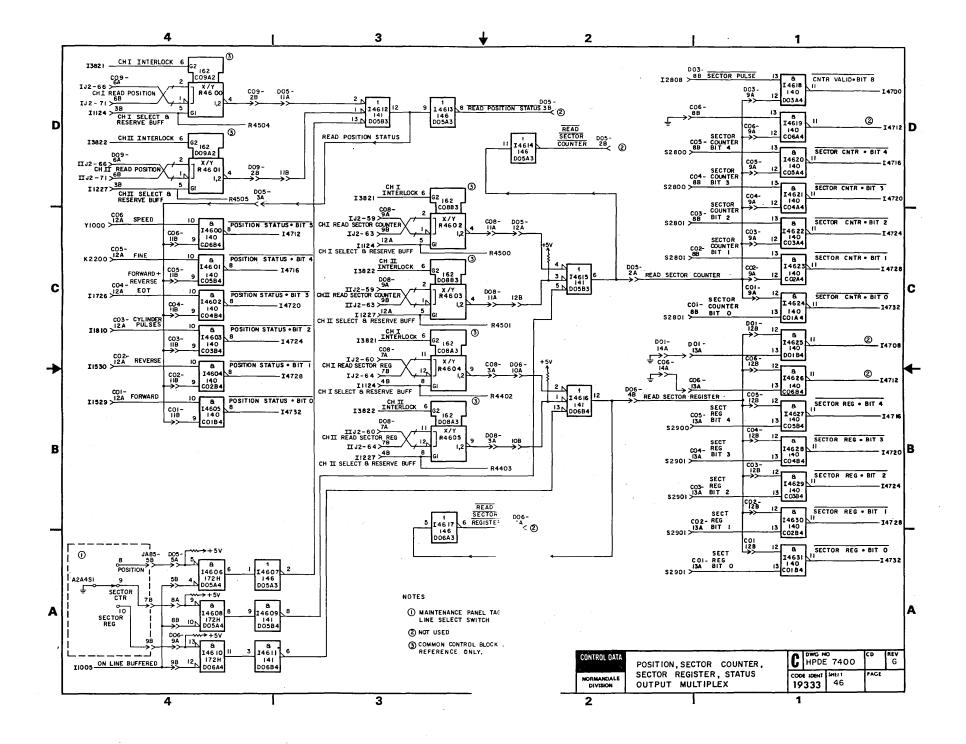
3,5

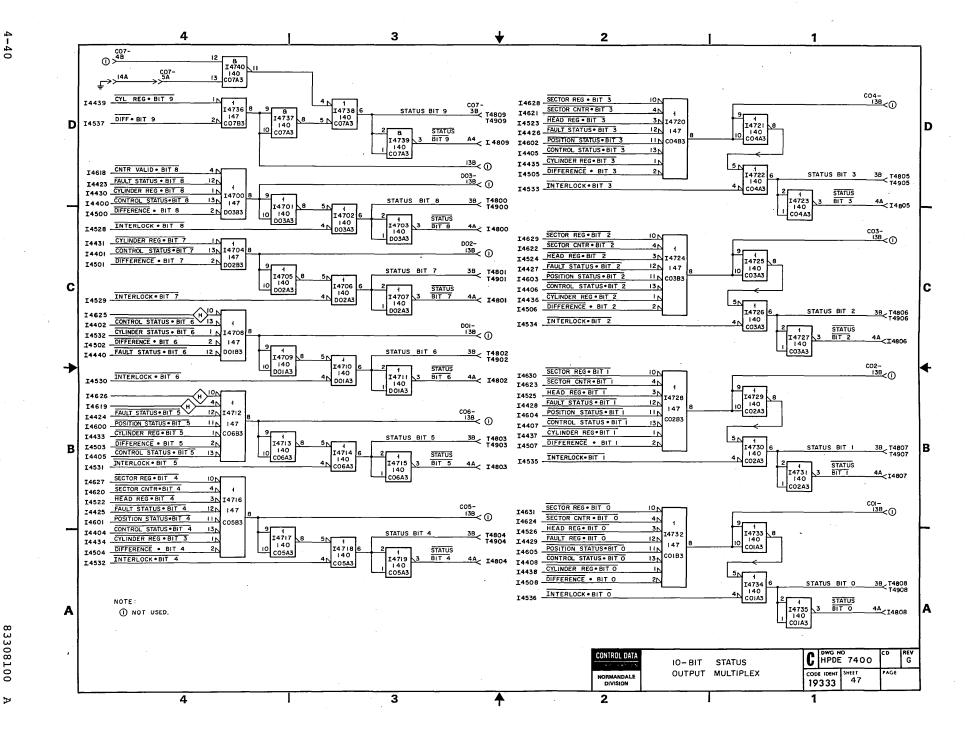


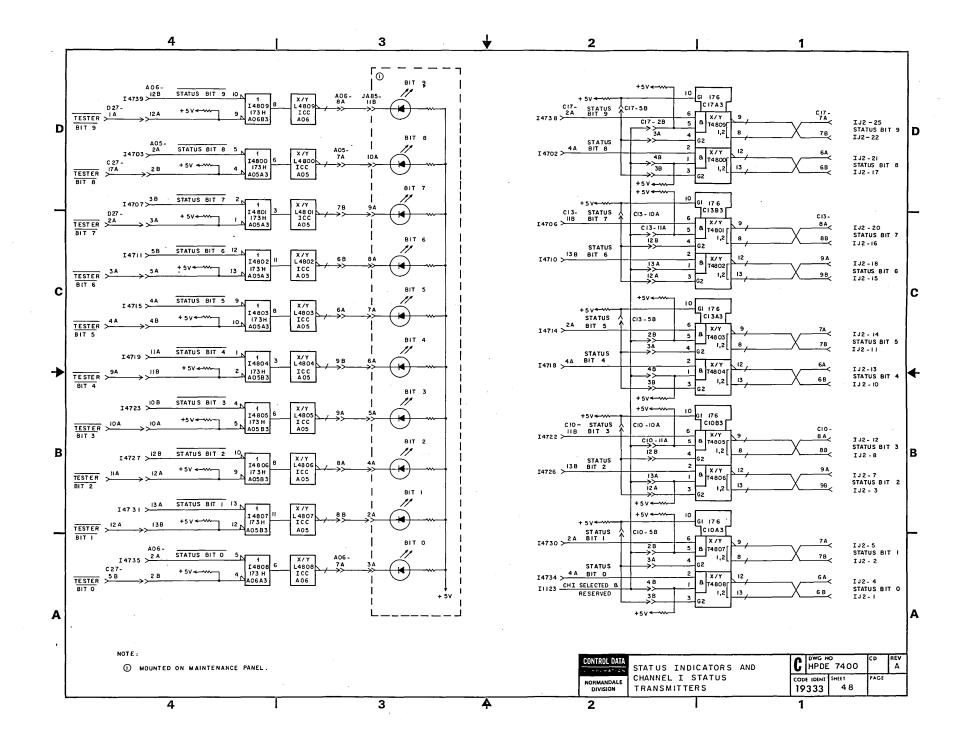
 $\triangleright$ 

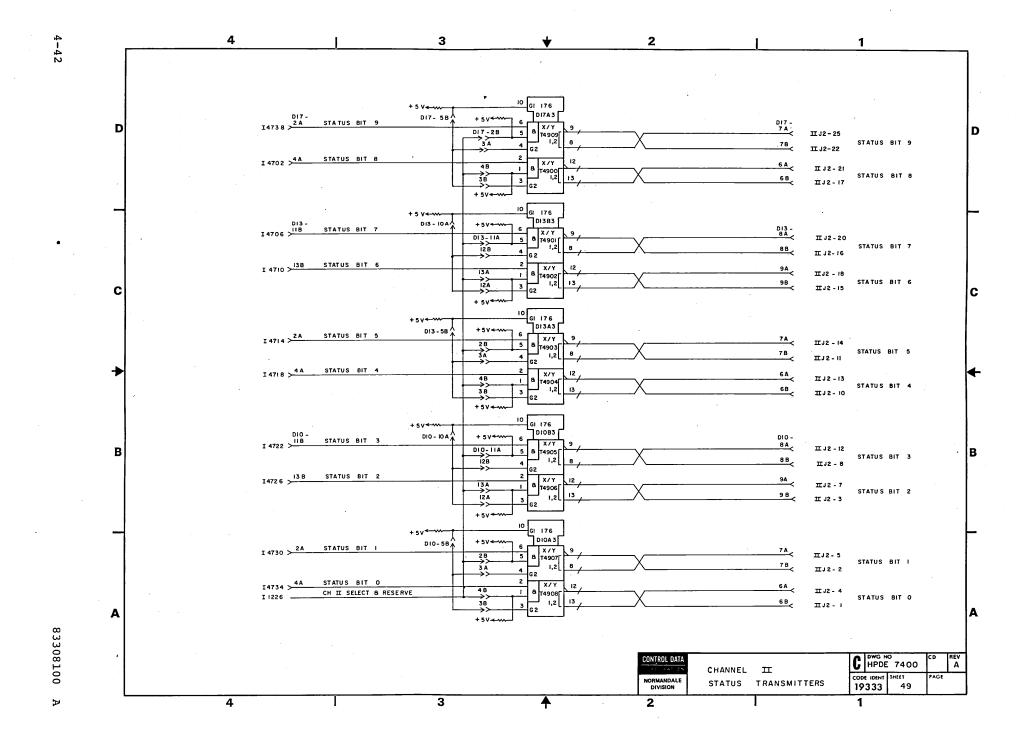


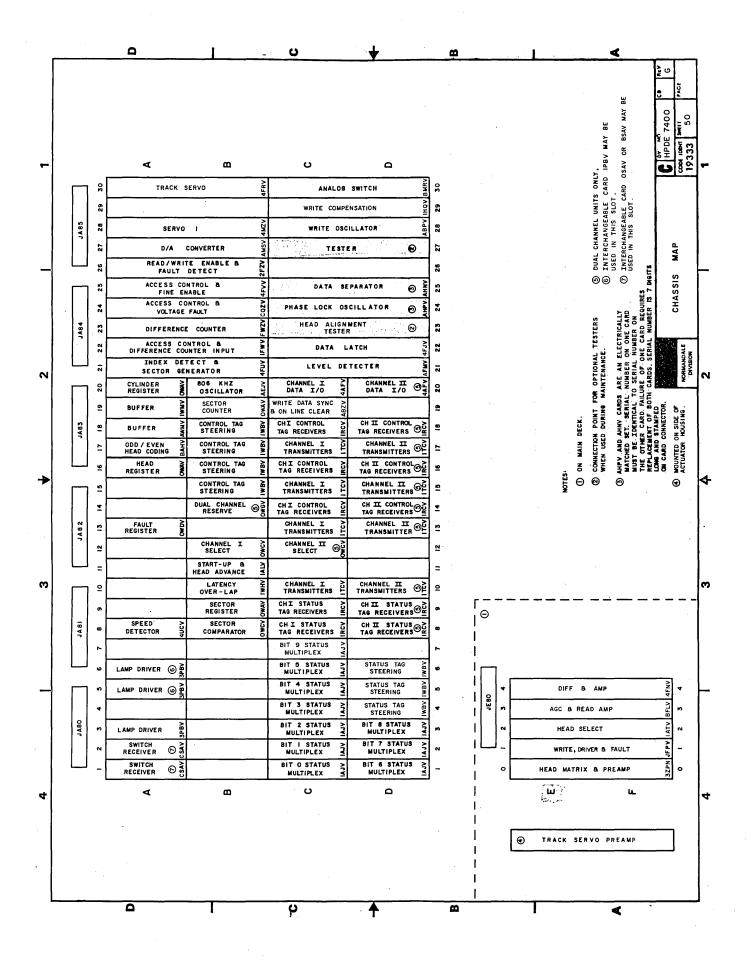


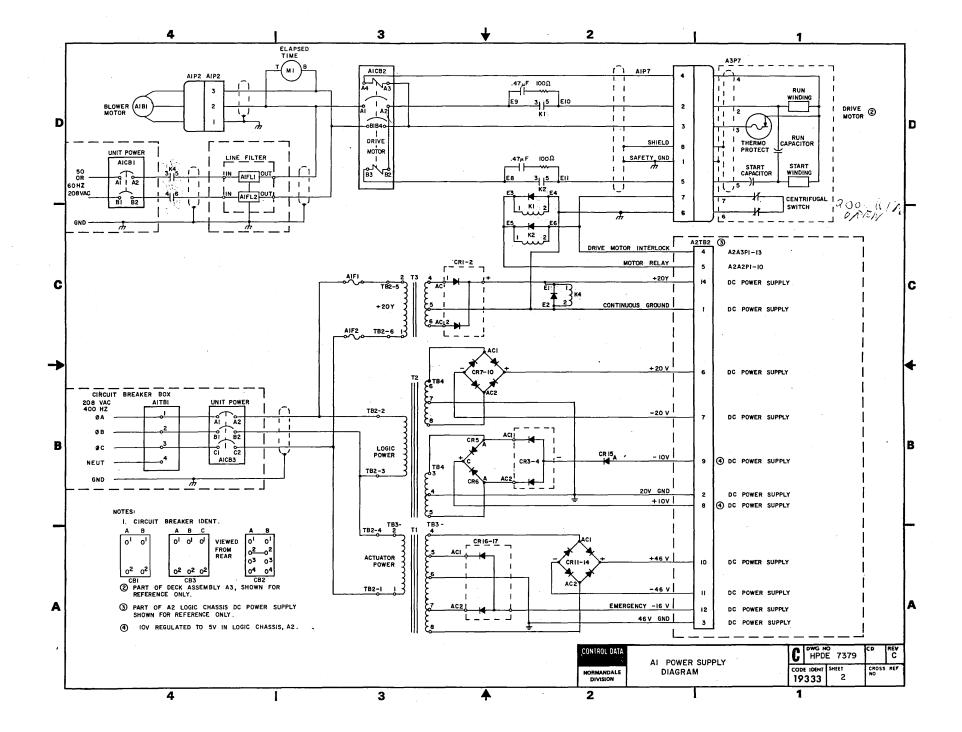


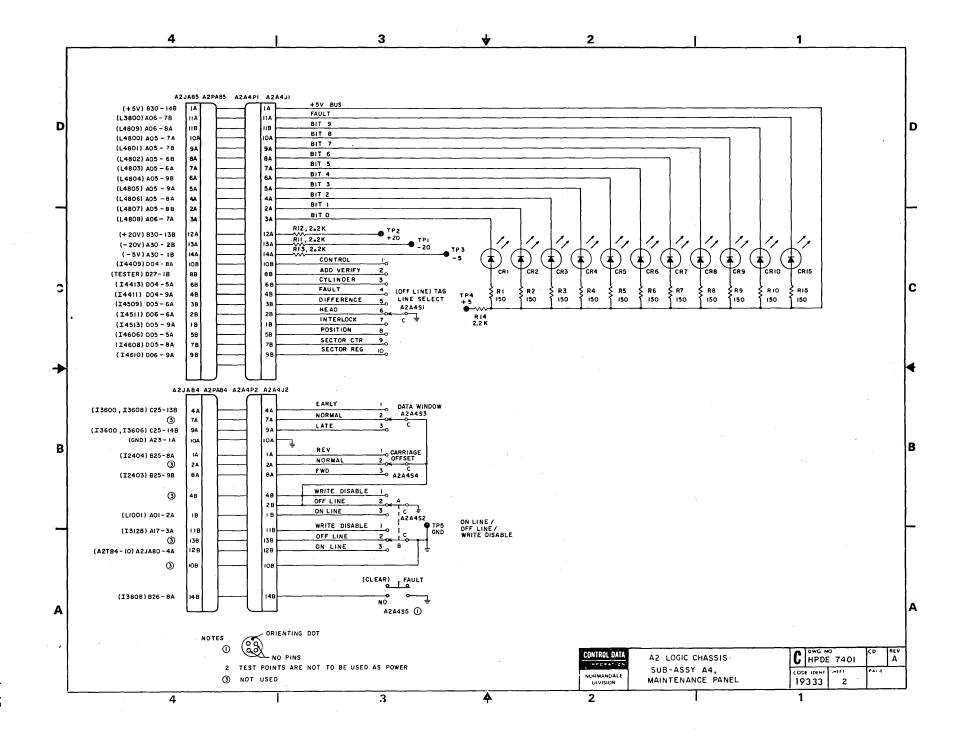


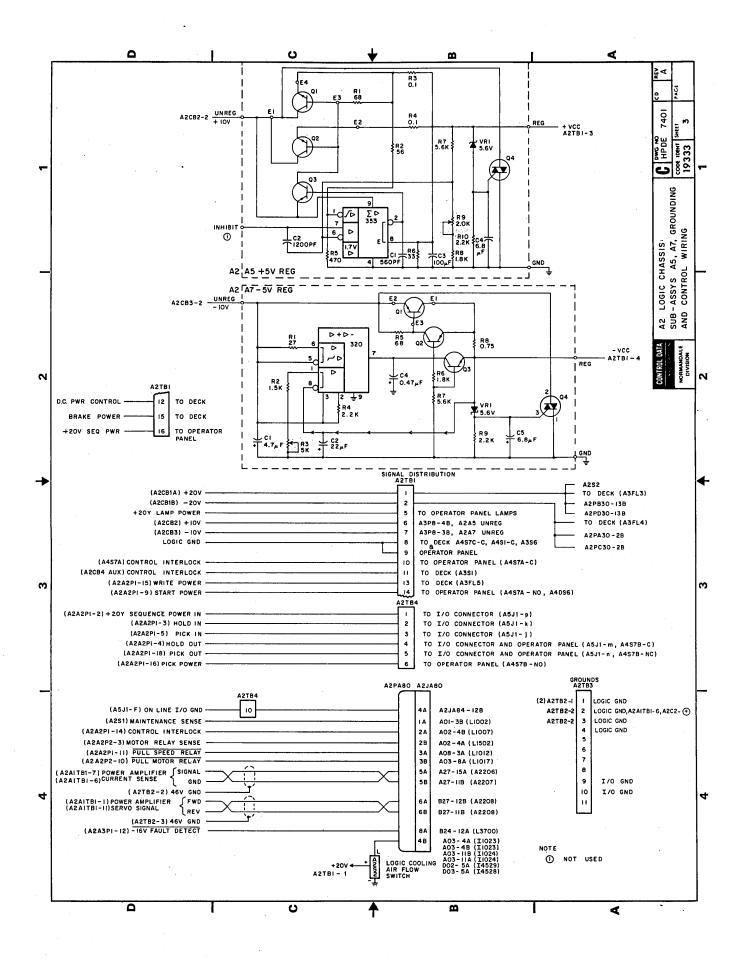


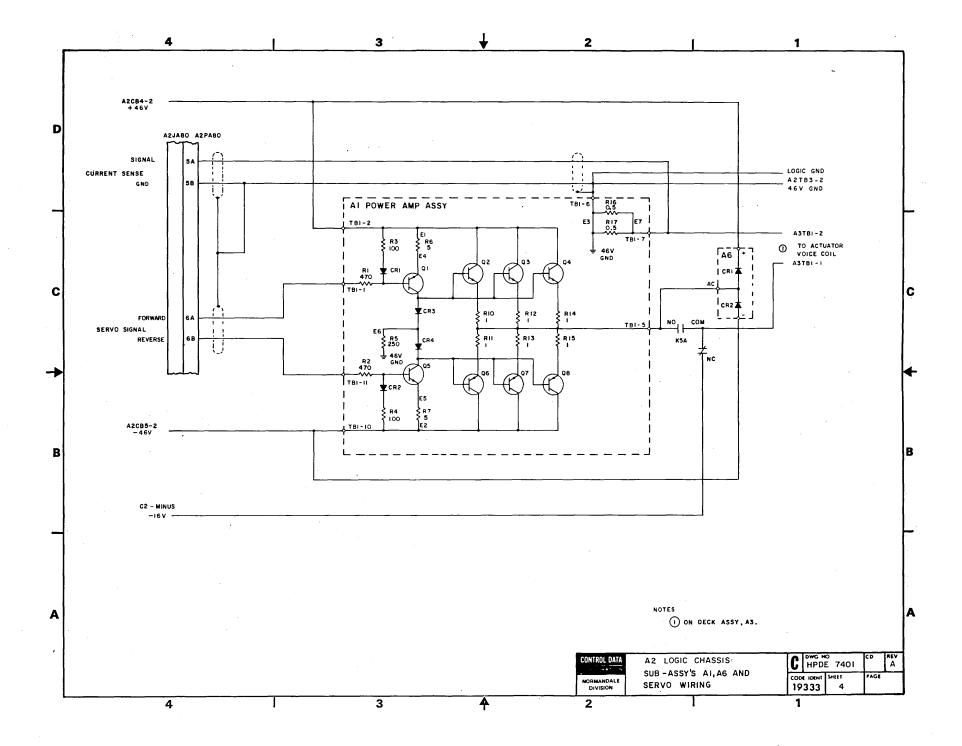






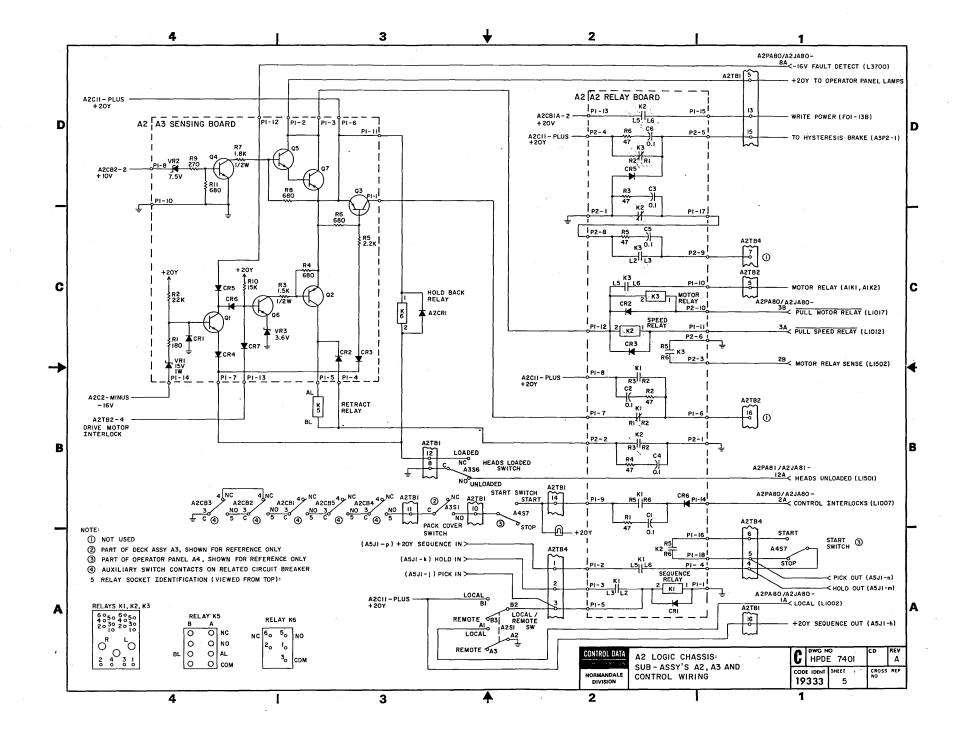


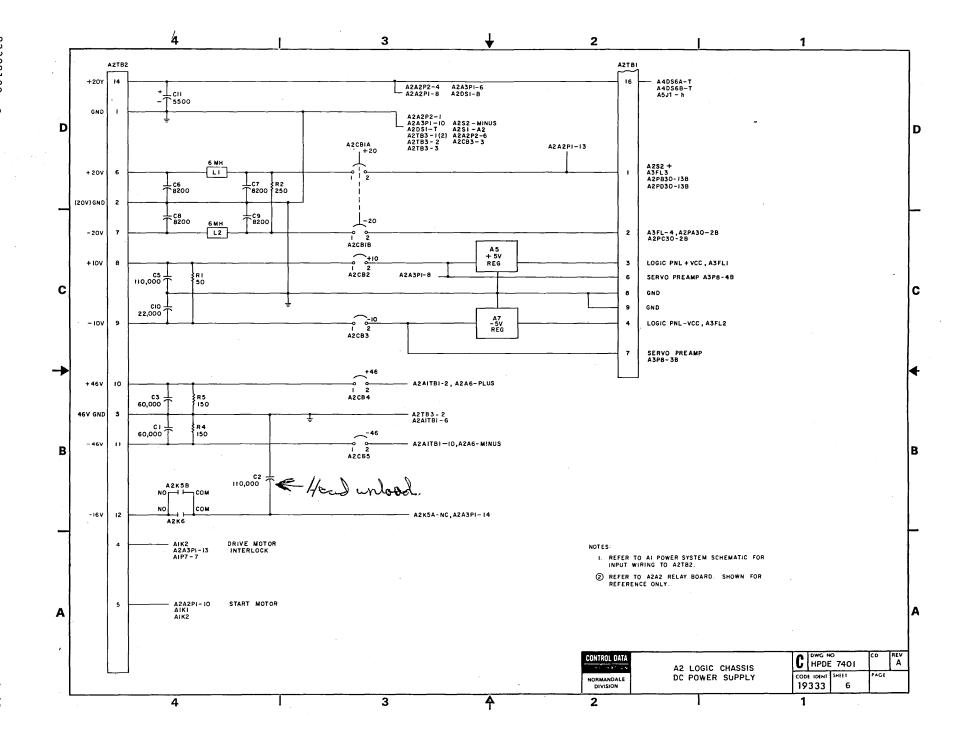


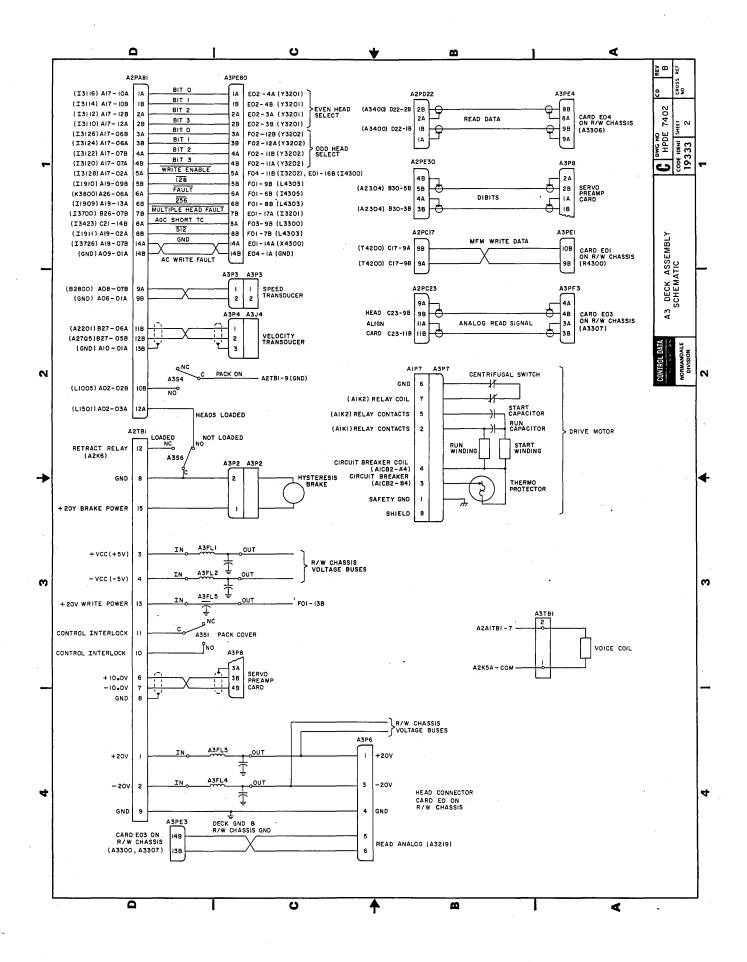


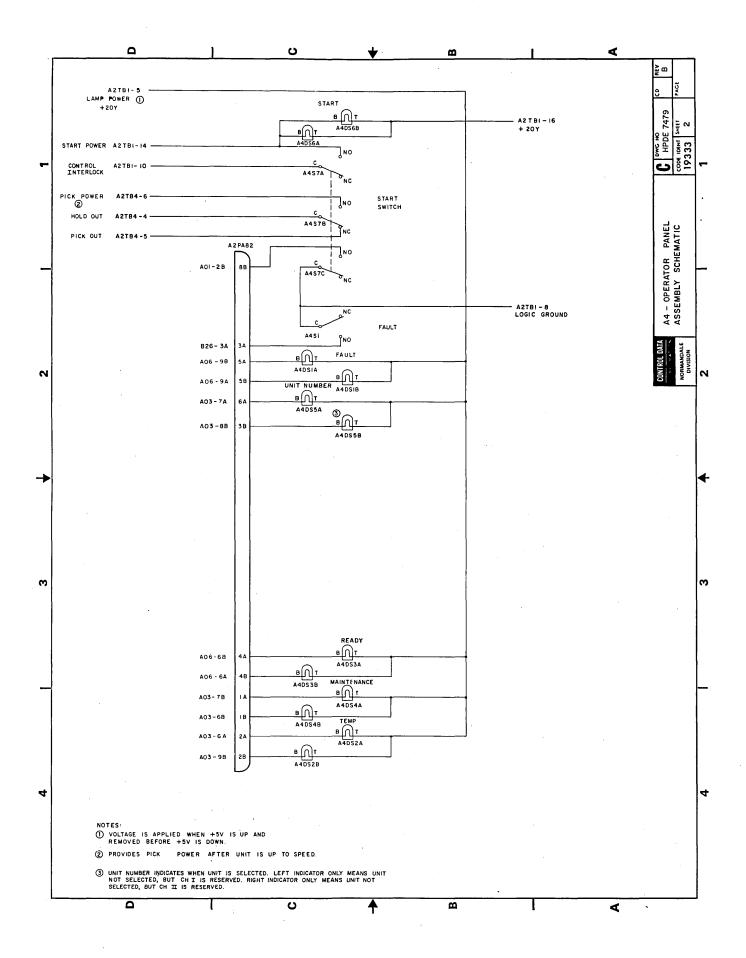
83308100

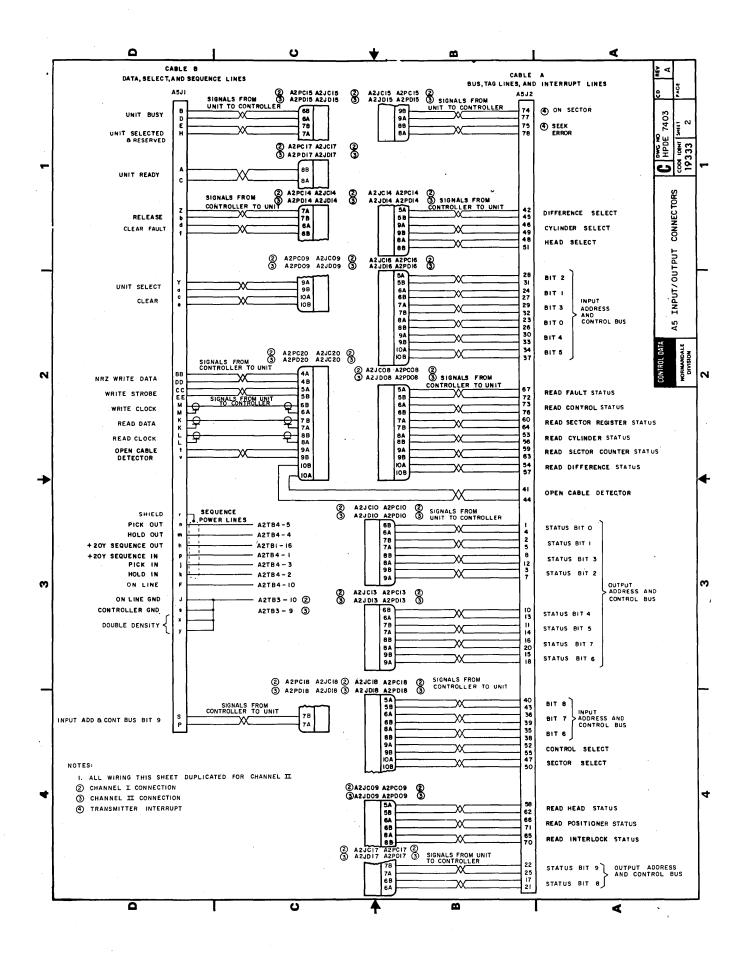
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SECTION 5

**WIRE LISTS** 

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## **WIRE LISTS**

#### INTRODUCTION

Wire lists are divided into two basic categories: wire wrap wire lists and non-logic wire lists.

# **WIRE WRAP WIRE LIST**

The wire wrap wire list provides signal name or number, wire origin, wire destination, and location of the wire on the pin.

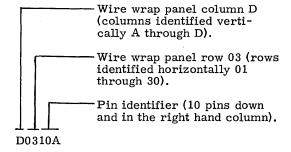
#### SIGNAL NAME OR NUMBER COLUMN

If the entry begins with a letter, the signal on the wire originates at the listed logic term. A multiple output is indicated when a term is repeated on successive line entries.

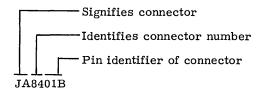
If the entry begins with a number, the signal on the wire generally originates at some point other than a logic term, such as a bus, test point, connector, etc.

#### ORIGIN/DESTINATION COLUMNS

The origin and destination columns in the wire wrap wire list locate the pins on the logic chassis as shown below:



If the origin or destination column is preceded by the letter J, the wire attaches to one of the connectors as shown below:



#### Z LEVEL COLUMN

The Z level denotes the vertical separation which an installed wire has relative to the surface of the wire wrap board. This vertical separation is maintained at both ends of the installed wire when it is wrapped on the pins. Two vertical separation distances are possible. A numeral 1 in this column indicates the smallest separation. A 2 in the column indicates the largest separation.

### **NON-LOGIC WIRE LIST**

Non-Logic wire lists provide wire origin/ destination information for harness assemblies and various panels.

The number identification is used to sequence the wire list and provide engineering reference for change order activity.

Wire color coding is as follows:

u - Black	5 - Green
1 - Brown	6 - Blue
2 - Red	7 - Violet
3 - Orange	8 - Gray
4 - Yellow	9 - White

In multi-digit color codes, the first digit denotes base color and the remaining digits denote tracer colors.

LOGIC WIRE WRAP (Ref:	77384302)		NL D	784	ENT NO.	SHEET NO.	RE
SIGNAL NAME OR NUMBER	651611		WIRE	Z			
IDENTIFICATION	ORIGIN	DESTINATION	COLOR			NOTES	
100004	AOLOZA	JA84018		1	ļ		
100001 100005	A01028	JA8208B		1			
L1002000	A0103B A0111A	JA8001A C0605A		1 1	Ī		
11006000	A01118	A0303A		i			
L1001000	AOIIZA	A0303B		i			
L1001002	A0112A	B1210A		2			
11004000	A01128	B1103A	]	2			
11004003	A0112B	B1013B		1			
L1000000 100008	A0113A A0202B	C0505A JA8110B		1			
100106	ACOSOA	JA8112A		i			
100105	A0203B	JA8110A		i			
100107	A0204A	JA8002B		1			
100009	A0204B	JA8002A		1			
11508000	A8020A	A1805A		ļ			
L1502000 I1013000	A0208A	D0105A A1807B		1	<b>1</b> .		
L1007000	A0209B	C0205A		1			
L1007001	A0209B	A0802B		ż			
11506000	A0210A	C0305A		2			
11506001	A0Ž10A	A1803B		1			
L1501000	A0210B	A0802A		1			
L1005000 L1005002	A0213A	B1105B		2			
11126001	A0213A A0302A	C0105A A0313A		1 2			
K1201001	A0302B	B1213A		2			
11006000	ACOCOA	A0111B		1			
11006001	AEOEOA	A0305B	}	2			
L1001000 L1001001	A0303B	A0112A		1			
10000601	A03038 A0304A	A0305A A0311B		2			
10000602	A0304A	A0304B		2			
10000602	A0304B	A0304A		- 2			
10000603	A0304B	A0311A		1			
L1001001	A0305A	A0303B		2			
I1006001 L1010000	A0305B A0306A	A0303A		2			
L1009000	A0306B	JA8202A JA8201B		1 1			
L1101000	A0307A	JAB206A		ī			
L1008000	A0307B	JA8201A		1			
L1017000	A0308A	JA8003B		1			
L1100000 L1011000	A0308B A0309B	BE058AL BS058AL		1		•	
10000603	A0311A	A0304B		i			
10000604	A0311A	D0305A		2			
10000600	A0311B	JAB004B		2			
10000601 11027000	A03118 A03128	A0304A A1805B		1			
I1126000	A0313A	B1108A	·	1			
11126001	A0313A	A0302A		2	`		
						4	
	- 1	1					
	- [						
	1	i	1	1			
	1						

TITLE LOCIC WIDE WEAD			WL D		ENT NO.	SHEET NO.	REV.
LOGIC WIRE WRAP		- <del> </del>	***	78	43	2	A
OR NUMBER	ORIGIN	DESTINATION	WIRE			NOTES	
IDENTIFICATION		Joe of Marin	COLO	RLEVEL		WOTES	
		T		<u> </u>			
K1200001	A03138	C1213A	1	2			
14703000	A0502A	D0304A		l ī	ł		
100055	A0502B	C2717A	Ì	lī	1		
100056	A0503A	D2702A		l i			
14707000	A0503B	D0204A		1	j		
14715000	A0504A	C0604A		1	1		
100058	A0504B	D2704A	l	1 1	1		
100057	A0505A A0505B	D2703A		1			
14711000 L4803000	A0506A	D0104A JA8507A	ŀ	1 1	1		
L4802000	A0506B	JA8508A		i	1		
L4800000	A0507A	JA8510A	ļ	i			
L4801000	A0507B	JA8509A	ì	l i	Ì		
L4806000	A0508A	JA8504A	ľ	1	1		
L4807000	A05088	JA8502A		1			
L4805000	A0509A	JA8505A	1	1	1		
L4804000	A0509B	JA8506A		1			
100118 14723000	A0510A A0510B	D2710A	- 1	1 1			
14723000	A0511A	C0504A	1	li			
100117	A0511B	D2709A	-	l i			
100119	A0512A	D2711A		i			
14727000	A0512B	C0304A	ļ	1	<b>[</b>		
14731000	A0513A	C0204A		1			
100120	A0513B	D2712A	İ	1			•
100086	A0601A	JA8109B	ŀ	1	ļ		
14735000 100121	A0602A A0602B	C0104A	ŀ	1	ŀ		
K3800001	A0603B	A2203B	1	2			
K3800002	A0603B	A0611A	l	i	1		
11622001	A0604A	A0605B		l ī	ł		
11622000	A0605B	B2405A	1.	l Ž	•		
11622001	A0605B	A0604A	ŀ	1	ļ		
L1014000	A0606A	JA8204B	ļ	1			
L1013000	A0606B	JA8204A		1			
L4808000	A0607A A0607B	JA8503A	ļ	1			
L3800000 L4809000	A0608A	JA8511A JA8511B	l	1			
L1016000	A0609A	JA8205B	١.	1 1			
L1015000	A0609B	JA8205A	ļ	l i	ĺ		
K3800003	A0610B	A0611A		2			
K3800004	A0610B	JA8106A		l ī			
K3800002	A0611A	A0603B		1			
K3800003	A0611A	A0610B		2			
10016300 14739000	A0612A A0612B	D2701A C0704A	ŀ	1 1			
L1501000	A0802A	A0210B	1	li			
L1501001	A0802A	A1804B		l ż			
L1007001	A0802B	A0209B	ļ	2			
L1007002	A0802B	B1104B		ī			
L1012000	A0803A	AE003A	l	1			
X2800100	A0803B	A0811B		1			
		1					
	1						
	1						
•	1						
		<b>'</b> ]			]		•
		1	1				
	İ	1	<u> </u>		1		
		1		1	<u></u>		

TITLE  LOGIC WIRE WRAP			WL D'	OCUM 784	ENT NO. 43	SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE COLOR	Z LEVEL		NOTES	
	A0804A A0804B A0805B A0806B A0806B A0809A A08011A A0811A A0811A A0811A A0814A A0901A A1305A A1505A A1605A A1605B A1605B A1605B A1605B A1605B	B2408B C0612A A1807A B1104A JA8109A A0814A A2203A A0814A A0809A A0812A JA8113B A1305A C0209B A1305A C0209B A1306A A1305A C0309B A1306A A1306A A1306A A1306A A1310B A1306A A1311A B2406B B2410B A1311A B2406B B1111A B1111A B1111A B1111A B1111A B1507B B1111B B1507A C0108A B111B B1507A C0108A B111B B1709A C0108A B1709A C0108A B1709A C0108A B1709A C0108A B1709A C0108A B1709A C0108A B1709A C0108A C0108A B1709A C0108A B1709A C0108A C0108A B1709A C0108A B1709A C0108A C0108A	COLOR				
			}				

TITLE  LOGIC WIRE WRAP			WL D		ENT NO.	SHEET NO.	 REV.
SIGNAL NAME			WIRE	2	843	4	 A
OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION		LEVEL		NOTES	
I1430003 I1430004	A1606A A1606A	B1503A B0906A		2			
11422002	A1606B	B1504B	Ì	2			
11422003	A1606B	A1906A		1			
1000320GND S3001300	A1607A A1607B	A1601A A1711A	1	1			
S3001301	A1607B	C0408A		2			
I1418002 I1418003	A1608A A1608A	B1607B B0908A		2			
\$300000	A1608B	A1713B		i			
\$3000001	A1608B	C0508A		2			
I3128000 I3705001	A1702A A1702B	JA8105A A2610B	1	1 2			
100002	A1703A	JA8411B		1			
I2104004 I2104005	A1703B A1703B	A2213A B1002B	į.	1 2			
13108000	A1704B	D0110B		1			
13105000	A1705A A1705A	D2704B	l	2			
I3105001 I3124000	A1705A	B1109B JA8103B		1 1			
13126000	A1706B	JA8103A		1			
I3120000 I3122000	A1707A A1707B	JA8104B JA8104A	1	1			
\$3001200	A1709A	A1605A	ł	1			
I3130000 I3116000	A17098 A1710A	A1911A JA8101A	1	1			
I3114000	A1710B	JA8101B		i			
S3001300 S3001100	A1711A	A1607B		1			
I3110000	A1711B A1712A	A1605B JA8102B		1			
13112000	A1712B	JA8102A		1			
\$3001000 \$3000000	A1713A A1713B	A1603B A1608B		1			
I1026000	A1802B	A1806B		1			
11012000 11506001	A1803A A1803B	B1106A A0210A		1			
11506002	A1803B	A1907A		ż			
11025000 L1501001	A1804A A1804B	A1806A A0802A		1 2			
L1501002	A1804B	A2214B		1			
11508000	A1805A	A0208A		1			
I1027000 I1025000	A18058 A1806A	A0312B A1804A		1			
11026000	A1806B	A1802B		1			
K1001000 I1013000	A1807A A1807B	A0805B A0209A	1	1 1			
11034000	A1808A	A1808B		i			
I1034000 I1034001	A1808B A1808B	A1808A B2409A		1 2			
11623000	A1809A	A2508B		i			
11624000	A1809B A1813A	C1511B		1			
14216000	MIGISM	D1712A	1	1			
		1					
		1					
			1				
L			<u> </u>	L	<u></u>		

TITLE LOGIC WIRE WRAP			WL D	OCUMI 784	NT NO. 13	SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE	Z LEVEL		NOTE	S
I1005024 I1005025 I1911000 I3828000 I3809001 I3809001 I3827000 I3827000 I3827001 I3828000 100039 I3131000 I1422004 I1502002 I1506003 I1506003 I1506003 I1506003 I1506000 I3726000 I3726000 I3726000 I3727000	A1813B A1813B A1902A A1903A A1903A A1903A A1904A A1904A A1904B A1906B A1906B A1906B A1907A A1908B A1907A A1908B A1907A A1908B A1907A A1908B A1909B A1911B A1911B A1911B A1911B A1911B A1911B A1911B A1913B A1903B A19004A A19004B A19004B A19004B A19004B A19008B A19008B A1901A A1901B A1911B A1913B A1913B A1913B A19005B A19006B A1	B1806B C1712A JA8108B A1904B B2605B A1302B A1903B A1903B A1903B A1903B A1906B B1106A A1803B A1910A A1803B A1910A A18012A A18012A A1910B A2017A A1910B A2017A A1910B A2103B A2113B B1908B A2113B B1908B A2113B B1908B A2113B B1908B A2113B B1908B A2113B B1908B A2113B B1908B A2113B B1908B A2113B B1908B A2113B B1908B A2113B B1908B A2113B B1908B A2113B B1908B A2113B B1908B A2113B B1908B A2113B B1908B A2113B B1908B A2113B B1908B		1211121112212111121211111212111121212121			

SIGNAL NAME	TITLE  LOGIC WIRE WRAP			WL D		ENT NO. 343	SHEET NO.	REV.
\$1902300       \$20078       \$20078       \$2138       \$2         \$1902301       \$20078       \$22138       \$2         \$11418000       \$20084       \$16078       \$1         \$11418001       \$20084       \$22068       \$2         \$1901000       \$20088       \$20507A       \$1         \$1901201       \$20088       \$2713A       \$2         \$1901200       \$20094       \$20107A       \$1         \$1901201       \$20094       \$27168       \$2         \$1410000       \$20098       \$1602A       \$1         \$14140001       \$20098       \$2211A       \$2         \$1414001       \$2010A       \$1603A       \$1         \$1901100       \$2010A       \$2212B       \$2         \$1901101       \$2010B       \$2067A       \$1         \$1901101       \$2010B       \$20607A       \$1         \$1901101       \$2010B       \$2214B       \$2	OR NUMBER	ORIGIN	DESTINATION				NOTES	
S1901300	\$1902300 \$1902301 \$11418000 \$11418001 \$1901000 \$1901001 \$1901201 \$11410000 \$11410001 \$11414000 \$11414001 \$1901100 \$1901101 \$1901300 \$1901302 \$11406000 \$11406001 \$1900100 \$1900102 \$11438000 \$11402000 \$11402000 \$11402001 \$10007400GND \$13129000 \$13131000 \$13011000 \$2702000 \$2800000 \$11002004 \$2702000 \$22003000BIAS \$12705000 \$12705001 \$10007400GND \$1506004 \$1506005 \$1506000 \$1506000 \$1506000 \$1506000 \$1506000 \$1506000 \$1506000 \$1506000 \$1506000 \$1506000 \$1506000 \$1506000 \$1506000 \$1506000 \$1506000 \$1506000 \$1506000 \$1506000 \$1551000 \$1511000 \$1511000 \$1511000	A20078 A20078 A20088 A20088 A20088 A20099 A20099 A20099 A200090 A2200100 A22001100 A22001118 A220113 A22011	C0407A C2713B B1607B B2206A C0507A C0507A C0507A C0507A C0716B B1602A B160A B		121212121212121212111111111111111111111			

83308100 A 5-7

SIGNAL NAME   ORIGIN   DESTINATION   WHE   Z   NOTES	TITLE  LOGIC WIRE WRAP			VL DO		ENT NO.   \$	SHEET NO.	REV.
11530000	OR NUMBER	ORIGIN	DESTINATION					
	11530000	78	C0212A A2306B A2709B B2312B A22007A B2307A B23007A B23007A B23007B A22007B A22007B A22007B A2212B A2212B A2212B A2212B A2212B A22112B		1111112111121221121211211211211221122112112112112			

SIGNAL MANE ORIGIN   DESTINATION   WIRE   Z   NOTES	TITLE LOGIC WIRE WRAP			WL P		ENT NO. 843	SHEET NO.	8	REV.
S1801101	SIGNAL NAME OR NUMBER	ORIGIN	DESTINATION				NOTES	3	
	\$1801100 \$1801101 . I1701000 \$1801200 \$1801201 . I1705000 . I1705000 . I1703000 . I1703000 . I1802000 . S1802001 . S1802001 . S1802101 . 1001090GND . 10010901 . I1028000 . X2500000 . I2506000 . I1619000 . L1007003 . 10010901 . I1605002 . I1726001 . I1605002 . I1726001 . I1605002 . I17000 . I1617002 . I1617002 . I1614000 . I3702001 . I1621000 . I1828002 . I1621000 . I1828002 . I1621000 . I1828002 . I1621000 . I1828002 . I1621000 . I1635000 . I1535000	28	B2813B B2813B B2813B B2818B D0105B B22112B B22007A B22105A B22005A B22005A B22005A B22005A B22005A B22005B B2005B B2		211211111212121112212121211211211211211				

TITLE  LOGIC WIRE WRAP			WL D		ENT NO. 843	SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE	Z LEVEL		NOTES	
I1623000 L1001007 L1001007 L1001008 A2203000 I1811000 I1811001 I1414002 I1512000 I1512001 I1810002 I1610000 X1701100 I1726001 I1512001 K3800100 K3800101 I2418000 I4006000 I1538000 I0014000 GND K3700000 I3713000 K3700000 I1617001 I1502000 I1617001 I1502000 I1502001 I2104001 I2104002 I3703000 I3703000 I3703000 I3717000 K3903101 I4414000 I3717000 K3903101 I4414000 I3717000 I3727000 I0014000 GND K3700000 I3727000 I0014000 I3710000 I3727000 I0014000 I3710000 I37270000 I3710000 I37270000 I37270000 I3811000 A2002000 I2024000	88 898 825098 825098 825098 825098 825108 825118 82	A1809A C1908A D2702B A2714B A2310B A2806B A2216A A2515B A2211A C0312A B22007A B2501A A2501A A2501A A2511B B2604A C1912A A2617A A1303B B22407A A1303B B22407B A2617A A1303B B22407B A2617A A1303B A2211B B2207B A2212		1 1 2 1 1 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1			

E LOGIC WIRE WRAP			WL  D		SHEET NO. RE
SIGNAL NAME OR NUMBER	ORIGIN	DESTINATION	WIRE	Z	NOTES
IDENTIFICATION			COLOR	LEVEL	-
12025000	A2704A	B2806B	1	1	1
12026000	A2704B	B2807B	1	1	
12027000	A2705A	B2806A	1	1	
12023000	A27058	82805B	1	1	
12022000	A2/06A	B2804A	1	1	
12021000	A2706B	B2804B	1	1	
11533000	A2709B	A2208B	1	1	
K2200000	A2710A	A2806A	1	1	<u> </u>
A2404000	A2710B	C3008B		1	
K2201000	A2711A	A2802A		1	ļ
10000701	A27118 A2712A	JA8005B	1	1	
11532000 L2101000	A2712B	A2207B B2802B	j	1	
12102000	A2713B	A2802B	1	1 1	
L2100000	A2714A	B2802A		i	į
A2203000	A2714B	A2510A		l i	
10000700	A2715A	JA8005A	i	i	<u>.</u>
A2201000	A2715B	B2502B	l	l i	1
K2201000	A2802A	A2711A		l i	
12102000	A2802B	A2713B		Ī	
K2200100	A2803A	C0512A	i	i	
11524003	A2803B	B2507B	1	li	1
I1509003	A2804A	A2504A	ļ	1	
11002004	A2804B	A21108		1	
X1500002	A2805B	B2504A	ı	1	
K2200000	A2806A	A2710A		1	
11811001	A2806B	A2510B	1	2	
12204000	A2807A	B2709B	}	1	
11823000	A2807B	B2305B		1	
12103000	A2808A	A2305B	1	1	
I2104000 I2418000	A2808B A2816A	C2709B A2516B	1	1 1	ì
11825000	A2816B	B2305A	1	i	1
20023000 <b>-</b> 5V	A30018	JA8514A		l i	·
20021000-20V	A3002B	JA8513A	İ	i	
L2301000	A3007B	AEOESA	1	1	· · · · · · · · · · · · · · · · · · ·
L2300000	A3008B	A2304B	1	Ī	
A2310000	A3009B	C3007B		1	
12302000	A3010B	B2111A	1	2	•
K2301000	A30118	B2202A		1	1
K2300100	A3012B	B2109B	1	1	
12934000	B0802B	B1002A	1	1	
\$2901000	B0803B	B0903B		1	1
\$2901001	B0803B	C0113A	1	2	,
S2801100	B0804A	B1905B	1	1	
S2801101	B0804A B0804B	C0108B B1905A	]	2	
S2801200 S2801201	808048	C0208B	1	1 2	
	B0805A	80905B	ļ	i	
	B0805A	C0213A		\$	
\$2901100 \$2901101		1 005134	1		
52901101		B09054	1	1 1	
	80805B 80805B	B0905A C0313A	į	1 2	
S2901101 S2901200	B0805B				
S2901101 S2901200	B0805B				
S2901101 S2901200	B0805B				
S2901101 S2901200	B0805B				
S2901101 S2901200	B0805B				
S2901101 S2901200	B0805B				
S2901101 S2901200	B0805B				
S2901101 S2901200	B0805B				
S2901101 S2901200	B0805B				
S2901101 S2901200	B0805B				
S2901101 S2901200	B0805B				
S2901101 S2901200	B0805B				

TLE LOGIC WIRE WRAP		[	WL D		ENT NO. 843	SHEET NO.	1	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE	Z LEVEL		NOTES		
\$2801300 \$2801301 \$2900000 \$2900001 \$2800100 \$2800000 \$2800001 \$2901300 \$2901301 \$2901300 \$2901301 \$20006000BIAS \$20006000BIAS \$20006000BIAS \$20006000BIAS \$20006000BIAS \$20016000 GND \$29010000	B0806A B0807A B0807B B0807B B0807B B0808A B0808B B0809A B0809A B0809A B0809A B0809A B0809A B0809A B0809A B0809A B0809A B0809A B0809A B0902B B0903A B0903A B0903A B0903A B0903A B0903A B0903A B0903A B0905B B0906B B1002B B1002B B1004A B1004A B1006A B1006A B1006A B1006A B1006A B1013A B1013A B1013A B1013A B1013A B1013A B1013A	B1907B C0308B B1005A B0908B C0513A B1910B C0513A B1910B B1908B C0408B B1908B C0413A B0811A B0810A B0809B B0902B		121121212111111111111111111111111111111				
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ITLE LOGIC WIRE WRAP			NL   b'		ENT NO. 843	SHEET NO.	12	REV. A
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE COLOR	Z LEVEL		NOTES		
	B1103B B1104A B1104A B1104B B1105B B1105B B1105B B1106A B1108B B11108A B11208A B11218A	B1504B B0906B A0802B A0802B A2405A B1105B A0213A B1105A A1803A A1803A A1803A A1803A A1803A B1105A B1102B B1112A B1102B B1112A B1202B B1112A B1202B B1112A B1202B B1403B B1403B B1403B B1403B B1403B B1204B B1204B B1204B B1204B B1205A B1205B	COLOR	12112111211111111111111111111111111111		NOTES		

ILE LOGIC WIRE WRAP			WL D		ENT NO. 843	SHEET NO.	13	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATIO	N WIRE	Z		NOTES		
IDENTIFICATION	B1213A B1213B B1214A B1214A B1214A B1214A B1214A B1214A B1214A B1214A B1214A B1214A B1214A B1214A B1214A B1214A B1213A	A0302B C1504B B1206B B1206B B1403A B1110B C1908B C1213A C1511A C1212A C1513A C1513A C1513A C1513A C1212A C1213A C1		211121212121212121212121211211212121121				

SIGNAL NAME OR NUMBER ORIGIN		<del></del>				1
IDENTIFICATION I	DESTINATION	WIRE	Z LEVEL	NOT	res	
R1318000	D1602A A2009B C1909B A2010A C2513A A22011B C2707A B1606B B1608B C2707A B1506B B1605B A2008A A1608A C2706A B1605B B1609B C2706B B1609B C1612B C1802A C1611A D1802A C1611A A2308A A1906B A2003A B1705B C2711B B1708B B1705B C2711B B1708B B1705B C2711B B1708B B1705B C2711B B1708B B1705B C2711B B1708B B1705B C2711B B1708B B1705B C2711B B1708B B1705B C2711B B1708B B1705B C2711B B1708B B1706B B1705B C2711B B1708B B1706B	WIRE		NOT	TES	

TITLE LOGIC WIRE WRAP			WL P		ENT NO. 843	SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE COLOR	Z LEVEL		NOTES	
R1300000 R1310000 R1310000 R1301000 R1301000 R1301000 R1306000 R1005013 R1005013 R1005023 R1005023 R1005023 R1005023 R10050202 R1002002 R1002002 R1002002 R1002002 R1002000 R2900000 R2900000 R3001000 R3001000 R1309000 R1319000 R1309000 R1319000 R1309000 R1319000 R1006806 R2701101 X2701101 X2701102 S2801000 X2701101 X2701102 S2801100 S2801200 S2801200 S2801200 S2801200 S2801200 S2801300 R1006804 R12809000 S2801300 R1006804 R12809000 S2800002 R10006806 R0D R12809000 S2800002 R0D	33BABBBBBBBBBBBBBBBBBBBBBBBBBBBBBBBBBB	C1804A D1804A A1603A A2104B B1004B B1004B B2601B C2704B B1808B C2709A B1808B A1813B A2012B D0612A C27,08A B1806B B1810A B1809B A1813B D1402B D1402B D1402B D1402B D1402A C1803A B1906A B1906A B1906A B1906B B1906B B1906B B1904A B1906B B1904A B1906B B1904A B1906B B1904B B1906B B1904B B1906B B1904B B1906B B		111121121121212112111111112121121121121			

LOGIC WIRE WRAP	·		WL D	7	843		16	
SIGNAL NAME			WIRE	Z				
OR NUMBER	ORIGIN	DESTINATION		LEVEL		NOTE	S	
IDENTIFICATION		<del></del>	1					
•	<b>,</b>			1 1				
10006801 GND	B1503B	B1910A	1	2				
10006801 GND	B1910A	B1909B	1	2				
10006802 GND	B1910A	B1908A	1	1				
S2800100	B1910B	B0808A	1	1 1				
\$2800102	B1910B	B2112A		2				
10006800 GND	B1911B	B1909B		1 1				
X1602000	B2003B	B2404A	1	1 1				
I1506003	B2004A	A1907A		1 1				
11506004	B2004A	A2202A	1	2				
11617003	- 820048 82005A	A1313B		5				
12103001 K1700000	B2005B	A2305B		2				
K2601100	B2008B	B2204B B2110A		$\begin{vmatrix} 1\\1 \end{vmatrix}$				
K2601100	B2009B	C2804B		i				
12302001	B2011B	B2111A		i				
10007600GND	B21028	B2103A		2				
10007601GND	B2102B	B2114A		[ ]				
10007600GND	B2103A	B2102B		Ž				
10007602GND	BZÍO3A	B2104A		ī				
10007602GND	B2104A	B2103A		i				
K2300100	B2109B	A3012B		i				
K2601100	B2110A	B2008B		l i l				
X2701100	B2110B	D2706A		i				
X2701101	B2110B	B1903A	ļ	Ž				
12302000	B2111A	A3010B		2				
12302001	B2111A	B2011B		ī				
S2800002	821118	B1908B	.1.	2				
S2800102	82112A	B1910B		2				
12809000	821128	B1907A		1				
10007601GND	B2114A	B2102B		1 1				
X1701100	B2201A	A2513B	1	1 1				
11614000	822018	A2409A		1 1				
K2301000	B2202A	A3011B		1 1				
L2501000	B2202B	A2505B		1 1				
L2501001	B2202B	B2203B	1	2				
K2300000 L2501001	B2203A	B3012A	1	1 1				
	B2203B	B2202B	ľ	5				
I1406000 K1700000	B2204A B2204B	A2011B		2				
11703000	B2205A	B2005B A2316B		1 1				
11402000	B2205B	A2013B		2				
11709000	B2206A	A2315B		1				
11418001	B2206B	A2008A		2				
11430001	B2207A	A2006A	]	2				
11430002	B2207A	A2608B	1	ī				
11434001	82207B	A2004A	1	2				
11434002	B2207B	A2609B		l i				
I1717000	B2208A	B2302B		i				
11715000	B2208B	B2302A	ł	i				
11426003	B2209A	A2004B	1	2				
I1426004	B2209A	B2501B		1				
I1422005	B22098	A2006B		i				
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TITLE  LOGIC WIRE WRAP			WL D		ENT NO. 843	SHEET NO.	17	REV.
SIGNAL NAME OR NUMBER	ORIGIN	DESTINATION	WIRE	Z	043	NOTE:		A
IDENTIFICATION		DESTINATION	COLOR	LEVEL			ა 	
11711000 11713000 11410001 11705000 11414001 11414001 11414002 11701000 L2500000 11713000 S1802200 S1802201 11715000 11717000 S1802301 S1802301 11711000 11821000 20000000BIAS 11825000 11823000 S1800100 S1800101 S1801301 S1800001 20000000BIAS 2000200BIAS 21509000 11509001 21000000 x1500001 x1500001 x1500000 x1507000 x1507000 x1507000 x1507000 x1507000	822113A 822113A 822113A 822212301A 822213A 822213A 822213A 822213A 822213A 822213A 822213A 822213A 8223005A 8223005A 8223005A 8223005A 8223005A 8223005A 8223005A 8223005A 8223005A 8223005A 8223005A 8223005A 8223005A 8223005A 8223005A 8223005A 8223005A 8223005A 822313B	B2303B B2301A A2009B A2315A A2010A A2313A A2210B B2210B B2208B B2208B B2208B B2208B B2208B B2208B B2208B B2208B B2208B B2208B B2309A C0405B B2309A C0705B A2309A C0705B A2307B A2307B A2307B A2307B A2307B A2307B A2307B A2307B A2307B A2307B A2307B B2311B B2211A B2301B B2311B B2211A B2309B B2311A B2309B B2311A B2309B B2311A B2309B B2311A B2309B B2311A B2309B B2311A B2309B B2311A B2309B B2311A B2309B B2311A B2309B B2311A B2309B B2311B B2401A B2504A B1013B C2711A B2503A B1013B B2503A B1013B B2503A B1013B B2503A B1013B B2503B B2503B B203B		112112111212121211211211211211211211211				

TITLE LOGIC WIRE WRAP			WL D'		AENT NO. SHEET NO. REV. 7843 18 A
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE	Z LEVEL	NOTES
I1618000 I1622000 I1622002 I3725000 I3721000 Y1000000 I1034001 I1507001 I3723000 I1603000 I1603000 A2201000 I15511001 I1426004 I1602000 A2201000 I1507000 I1603000 X1500001 X1500001 X1500001 X1501003 L1501004 I1519000 I1622002 I1605000 I1524002 I1524003 I100073 X1601000 I1721000	### ### ##############################	A2605B A2605B A2605B A2605B A1309A A0804B B2503B A13103B A22015A A22115B B2411B B2210B B22115B B22210B		121112111121212111211112111111111111111	

TITLE  LOGIC WIRE WRAP			WL		ENT NO. 843	SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATIO	N WIRE	<del></del>	<u> </u>	NOTES	
100038 13830000 13811000 13811000 13506005 13701000 X2200100 X2200100 X2200200 11522000 11522000 11522000 11520000 L1501004 L1501005 12204000 A2208200 A2208100 L2101000 L2101000 L2101000 12022000 120221000 12022000 12023000 12023000 12027000 12025000 1821000 12026000 S1801200 S1802000 S1802100 S1802000 S4515003 S44419004	888 88 88 88 88 88 88 88 88 88 88 88 88	JA8606A A2617B A2617B A2617B A2617B A2607A A2614B D0109A B2607A A2614B B2607A B2607A B2607A B2607A B2607A B2607A B2708A B2313B B231B B231B B231B B231B B231B B231B B231B B231B B231B B231B B231B B231B B231B B2		111111111111111111111111111111111111111			

E LOGIC WIRE WRAP			WL		ENT NO. 843	SHEET NO.	20	REV.
SIGNAL NAME	6510111		WIRE	z				
OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION		LEVEL		NOTE	:S	
IDEATH TOATTON	<del></del>	<del>                                     </del>	<del>                                     </del>	i —				
S1902000	C0107A	A2003B	}	1				
I4517004	C0107B	C0207B	1	i				
S3001001	COLOBA	A1603B	1	2	ľ			
S2801101	C0108B	B0804A	ļ	Ž	ŀ			
14615004	COLOGA	C0209A	Ì	2	l			
14615005	COÎO9A	C0609A	į	1				
13822000	C0109B	A1304B	l	1				
14418002	COLLOA	D0110A		2				
I4418003 I2807001	C0110A C0110B	C0210A D0407B	1	1 2				
14415003	COLLID	D0111A		2				
14415004	COLLIA	COZILA	}	i	1			
14612000	COLLIB	D0503A	1	2				
14612001	C0111B	C0211B		Ī	ļ			
11529000	C0112A	A2206B		1	1			
14616006	C0112B	C0212B	1	1	:			
52901001	C0113A	B0803B		) S	}			
14730000	C0203B	C1002A		1	}			
I4731000 I4518007	C0204A	A0513A	}	1				
14518008	C0204B C0204B	C0304B C0104B	1	2				
L1007000	C0205A	A0209B	1	i	l			
51802101	C02058	A2317B		Ş	ŀ			
14515004	C0206A	C0106A	].	ī	j			
I4515005	C0206A	C0306A	Ì	2				
I4419004	C02068	C0106B	ĺ	1				
14419005	C0206B	C0306B	1	2				
51902100	C0207A	A2005B	1	1				
I4517003 I4517004	C0207B	C0307B		2	ľ			
S3001101	C0207B C0208A	C0107B		1 2	ļ			
52801201	C0208B	80804B	1	2				
14615003	C0209A	C0309A	1	ī				
14615004	C0209A	C0109A	1	2				
13820000	C0209B	A1303A	1	1				
14418003	C0210A	C0110A		1	ł			
I4418004	C0210A C0210B	C0310A	}	2	1			
K3800101 I4415004	C0211A	A2516A C0111A		2	ļ			
I4415005	COZITA	C0311A		2	į			
14612001	C02118	C0111B		ī				
14612002	C0211B	C0311B		Ž				
11530000	C0212A	A2207A	l	1				
14616005	C05158	C0312B		2				
I4616006	C0212B	C0112B		1	1			
S2901101 I4726000	C0213A C0303B	B0805A Cl013B		2				
14727000	C0303B	A0512B		l i				
14518006	C0304B	C0404B		li				
14518007	C0304B	C0204B		2	<u> </u>			
I1506000	C0305A	A0210A		2				
\$1802201	C0305B	B2301B		2				
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SIGNAL NAME OR NUMBER IDENTIFICATION ORIGIN ORIGIN DESTINATION WIRE Z COLOR LEVEL NOTES	
14515005	1 2 1 1 1 2 2 2 2 1 1 2 1 2 1 2 1 2 1 2

TITLE			WI	DO	CUM	ENT NO.	SHEET NO.		REV.
LOGIC WIRE WRAP			WL		7	843	<u></u>	22	A
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATIO	N WIF	RE .OR	Z LEVEL	,	NOTES		
I4718000 I4719000 I4518004 I4518005 L1000000 S1801000 S1801000 I4515008 I4419007 I4419008 S1901000 I4517001 S3000001 S2800101 I4615000 I4615000 I4615000 I4615000 I4615007 I4418007 X2701102 I4418007 X2701102 I4415008 I4612004 I4612005 K2200100 I4616002 I4616003 S2900001 I4714000 I4714000 I4714000 I4715000 I4518003 I4518003 I4518009 I4419009 S1901100 I0014101 GND I0014102 GND I4418007 I1619000 I4418007 I1619000 I4418007	C0504ABC0504ABC0504ABC0504ABC0505AAC0505BC0505BC0505BC0505BC0506AAC0506AC0506AC0507ABC0507ABC0507ABC0507ABC0507ABC0507ABC0507ABC0511AAC0511AAC0511AAC0511AAC0511AAC0604ABC0606AABC0606AABC0606AABC0606AABC0606AABC0606AABC0606AABC0606AABC0606AABC0606AABC0606AABC06AABC06AABC06AABC06AABC06AABC06AABC06AABC06AABC06AABC06AABCCC06AABCCC06AABCCC06AABCCCCAAAAAAAAAA	C1304A A0511A C0604B C0404B A0113A A2312A D0606A C0406B C0606B A2008B D0607B C0407B A1608B D0502A A1311B C0410A C0411A C0611A C0611B A2803A D0604B B0808B C0401B A2803A D0504B C0411B C0611B A2803A C0504B C0504B C0504B C0504B C0504B C0504B C0506B C0			1112112212111222112112211122111212112121				

LOGIC WIRE WRAP	,		WL		<b>ENT NO</b> . 843	SHEE	T NO.	23	REV.
SIGNAL NAME	001011		WIRE	Z					
OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION		LEVEL			NOTES		
TOCKTH TOATION	<del>-  </del>	<del></del>	<del>}</del>	<del>}</del>			<del></del>		
74616000	606120	204045	}	١ ,					
I4616000 I4616001	C0612B	D0604B D0112B	İ	2					
10014102 GND	C0613A	C0608B	1	i					
1001410GND	C0614A	C0607B	1	i	·				
14738000	C0703B	C1702A	1	2					
14739000	C0704A	A0612B	1	1					
10016206	C0705A	C0708A		1					
51800101	C0705B	B2306A		2					
I4515009 I4419009	C0706A C0706B	C0606A C0606B	1	5					
S1900101	C0707A	A1908B		2					
10016205 GND	C0708A	C0708B		2					
10016206	C0708A	C0705A		ī					
10016204 GND	C0708B	C0709B	ì	li					
10016205 GND	C0708B	C0708A		2					
10016203 GND	C0709B	C0710B		2					
10016204 GND	C0709B	C0708B	1	1					
10016202 GND	C0710B C0710B	C0712A C0709B		1 2					
10016203 GND 10016201 GND	C0712A	C0713A	1	2					
10016202 GND	C0712A	C0710B		l ī					
10016200 GND	C0713A	C0714A	1	l i					
10016201 GND	C0713A	C0712A		2				•	
10016200 GND	C0714A	C0713A		1					
R4404000	C0802A	D0411A		1					
R4400000 R4604000	C08028	D0412A		1	,				
I1124002	C0803B	C0804B		1 1					
11124003	C0803B	C0903B		Ż					
R4402000	C0804A	D0410A	Ì	1					
I1124001	C08048	C0812A	-	2					
11124002	C0804B	C08038	1	1	,				
R4602000 I1124000	C0811A	D0512A B1112B	1	1 1					
I1124001	C0812A	C0804B		2					
R4500000	C08128	D0513A		lī					
R4507004	C0813A	C0913A		2					
R4506004	C0813B	C0913B	1	2					
R4504000 ·	C0902A	D0510A	[	1	,				
R4600000	C09028	D0511A		1 1					
I1124003 I1124004	C0903B C0903B	C0803B C0904B	1	2					
R4502000	C0904A	D0613A	İ	l i					
11124004	C0904B	C0903B		i					
11124005	C0904B	C1403B	-	2					
R1100000	C0911A	B1207A		1					
20019000BIAS	C0912A	812108		1					
R1101000 R4507003	C0912B	B1412B C1413A		1					
R4507003	C0913A	C0813A	1	1 2					
R4506003	C0913B	C1413B		l ī					
R4506004	C0913B	C0813B	1	2					
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TITLE			WL DO	OCUM	ENT NO.	SHEET	NO.	REV.
LOGIC WIRE WRAP			M L	7	843	<u></u>	24	A
SIGNAL NAME	ODICIN	DESTUNATION	WIRE	Z				
OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	COLOR			ı	NOTES	
IBENTII TOATTON		<del> </del>		<del> </del>	<del></del>			
14730000	610024	000000	Į					
1473000	C1002A C1002A	C0203B	Ì	1				
11123000	C1002B	B1202A	l	2				
11123001	C1002B	C1004B		5				
100129	C1003A	C1005B	1	2				
100130	C1003A	C1003B	l .	ī				
100130	C1003B	C1003A	}	1				
14734000	C1004A	C0103B	1	1				
14734001	C1004A	D1004A	ì	2				
I1123001 I1123002	C10048 C1004B	C1002B		2				
100129	C10058	C1003A	Ì	1 2				
100127	CIOLOA	C1012B		ī				
I1123002	C1011A	C1004B		ī				
I1123003	C1011A	C1013A	(	2				
14722000	C1011B	C0403B	1	1				
14722001	C1011B	D1011B	<b>\</b>	2				
100128	C1012A	C1012B		2				
100128	C1012B	C1012A C1010A	1	2				
11123003	C1013A	Clolla	ļ	2				
14726000	C1013B	C0303B	ì	ī				
14726001	C1013B	D1013B		2				
100092	C1201A	C1212B		ī	1			
11226000	C1202A	D1304B	ļ	1				
I1226007	C1202A	D1004B	1	2				
I1225000 K1201100	C12028	B1108B B1407B		2				
K1201101	C1203A	Bloosa	1	í				
20014000B1AS	C1203B	C1204A		i				
20014000B1AS	C1204A	C1203B	1	i				
20015000B1AS	C12048	C1205A		1				
20015000B1AS	C1205A	C1204B		1				
20015000B1AS 20015000B1AS	C1205B C1206A	C1206A C1205B		1				
10009000GND	C1206B	C1214A	į .	1				
R1200000	C1207A	D0911A		i				
20017000B1AS	C1207B	C1208A	<b>[</b>	i				
20017000B1AS	C1208A	C1207B		1	•			
20016000B1AS	C1208B	C1209A		1	ì			
20016000B1AS 20018000B1AS	C1209A C1209B	C1208B	i l	1				
L1001003	C1210A	B1210A	1	1				
L1001004	C1210A	C1502B	ļ	5				
10002400	C12108	D0912A	1	ī				
20018000B1AS	CIŽIIA	C1504B	ļ	ì				
11224000	C1212A	B1406B		1				
11224001	C1212A	D1504A	1	2				
100092 K1200000	C12128 C1213A	C1201A B1404A		1				
K1200000	C1213A	A0313B	<b>!</b>	1 2				
11223000	C12138	D15048	1	ī				
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TITLE			WL P	OCUM	ENT NO.	SHEET NO.	REV.
LOGIC WIRE WRAP		<u> </u>	ΠL	7	843	25	A
SIGNAL NAME OR NUMBER	ORIGIN	DESTINATION	WIRE	Z		NOTES	
IDENTIFICATION	ORIGIN	DESTINATION	COLOR	LEVEL		NOTES	
		†		<del>                                     </del>			
10009000GND	C1214A	C1206B		1			
14714000	C1302A	C0603B		li	ļ		
14714001	C1302A	D1302A		Ž			
11123007	C13028	C1304B		1			
I1123008	C13028	C1502A	1	2			
100126	C1303A C1303A	C1303B C1305B	1 .	1 2			
100126	C1303B	C1303A		ĺ			
14718000	C1304A	C0503B		lī	<b>l</b> .		
14718001	C1304A	D1304A		2			
I1123006 I1123007	C1304B C1304B	C1311A		2			
100125	C1305B	C1302B	1	1 2			
100123	C1310A	C1312B		1	1		
11123005	C1311A	C1313A		i			
I1123006	C1311A	C1304B		2			
14706001	C13118	D1311B		1			
100124	C1312A C1312B	C1312B C1310A		2	Ì		
100124	C13128	C1310A		1			
I1123004	C1313A	B1202A		2			
I1123005	C1313A	C1311A	1	1			
14710001	C1313B	D1313B		1	ŀ		
R3000000 R3800000	C1402A C1402B	81812A 81810A		1			
R1102000	C1403A	B1408A		1 2			
I1124005	C1403B	C0904B		2			
R1800000	C1404A	B1712A	1	ī			
11119002	C1404B	C1504A		1			
R1900000 I1124006	C1411A C1412A	B1710A B1112B		1			
11124007	C1412A	C1612A		2			
R4507002	C1413A	C1613A		2			
R4507003	C1413A	C0913A	1	1			
R4506002 R4506003	C14138 C14138	C1613B		2			
11123008	C1502A	C1302B	1	1 2			
11123009	C1502A	C1704B		1			
L1001004	C15028	C1210A		2			
L1001005	C15028	D1502B		1			
100023	C1503A C1503B	C1503B C1503A		1 1			
100022	C1503B	C1505B	ļ	2			
I1119001	C1504A	B1405B		2	•		•
I1119002	C1504A	C1404B		1			
I1118000 100022	C15048 C15058	B1213B	1	1			
100122	C1510A	C1503B C1512A		2			
K1200102	C1511A	B1404B		l i			
K1200103	C1511A	C1513A		Ž			
11624000	C15118	A1809B		1			
11624001	C15118	015118		2			
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TITLE  LOGIC WIRE WRAP			WL D		ENT NO. SHEET NO. 843 26	REV.
SIGNAL NAME OR NUMBER	ORIGIN	DESTINATIO	WIRE	Z LEVEL	NOTES	
SIGNAL NAME OR NUMBER IDENTIFICATION  100112 10011000 100112 K1200103 I1613000 I1613001 R1308000 R1307000 R1305000 I1124010 I1124009 R1306000 I1124009 R1304000 I1124008 R1304000 I1124008 R1303000 R4507001 R4507001 R4507002 R4506002 I4738000 I1123010 I1123010 I1123010 I1123010 I1124011	C1512A C1512A C1513B C1513B C1513B C1602B C1603B C1603B C1604A C1604B C1604B C1612A C1612A C1612A C1612A C1613A C1613B C1702A C1702A C1702B C1703B C1704A C1704B C1710A C1711A	C1512B C1510A C1512A C1511A B2402B D1513B B1513A B1511A C1604B B1512A C1603B B1613A C1612A C1603B B1613A C1412A C1603B B1613A C1413A C1413A C1413B C1413B C1413B C1703B D1702A C1703B C1703B D1704A C1703B	WL	7 Z LEVEL 2 1 2 2 2 1 1 1 2 2 1 2 1 2 1 2 1 2 1	843 . 26	
I1621001 I1621003 I1005025 I0004000BIAS I3705005 I4203100 R1302000 R1301000 R1309000 I1124011 I1124012 R1300000 I1124012 R1300000	C17118 C17118 C17128 C17128 C17138 C17138 C18028 C18038 C18038 C18048 C18048 C18048 C18048	A2412B D1711B A1813B C1710A D1713A D2911A B1612A B1610A B1813A C1711A C1804B B1711A C1803B C1812A B1711A		2 1 2 1 1 1 1 2 1 2 1 1		

ITLE LOGIC WIRE WRAP		I	NL D'		ENT NO. 843	SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE COLOR	Z LEVEL		NOTES	
11124013 11124014 R2900000 R4507001 R4506000 R4506001 K4003000 R4002001 R4002001 R4000001 R4000001 R4001001 R4001001 R4003000 R4003001 R4003001 R4003001 R4003001 R4003001 I3705002 X4000000 L1001006 L1001006 L1001007 I1003001 K3904000 I1411000 I4006000 I1538000 R4507000 R4506000 I1124014 R4000000 I3705002 I3705003 R4001000 I3705002 I3703001 I3703002 K3903002 K3903002 K3903002 K3903002 K3603001 K3603001 I3703000 I3703001	C1812A C1812B C1813A C1813B C1813B C1903B C1903B C1904B C1904B C1905A C1905B C1906A C1906A C1906A C1906A C1906A C1907A C1906B C1907B C1	C1804B C2003A B1811A C2002A C1613B C2002B C1613B C1903B C1903B C1903B C1904A C2003B C1904A C2003B C1905A C1905A C1905A C1905A C1905B C1905A C1905B C1905A C1905B C1905A C1905B C1905A C1905B C1905A C1905B C1905A C1905B C1905A C1905B C1905A C1905B C1					
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TITLE			WL DO		ENT NO.	SHEET NO.	REV.
LOGIC WIRE WRAP			W L	7	843	28	A
SIGNAL NAME OR NUMBER	ORIGIN	DESTINATION	WIRE	Z		NOTES	
IDENTIFICATION	Ontroll	DEST INATION	COLOR	LEVEL		NOTES	
T2301	C23158	B3005B		1			
13619000	C2409B	C2509B		1			
K3500000 .	C24118	C2511B		1			
I3624000 K3603000	C2412B	C2512B D2712B		1			
K3603001	C2415B	C2013A		1			
10018300	C2501A	C2508A		1			
K3403100 10018300	C25048 C2508A	C2209B		1			
13619000	C25098	C2409B		i			
K3500000	C2511B	C2411B		1			
13624000	C25128	C2412B	1	1			
11407000 100042	C2513A C2513B	B1604A JA8404A		1			
11403000	C2514A	B1707A		ì			
100041	C2514B	JA8409A		1			
100100	C2703A C2703B	B1509A B1506A		1			
100103	C2704A	B1508A		i			
100087	C2704B	B1805A		1			
100102	C2705A	B1505A		1			
100121	C2705B C2706A	A0602B B1608A		1			
100096	C27068	B1609A		1			
100099	C2707A	B1606A		1	-		•
100098	C2707B C2708A	B1605A B1808A		1			
10003400	C2709A	B1806A		1			
12104000	C2709B	A2808B	1	1 2			
12104001 S1902101	C2709B C2710A	A2607B A2005B		2			
S1902002	C2711A	B2313A		1			
100095	C2711B	B1706A		1		•	
S1902201 11617001	C2712A C2712B	A2005A A2606B		1			
\$1901001	C2713A	A2008B		2			
\$1902301	C2713B	A2007B	l	5			
S1900102 S1901101	C2714A C2714B	A2012A A2010B		5			
11613002	C2715A	B2402B	{	ī			
\$1900002	C2715B	A2013A		2			
S1901302 S1901201	C2716A C2716B	A2011A A2009A	1	2			
100055	C2717A	A0502B	1	ī			
1000000 GND	C2717B	D2714A		1			
K2601000	C2804B C2817B	B2009B C1909A		1			
K3904000 10016100	C2901A	C2909B	1	i			
14114000	C2904B	A2614A	1	l i			
I4113000	C2905B	A2613A	1	1			
10016100 A2310000	C2909B C3007B	C2901A A3009B	1	1	:		
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TITLE LOGIC WIRE WRAP			WL P		ENT NO. 843	SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE	Z LEVEL		NOTES	
A2404000 K190000 I2406001 I4710000 I4711000 I4518002 L1502000 S1801201 I4515003 I4419002 I4419003 S1901200 10014203 GND 10014203 GND 10014203 GND 13810000 I4418001 I4418002 I3108000 I4415002 I4415003 10014201 GND 10014202 GND 10014203 GND 10014203 GND 10014201 GND 10014200 GND I4707000 I4518001 I4518002 I0000605 S1801301 I4515002 I4419001 I4419002 S1901301 1001480GND 1001480GND 1001470GND 100145 1001470GND 100145 100145001 I4415001 I4415001 I4415001 I4415001 I4415001 I4415001 I4415001 I00145 1001460GND 100149 100149	C3008B C3013B C3017B D0104A D0105A D0105A D0105A D0105B D0106B D0106B D0106B D0107A D0108A D0108B D0110A D0111A D011A D011A D0205B D0206A D0206B D0207A D0210A D0211A D0211B D0211B D0211A D0211B D0211A	A2710B B2312A B2512A D1313B A0505B D0204B A0208B A2313B D0206A C0106B A2009A D0112A D0108B D0110A B2609B D0310A C0111A D0113A D0113A D0113A D0113A D0113A D0113A D0113A D0114A D0113A D0116B D0114A D0113A D0113A D0113A D0113A D0113A D0113A D0113A D0113A D0113A D0113A D0113A D0113A D0113A D0113A D0113A D0113A D0113A D0113A D0113B D0306B D0306B D0306B D0207B D0214A D0211B D0214A D0211B D0214A D0212B		1122111212121212121212121212121212121212			
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LOGIC WIRE WRAP			WL D	7	843 30	REV.
SIGNAL NAME			WIRE	Z		
OR NUMBER	ORIGIN	DESTINATION		LEVEL	NOTES	
IDENTIFICATION			1000011			
		1	J	1	ļ	
10018900	D0214A	D0210B	1	2	1	
14702000	003038	D1704A	1	2		
14703000	D0304A	A0502A	ì	lī		
14518000	D03048	D0504B	Į	i		
14518001	D0304B	D0204B		2		
10000604	D0305A	A0311A	1	2		
10000605	D0305A	D0205A	1	li		
\$1800001	D0305B	B2307B	1		1	
14515000			1	5		
14515001	D0306A	D0507B	1	1	1	
	D0306A	D0206A	1	2		
14419000	D0306B	D0403A	ı	1		
14419001	D0306B	D0206B	ļ	2		
S1900001	D0307A	A1913B	1	2		
100152	D03078	D0311B	1	2		
12808000	D0308B	D0407A	1.	1		
I4615006	D0309A	D0502A	1	1		
13827001	D03098	A1904A	1	Ž		
14418000	D0310A	D0404B	1	2		
14418001	D0310A	D0110A	ł	ī		
10018800	D0310B	D0414A	1	li		
14415000	D0311A	D0402A	į			
14415001			1	1 1		
·	D0311A	D0211A	l	2		
100150	D0311B	D0312B		1		
100152	003118	D0307B	l	2	•	
100153	D03128	D0314A		2	•	
100150	D0312B	D0311B	1	1		
100153	D0314A	D0312B		2		
I4415000	D0402A	D0311A	1	1		•
I4419000	D0403A	D0306B	ŀ	1		
I4418000	D0404B	D0310A	1	2		
100047	D0405A	JA8506B	1	ī		
11005022	D04058	D0408B	i	i		
K2800000	D0406A	A2110A	ł	i		
S2801000	D0406B	B1903B	I			
12808000	D0407A	D0308B	1	1 1		
12807000		1	1			
12807001	D04078	D2707A	1			
100045	D0407B	C0110B	i	2		
	D0408A	JA8510B	ł	1		
11005021	D0408B	D0409B	1	2		
11005022	D0408B	D0405B	ì	1 1		
100046	D0409A	JA8504B	1	1 1		
11005020	D04098	D0506B	1	] ]		
11005021	D0409B	D0408B	I	2		
R4402000	D0410A	C0804A	i	1 1	,	
R4403000	D0410B	D0804A	<b>!</b>	1 1		
R4404000	D0411A	C0802A		1 1	•	
R4405000	D0411B	D0802A	1	i		
R440000	D0412A	C0802B	i	i		
R4401000	D0412B	D0802B	1	i		
20004000BIAS	D0413A	D0413B	ľ	lil		
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20004000BIAS 10018800	D0413B	D0413A		1 1		
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TITLE			WL D		ENT NO.	SHEET NO.	REV.
LOGIC WIRE WRAP SIGNAL NAME	-	T	WIDE		843	31	<u>A</u>
OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION		LEVEL		NOTES	
I4615000 I4615006 I4612000 I4518003 I00052 I1005018 I1005019 I00048 I1005020 I1005017 I00053 I1005016 I1005017 I00050 I1005017 I1005018 R4504000 R4604000 R4604000 R4604000 R4602000 R4603000 R4603000 R4501000 I1733000 I2415000 I2415000 I34616000 I4616000	0.50.34B 0.50.34B 0.50.34B 0.50.34B 0.50.35B 0.50.35B 0.050.	C0509A C0509A C0111B C0304B C0604B C0604B C0604B C0604B C0605B C0505B		212121121212111111111121211121112111211121112111			

ILE LOGIC WIRE WRAP			WL D		ENT NO. 843	SHEET NO.	32	REV.
SIGNAL NAME OR NUMBER	ORIGIN	DESTINATION	WIRE	Z		NOTES		<del></del>
IDENTIFICATION			COLOR	LEVEL	ļ.	NOTE.	3	
R4401000 R4605000 I1227000	D0802B D0803A D0803B	D0412B D0610B B1113B		1 1 1		:		
I1227001 R4403000 I1227001	D0803B D0804A	D0804B D0410B		2				
I1227002 R4603000	D08048 D08048 D0811A	D0803B D0812A D0512B		2 1 1				
I1227002 I1227003 R4501000	D0812A D0812A D0812B	D0804B D0903B D0513B		1 2 1				
R4509004 R4508004 R4505000	D0813A D0813B D0902A	D0913A D0913B D0510B		2 2				
R4601000 I1227003	D0902B D0903B	D0511B		1 2				
I1227004 R4503000 I1227004	D0904A D0904B	D0904B D0613B D0903B		1 1 1				
I1227005 R1200000 10002400	D09048 D0911A D0912A	D1403B C1207A C1210B		2 1 1				
R1201000 R4509003 R4509004	D0912B D0913A D0913A	B1409B D1413A D0813A		1				
R4508003 R4508004	D0913B D0913B	D1413B D0813B		1 2				
14730001 11226008 11226009	D1002A D1002B D1002B	C1002A D1004B D1011A		2 1 2				
10013901 10013800 10013901	D1003A D1003B D1003B	D1003B D1005B D1003A		1 2 1	·			
14734001 11226007 11226008	D1004A D1004B D1004B	C1004A C1202A D1002B		2 2				
10013800 10013600	D10058	D1003B D1012A		2				
11226010 11226009 14722001	D1011A D1011A D1011B	D1013A D1002B C1011B		2 1				
10013600 10013701 10013701	D1012A D1012A D1012B	D1010A D1012B D1012A		1 2 2				
11226010 14726001 14714001	D1013A D1013B	D1011A C1013B C1302A		1 2				
11226002 11226002	01302A 01302B 01302B	D1304B D1313A		2 1				
10013501 10013400 10013501	D1303A D1303B D1303B	D1303B D1305B D1303A		1 2 1				
			· .					

IITLE LOGIC WIRE WRAP			NL D		NT NO. SHEET 1	NO. 33	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE COLOR	Z LEVEL	N	OTES	<del></del>
I4718001 I1226000 I1226001 10013400 10013200 I1226003 I1226004 I4706000	D1304A D1304B D1304B D1305B D1310A D1311A D1311A	C1304A C1202A D1302B D1303B D1312A D1313A D1502A D0203B		212212			
14706001 10013200 10013301 10013301 R1202000 I1227005 R1801000 I1224002 R1901000 I1227006 I1227006	D1311B D1312A D1312A D1312B D1403A D1403B D1404A D1404B D1411A D1412A	C1311B D1310A D1312B D1312A B1411A D0904B B1712B D1504A B1710B B1710B B1113B		1 2 2 1 2 1 1 2 1		·	
R4509002  R4508002  L1001006 10009401 10009401 I1224001 I1224002 I1223000	D1413A D1413B D1502B D1503A D1503B D1503B D1504A D1504A	D1613A D1613B C1908A D1503B D1503B D1503A C1212A D1404B C1213B		2 2 1 2 1 2 1 1			
10009300 100111 K1201103 I1624001 100113 100111 100113 K1201102 K1201103 I1613001 R1318000	D15058 D1510A D1511A D1511B D1512A D1512A D1512B D1513A D1513A D1513B D1602A	D1503B D1512A D1513A C1511B D1512B D1510A D1512A B1407B D1511A C1513B B1513B		2122121211			
R1317000 R1315000	D1603A	81511B 81510B		1 1			

LOGIC WIRE WRAP		1	NL D		ENT NO. 843	SHEET NO	D. 34	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE COLOR	Z LEVEL		тои	ES	
I1227010 I1227009 R1316000 I1227009 R1314000 I1227007 I1227008 R1313000 R4509001 R4509001 R4508002 R4508001 I1226006 100115 10013100 I4702000 I4702000 I4702001 I1226006 10013100 T4201200 T4201200 T4201200 T4201200 I1227010 I1227010 I1227011 I1621003 I4216000 I0016400BIAS I3705004 I3705005 I0015500 R1311000 R1319000 I1227011 I1227012 I1227013 I1227013 I1227014 R2901000 R4509000 R4509000 R4509000 R4509000 R4509000 R4509000 R4509000 R4509000 R4509000 R4509000 R4509000 R4509000 R4509000 R4509000 R4509000 R4509000 R4509000 R4509000	D16038 D16034A D16048 D16048 D16048 D1612A D1613A D1613B D1613B D1613B D1703B D1703B D1704A D1704B D1704B D1704B D1704B D1704B D1704B D1704B D1704B D1704B D1704B D1711A D1711A D1711A D1711A D1711B D1711A D1711B D1711B D1711B D1711B D1803B D1803B D1803B D1803B D1803B D1803B D1813B D	D1711A D1604B B1512B D1612A D1603B B1613B D1412A D1604B B1611B D1813A D1813B D1413B C1702A D1703B D1703B D1703B C1704A D1703B C1704A D1703B C1704B D1703B C1709B C1709B C1709B C1709B C1709B D1603B D1812B D1813A D1710A D1712B D1603B D1813B		2112111212121212121212112111211121212121				

E LOGIC WIRE WRAP			WL D		ENT NO. 843	SHEET NO.	REV.
SIGNAL NAME OR NUMBER	ORIGIN	DESTINATION	WIRE COLOR	Z LEVEL		NOTES	
IDENTIFICATION	_	+	T	The Vict	<u> </u>		
	520004		ļ				
I1227014	D2003A D2003B	D1812A C1903B	1	2			
R4002000			1	1			
13705003	D2011A	C2011A	]	1	ļ		
13705004	D2011A	D1713A		2	1		
R4003000	D2011B	C1906A	i	1	ļ		
13703002	D2012A	C2012A	1	1			
13703003	D2012A D2012B	D2405B	i	2	ł		
K3903001		D2811B	i	2			
K3903002	D2012B	C2012B		1 1	[		
K3603002	D2013A	C2013A	]	1	]		
K3602001	D2013B	D2508B	ļ.	2	1		
K3602002	D2013B	C2013B	1	1	1		
A3400100	D21078	D2207B	1	1			
A340000	D2108B	D5508B	1	1	1		
A3400100	D2207B	D2107B		1	ŀ		
A3400000	D2208B	D2108B	1	1	[		
X3501000	D2404B	D2504B	ļ	1	j		
13703003	D2405B	D2012A	i	2			
I3618000	D2409B	D2509B	l	1	ł		
13617000	D2410B	D2510B		1			
X3501000	D25048	D2404B	Ì	1	j		
K3602000	D2508B	D2708B		1			
K3602001	D2508B	D2013B	ĺ	2			
13618000	D2509B	D2409B		] 1	ļ		
I3617000	D25108	D2410B	i	1	ļ		
10016300	D2701A	A0612A	Į.	1			
100044	D27018	JA8508B	1	1	ł		
100056	D2702A	A0503A	İ	1			
L1001008	D27028	A2509B	Į	2	Ì		
100057	D2703A	A0505A	1 .	1			
100039	D2703B	A1905A	] .	li			
100058	D2704A	A0504B	i	l i			
I3105000	D2704B	A1705A	ł	2	1 .		
100063	D2705A	B1709A	1	ì			
X2701100	D2706A	B2110B	ŧ	1			
100116	D2706B	B1708A		Ĭ			
12807000	D2707A	D04078	1	1			
100104	D2708A	B1705A	1	ì	ŀ		
K3602000	D2708B	D2508B		1			
100117	D2709A	A0511B	ì	ì	1		
100118	D2710A	A0510A		i			
10015500	D2710B	D1713B	İ	l i			
100119	D2711A	A0512A		ī			
100120	D2712A	A0513B	1	l i	1		
K3603000	027128	C2415B	1	i	,		
10000000 GND	D2714A	C2717B		ī			
K3903100	D2810B	D2910A	ł	1 ;			
	D2810B	A2613B		1 2			
K3903101 K3903000	D2811B	029118		ī			
	D2811B	D2012B		Ž			
K3903001	D2908B			1			
K4003000	D2910A	C1902B	1	i	ļ		
K3903100	DESTUA	D2810B		1		•	
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TITLE  LOGIC WIRE WRAP			WL D		ENT NO. 843	SHEET NO.	REV.
SIGNAL NAME OR NUMBER	ORIGIN	DESTINATION	WIRE	Z LEVEL		NOTES	<del></del>
Identification	D29118 D29118 D300028 D300028 D300028 D300028 D300038 D300038 D300038 D3800038 D3800038 D3800056 D3800056 D3800058 D3800	C1713B D2811B B2512B A2703A A0103B A0204B A0204A A0803A A0803A A0803A A0311B A2715B B2711B B2711B B2711B B2711B B2711B B2711B A1710A A1712A A1710B A1712A A1706B A1707A A1707B A1				NOTES	

TITLE  LOGIC WIRE WRAP			WL D		ENT NO. 843	SHEET NO.	REV.
SIGNAL NAME OR NUMBER	ORIGIN	DESTINATION	WIRE	Z		NOTES	A
IDENTIFICATION	<u> </u>	<u> </u>	COLOR	LEVEL			
100001	88028AL	A0102B		1	<u> </u>		
100073	JA8401A	B2508A	İ	1		•	
100004	JA8401B	A0102A	į	1			
100042	JA8404A JA8408A	C2513B B2509B		1 1			
100041	JA8409A	C2514B		i			Í
100173000	JA8410A	A2301A	]	1			
100002	JA84118 JA84128	A1703A JA8004A	}	1 1			
100038	JA8414B	B2608A		l î			
20022000 +5V	JA8501A	B3014B		1			
100050 L4807000	JA85018	D0509A A0508B	ļ	1 1			
100049	JA8502A JA8502B	D0606A	İ	i			
L4808000	JA8503A	A0607A	ļ	1			
100048	JA8503B	D0506A	ł	1			
L4806000 100046	JA8504A JA8504B	A0508A D0409A	l	1			
L4805000	JA8505A	A0509A	ł	1			
100052	JA8505B	D0505A	ļ	1			
L4804000 100047	JA8506A JA8506B	A0509B D0405A	İ	1 1			
L4803000	JA8507A	A0506A	}	1			
100053	JA8507B	D0508A	ł	1			
L4802000 100044	JA8508A JA8508B	A0506B D2701B		1 1			
L4801000	JA8509A	A0507B		li			
100054	JA8509B	D0609A		1			
L4800000 100045	JA8510A JA8510B	A0507A D0408A	1	1 1			
L3800000	JA8511A	A0607B		1	•		
L4809000	JA8511B	A0608A					
20020000+20V 20021000=20V	JA8512A JA8513A	B3013B A3002B	ţ	1			
20023000 -5V	JA8514A	A3001B	1 .	1			
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TITLE READ/WRITE WIRE WI	RAP (Ref: 7650	9500)	W	L	OCUM 7095	SHEET NO. 1 OF 2	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATIO	N C	VIRE OLOR	Z LEVEL	NOTES	
A33051	F0308B	F0408B	T		1		
A33052	F0307B	F0407B			1		
Current Sense	E0310B	JE8009A			1		
I19090	F0108B	JE8006B			1		
I19100	F0109B	JE8005B			1		
I19110	F0107B	JE8008B			1		
I31100	E0203B	JE8002B			1		
I31120	E0203A	JE8002A			1	·	
I31140	E0204B	JE8001B			1		
I31160	E0204A	JE8001A			1		
I31200	F0211A	JE8004B			1		
I31220	F0211B	JE8004A			1		
I31240	F0212A	JE8003B			1		
I31260	F0212B	JE8003A			1		
I31280	E0016B	JE8005A			1		
I31280	F0411B	JE8005A			2		
132010	E0117A	F0410B			1		
I32010	E0117A	JE8007B			2		
I32020	F0012B	F0409B			1		
I34230	F0309B	JE8008A			1		
I43080 .	E0114B	JE8007A			1	,	
K38002	F0106B	JE8006A			1		
L32000	E0006B	E0205B			1		
L32010	E0007B	F0201B			1		
L32020	E0008A	E0206B			1		
L32030	E0008B	F0202B			1 '		
L32040	E0010A	E0207B			1		
L32050	E0011B	F0203B			1		
L32060	E0011A	E0208B			1		
L32070	E0012B	F0204B			1		
L32080	E0012A	E0209B			1		
L32090	E0013A	F0205B			1		
L32100	E0210B	F0002A			1		
L32110	F0003A	F0206B			1		

TITLE WEAD/WHITE WIRE WE	RAP		WL D'	<b>OCUM</b> 709	ENT NO. 5	SHEET NO. 2 OF 2	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE COLOR	Z LEVEL		NOTES	
L32120	E0211B	F0003B		1			
L32130	F0004B	F0207B		1			
L32140	E0212B	F0006B		1			
L32150	F0007B	F0208B		1			
L32160	E0213B	F0008B		1			
L32170	F0009A	F0209B		1			
L32180	E0214B	F0000B		1			
L43021	E0005B	E0107B		1			
L43022	E0003B	E0104B		1			
Write +20 <b>V</b>	F0113B	JE8100A		1			
X43002	E0114A	JE8014A		1	1		
Y32000	E0113B	F0011B		1			
430000	E0401A	JE8014B		1			
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						19-21	
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TITLE			<del></del>	Т,	ID (	OCUM	ENT NO.	SHEET NO.	REV.
LOGIC HARNESS (Ref: 765	05600)				NT D		056	1 OF 5	A
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	-	DESTINAT	TION	WIRE COLOR	EVEL		NOTES	
1	A2TB2	1,4	A2C11	+	2				
2	A2TB2	1i	A2C11	-	0				
3	A2CB2	2	A2TB1	6	2				
4	A2A2P1	17	A2A2 <del>12</del> 2	8	4				
5	A2A2P2	9	A2TB4	7	4	[			
6									
7	A2TB2	13	A2TB4	8	4				
8	A2TB2	6	A2C6	+	2				
9									
10	A2TB2	2	A2C6		0				
. 11	A2TB2	2	A2TB3	2	0				
12	A2TB2	1	A2TB3	1	0				
13	A2TB2	7	A2C8	-	6				
14	A2PA80	1В	Dead Er	nd	0				
15	A2TB2	8	A2C5	+	2				
16	A2C5	+	A2R1	Т	2				
17	A2C5	+	A2CB2	1	2				
18	A2TB2	9	A2C10		6				
19	A2C10	_	A2R1	3	6				
20	A2C10	_	A2CB3	1	6				
21	A2TB2	10	A2C3	+	2				
22	A2C3	+	A2R5	Т	2	1			
23	A2C3	+	A2CB4	1	2				
24	А2ТВ3	2	A2C3		0				
25									
26	A2C3	+	A2R5	В	0		ļ 		
27	A2C1	+	A2R4	Т	0				
28									
29	A2C2	+	A2A1TE	316	0				
30	A2TB2	11	A2C1		6				· · · · · · · · · · · · · · · · · · ·
31	A2C1		A2R4	В	6				
32	A2C1		A2CB5	1	6				
33	A2TB2	12	A2K5B	NO	6				
34	A2TB2	12	A2K6	NO	6				

TITLE LOGIC HARNESS	***			V	VL DO	<b>OCUM</b> 170	ENT NO. S	HEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN		DESTINATION	ON	WIRE COLOR	Z LEVEL		NOTES	
35	A2TB1	8	A2A2P2	16	0				
36									
37	A2TB2	5	A2A2P1	10	2				
38	A2TB2	16	A2A2P1	6	2				
39	A2L1	2	A2C7	+	2				
40	A2R2	т	A2L1	2	2				
41	A2CB1A	1	A2C7	+	2				
42	A2TB2	3	A2TB3	1	0				
43	A2CB1A	2	A2A2P1	13	2			-	
44	A2CB1A	2	A2TB1	1	2				
45	A2TB1	1	A2PB30 1	3E	2				
46	A2TB1	1	A2PD30 1	3E	2				
47	A2L2	2	A2C9	_	6				
48	A2R2	В	A2L2	2	6				
49	A2CB1B	1	A2C9	-	6				-
50	A2CB1B	2	A2TB1	2	6				
51	A2TB1	2	A2PA30 2	2B	6				
52	A2TB1	2	A2PC30 2	2B	6				
53	A2CB2	2		n- eg	2				
54	A2CB2	2	A2A3P1		2				
55	A2CB3	2	A2A7 R	n- eg	6				
56	A2CB3	2	A2TB1	7	6				
. 57	A2TB2	2	A2TB3	3	0				
58	A2TB2	4	A2A3P1	13	4				
59	A2CB4	2	A2A1TB1	L 2	2				
60	A2CB4	2	A2A6	+	2				
61	A2CB5	2	A2A1TB1	110	6				
62	A2CB5	2	A2A6	-	6				* .
63	A2K6	С	A2C2	_	6				
64	A2K5B	C	A2C2	_	6			.,	
65	A2C2	_	A2K5A	NC	6				
66	A2C2	_	A2A3P1	14	. 6			•	
67	A2A5 F	Reg	A2TB1	3	2				
68	A2TB1	3	Logic Vcc+ T	'op	2				

TITLE LOGIC HARNESS			WL	DC		ENT NO. 056	SHEET NO.	3	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATIO	N WIF	RE OR	Z LEVEL		NOTES		
69	A2A7 Reg	1	$\top$	$\neg$					
70	A2TB1 4	Logic Vcc- To	op 6	;					
71	A2TB1 4	Logic	1						
72	A2TB1 3	Logic Vcc+ Bo	Τ,			-			
73									
74	A2A2P2 4	A2C11 +	- 2	2					
75	Dead End	A2C11 +	- 2	,		l			
76	A2A2P1 8	A2C11 +	- 2	,					
77	A2A3P1 6	A2C11 +	- 2	2					
78	A2DS1 B	A2C11 +	- 2	2					
. 79	A2C11 +	A2TB1	.6 2	2					
80	A2DS1 B	A2S1-B1	2	2					
81	A2C11 -	A2C8	- C	,					
82									
83	A2TB1 8	A2A2P2 6	3 C						
84	A2TB1 8	A2S2 -	·   c	)					
85	A2TB1 8	A2A3P1 1	0 0						
86	A2TB1 8	A2A2P2	L C	)					
87	A2TB1 9	A2CB3	3 0	,					
88	A2TB1 9	A2S1 A	2 0	)					
89	A2TB1 9	A2DS1	r c	)					
90	A2TB1 9	Dead End	C	)					
91	A2C6 +	A2L1 1	ι 2	2					
92	Dead End	A2TB4	9 2	2					
93	Dead End	A2TB4	L 2	2					
94	A2C7 -	A2C9 -	+ (	)					
95	A2C9 +	A2C5 -	- (	)					
96									
97	A2TB2 1	A2A5 Gr	ıd (						
98	A2TB2 1	A2A7 Gr	ıd (	2					<u> </u>
99	A2C8 -	A2L2	1 6	6					
100									
101									
102	A2C8 +	A2TB1	9 0	0					

TITLE			T	MI DO	OCUMI	ENT NO.	SHEET NO.	REV.
LOGIC HARNESS			1	WL P	705	6	4	A
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINAT	ION	WIRE COLOR	Z LEVEL		NOTES	
103	A2A3P1 7	A2TB1	12	0				
104	A2K6 2	A2TB1	12	0				_
105	A2A2Pl 1	A2TB1	8	0				
106	A2A3P1 5	A2K5	AL	2		L		
107	A2K5 BL	A2A3P1	4	0		·		<u>.</u>
108	A2K5 BL	A2A2P2	2	0				
109	A2A3P1 2	A2TB1	5	2				
110	A2A3P1 3	A2A2P1	12	2				
111	A2A3P1 11	A2K6	1	2				
112	A2TB1 5	A2PA80	8B	2				
113	A2A3P1 1	A2A2P1	7	2				
114	A2A3P1 12	A2PA80	8A	6				
115								
116							<u> </u>	
117	A2A2P2 5	A2TB1	15	4				
118	A2A2P2 3	A2PA80	2B	0				
119	A2A2P1 5	A2TB4	3	0				
120	A2TB4 3	A2S1	<b>B</b> 2	0				
121	A2A2P1 3	A2TB4	2	0				
122	A2A2P1 4	A2TB4	4	2				
123	A2TB4 4	Dead En	d	2			<u> </u>	
124	SS	A2TB4	1	0				
125	A2A2P1 18	A2TB4	5	2				
126	A2A2P1 16	A2TB4	6	2				
127	A2A2P1 11	A2PA80	3A	0	_			
128	A2A2P2 10	A2PA80	3B	0				
129	A2A2P1 9	A2TB1	14	0				
130	A2A2P1 14	A2PA80	2A	4				·
131	A2A2P1 15	A2TB1	13	2				
132		ļ	_					
133	A2CB1 3	A2TB2	15	0			-	
134	A2S1 A1	A2PA80	1A	4_				
135	Dead End	A2PA80	7B	0				
136	A2CB3 4	A2CB2	4	0			·	

							A
ORIGIN	DESTINATIO	N COI	RE LOR	Z LEVEL		NOTES	
A2CB3 4	A2PA80 7A	1 (	0				
A2CB3 5	A2CB2 3	(	0				
A2CB2 5	A2CB1 3		0				
A2CB1 5	A2CB5 3		0				
A2CB5 5	A2CB4 3		0				
A2CB4 5	A2TB1 11	L	0				
A2S2 L	A2PA80 4F	3 4	4				
A2S2 +	A2TB1 1	.   :	2				
A2PA80 5A	A2A1TB17	$\int \int d^{3}x d^{3}x$	9				
A2PA80 5B	A2A1TB16	; (	0				
	A2A1TB16	Si	ıld				
					,		
	A2A1TB16	Sh	ıld				
A2PA80 6A	A2A1TB1 1		9				
A2PA80 6B	A2A1TB11	1	0				
A2TB4 9	Dead End		0				
A2A6 AC	A2A1TB1 5	5	4				
A2A1TB1 5	A2K5A N	o	4				
A2TB3 1	Logic Gn	ıd	0				
A2TB3 2	Logic Gn	ıd	0				
A2TB3 3	Logic Gn	ıd	0				
A2TB3 4	Logic Gn	ıd	0	1			
A2TB4 10	A2PA80 4	4	0				
A2AlTBl 6	Logic Gn	ıd	0				
,				-			
				,			
		1					
	A2CB3 4 A2CB3 5 A2CB1 5 A2CB1 5 A2CB4 5 A2CB4 5 A2S2 L A2S2 + A2PA80 5A A2PA80 5B A2PA80 6B A2TB4 9 A2A6 AC A2A1TB1 5 A2TB3 1 A2TB3 2 A2TB3 3 A2TB3 4 A2TB4 10	A2CB3       4       A2PA80       7A         A2CB3       5       A2CB2       3         A2CB1       5       A2CB1       3         A2CB1       5       A2CB5       3         A2CB5       5       A2CB4       3         A2CB4       5       A2TB1       1         A2CB4       5       A2TB1       1         A2S2       L       A2PA80       4E         A2PA80       5A       A2A1TB1       7         A2PA80       5B       A2A1TB1       6         A2PA80       6A       A2A1TB1       6         A2PA80       6A       A2A1TB1       6         A2PA80       6B       A2A1TB1       6         A2A6       AC       A2A1TB1       7         A2A6       AC       A2A1TB1       7         A2TB3       1       Logic       Gn         A2TB3       2       Logic       Gn         A2TB3       4       Logic       Gn         A2TB3       4       Logic       Gn         A2TB4       10       A2PA80       4	A2CB3	A2CB3       4       A2PA80 7A       0         A2CB3       5       A2CB2 3       0         A2CB2       5       A2CB1 3       0         A2CB1       5       A2CB5 3       0         A2CB5       5       A2CB4 3       0         A2CB4       5       A2CB4 3       0         A2CB4       5       A2CB4 3       0         A2CB4       5       A2TB1 11       0         A2S2       L       A2PA80 4B       4         A2PA80       5A       A2A1TB1 7       9         A2PA80       5B       A2A1TB1 6       Shld         A2PA80       6A       A2A1TB1 6       Shld         A2PA80       6A       A2A1TB1 1       9         A2PA80       6A       A2A1TB1 1       9         A2PA80       6B       A2A1TB1 1       9         A2PA80       6B       A2A1TB1 1       9         A2PA80       6B       A2A1TB1 1       9         A2PA80       6B       A2A1TB1 1       9         A2PA80       6B       A2A1TB1 1       0         A2PA80       6B       A2A1TB1 5       4         A2PA80 <td< td=""><td>A2CB3</td><td>A2CB3</td><td>A2CB3</td></td<>	A2CB3	A2CB3	A2CB3

TITLE  DECK HARNESS (Ref: 77	382807)		WL D	OCUM 782		SHEET NO. 1 OF 3	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE	Z LEVEL		NOTES	
1	A3P2 1	A2TB1 15	4				
	Dead End C	A3S6 C	<del></del>				
3	A3S6 C	A3P2 2	<del> </del>				
4	A3P2 2	A2TB1 8	+				
	Dead.End NC		<del> </del>			· .	
6	Dead End 2	A2TB4 7	<del>                                     </del>				
7	Dead End 1	A2TB4 8	4				
8		A2TB1 1	2 4				
	Dead EndNO		A 0				
10	A3S6 NO	A2PA81 12	A 4				
. 11	A3S4 C	A2TB1 9	$\dashv$				
12	A3S4 NO	A2PA81 10	в 0				
13	A3S1 C	A2TB1 11	. 0				
14		A2TB1 10	0				
15	A3PE80 9B	A2PA80 13	В 4		-		
16							
17							
18							
19	Dead End	A2TB4	4				
20	Dead End	A2TB4	4				
21	A3PE80 1A	A2PÁ81 1.	A 4				
22	1B	1:	в				
23	2A	2	A				-
24	2B	2	В				
25	3A	3.	A				
26	3B	3	В				
27	4A	4.	A				
28	4B	4	В				
29	5A	5	A				
30	5B	5	в			_	
31	6A	6	A				
32	6B	6	В				
33	▼ 7A	7	A 🔻				
34	A3PE80 7B	A2PA81 7	В 4				

TITLE DECK HARNESS			WL D	OCUM 78	ENT NO. 28	SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE COLOR	Z LEVEL		NOTES	
35	A3PE808A	A2PA81 8A	4				
36	A3PE808B	A2PA81 8B	4				-
37	A3PE809A	A2PA8111A	4				
38							
38A	A3PE8014A	A2PA81 14	4				
38B ·	A3PE8014B	A2PA8114E	0				
39							
39A	A3P3-1 1	A2PA81 9B	0	·			
39B	A3P3-2 2	A2PA81 9A	. 4				
40							
40A	A3J4 1	A2PA8112E	9				
40B	A3J4 2	A2PA8111F	3 0				
40C	A3J4 3	A2PA8113E	Sh1d				
41	A3TB1 1	A2K5A C	4				
42	A3TB1 2	A2A1TB17	1				
43					<u> </u>		
43A	A3P8 4B	A2TB1 6	9	<u></u>			
43B	A3P8 3B	A2TB1 7	0	<u></u>			
43C	A3P8 3A	A2TB1 8	Shld				•
44							
44A	A3P8 1B	A2PB30 3B	Cente	ŗ			
44B	A3P8 1A	A2PB30 4A	Shld				
45							
45A	A3P8 2B	A2PB30 5B	Cente	ŗ			
45B	A3P8 2A	A2PB30 4E	Shld				
46							
46A	A3PE1 9B	A2PC17 9E	0				
46B	A3PE1 10B	A2PB17 9A	4				
47	A3P6 1	A3FL3 Out	2				
48							
49	A3P6 3	A3FL4 Ou	6				
50							
51	A3P6 4	A2TB1	0				
52							

TITLE DECK HARNESS	·		WL	DC	78		SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	N CC	/IRE OLOR	Z LEVEL		NOTES	
52A	A3P6 5	A3PE3 13	В	4				
52B	A3P6 6	A3PE3 14	В	0				
53								
54								
55								
56	A3PE8010A	A2PA8013	BA	4				
57	A3FL1 In	A2TB1	3	2				
58	A3FL2 In	A2TB1	4	6				
59	A3FL3 In	A2TB1	1	2				
60	A3FL4 In	A2TB1	2	6				
. 61	A3FL5 In	A2TB1 1	.3	2				
62								
62A	A3PE4 9E	A2PD22 1	вс	ond				
62B	A3PE4 9A	A2PD22 1	A S	Shld				
63						-		
63A	A3PE4 8E	A2PD22 2	ВВС	ond				
63B	A3PE4 8A	A2PD22 2	A S	hld				
64								
64A	A3PF3 4A	A2PC23 9	A S	hld			-	
64B	A3PF3 4E	A2PC23 9	вс	ond				
65 .								
, 65A	A3PF3 3A	A2PC231	LA S	Shld				
65B	A3PF3 3E	A2PC231	IB C	Cond				
66								
67	R/W Panei Gno	Deck Gr	ıd 3	8,40				
68								
68A	A2TB4 9	Dead End	1	0				
68B	A2TB1 5	Dead End	2	4				
69								
69A	A2PA8014	A.		0				
69B	A2PA8014	В		4				
						I		

TITLE I/O PANEL (Ref: 774708	100)		V	VL DO	OCUMI 77	SHEET NO. 1 OF 10	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATI	ION	WIRE COLOR	Z LEVEL	NOTES	
1	A2TB4 5	IA5J1	N	2			
2	A3TB4 4	<b>A</b>	$\overline{\overline{M}}$	2			
3	A2TB1 16		Ħ	2			
4	A2TB4 1		Ē	2			
5	A2TB4 3		J	2			
6	A2TB4 2		K	2			
7	A2TB3 10		ร	0			
8	A2TB3 10	•	J	0			
9	A2TB4 10	IA5J1	F	0			
10							
· 10A	A2PC10 6B	IA5J2	1	0			
10B	A2PC10 6A	IA5J2	4	4			
11							,
11A	A2PC10 7B	IA5J2	2	0			
11B	A2PC10 7A	IA5J2	5	4			
12							
12A	A2PC10 8B	IA5J2	8	0			
12B	A2PC10 8A	IA5J2	12	4			
13							
13A	A2PC10 9B	IA5J2	3	0			
13B	A2PC10 9A	IA5J2	7	4			
14							
14A	A2PC13 6B	IA5J2	10	0			,
14B	A2PC13 6A	IA5J2	13	4			
15							
15A	A2PC13 7B	IA5J2	11	0		 	
15B	A2PC13 7A		14	4			
16							
16A	A2PC13 8B	IA5J2	16	0			
16B	A2PC13 8A	IA5J2	20	4			
17			_				
17A	A2PC13 9B	IA5J2	15	0		 	
17B	A2PC13 9A		18				
18							

TITLE I/O PANEL		-	V	NL D	770	ENT NO. )8	SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINAT	ION	WIRE COLOR	Z LEVEL		NOTES	
18A	A2PC17 6B	I A5J2	17	0				
18B	A2PC17 6A	I A5J2	21	4				
19								
19A	A2PC15 9B	I A5J2	74	0				
19B	A2PC15 9A	I A5J2	77	4				
20								
20A	A2PC15 8B	I A5J2	75	0				
20B	A2PC15 8A	I A5J2	78	4				
21								
21A	A2PC8 5A	I A5J2	67	0				
21B	A2PC8 5B	I A5J2	72	4				
22								
22A	A2PC8 6A	I A5J2	73	0_				
22B	A2PC8 6B	I A5J2	76	_4				
23						·		
23A	A2PC8 9A	I A5J2	59	0				
23B	A2PC8 9B	I A5J2	63	4				
24					]			
24A	A2PC8 7A	I A5J2	60	0				
24B	A2PC8 7B	I A5J2	64	4				
<b>2</b> 5 .								
25A	A2PC8 8A	I A5J2	53	0				
25B	A2PC8 8B	I A5J2	56	4				
26								
26A	A2PC8 10A	I A5J2	54	0				
26B	A2PC8 10B	I A5J2	57	4				
27								
27A	A2PC14 5A	I A5J2	42	0			·	
27B	A2PC14 5E	I A5J2	45	4				
28								
28A	A2PC14 9A	I A5J2	46	0				
28B	A2PC14 9E	I A5J2	49	4				
29								
29A	A2PC14 8A	I A5J2	48	0				

TITLE I/O PANEL			1	WL DO		ENT NO. SHEET NO. REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINAT	ION	WIRE COLOR	Z LEVEL	NOTES
29B	A2PC14 8B	I A5J2	51	4		
30						
30A	A2PC9 5A	I A5J2	58	0		
30B	A2PC9 5B	I A5J2	62	4		
31						
31A	A2PC9 6A	I A5J2	66	0		
31B	A2PC9 6B	I A5J2	71	4		
32						
32A	A2PC9 8A	I A5J2	65	0		
32B	A2PC9 8B	I A5J2	70	4		
· 33						
33A	A2PC16 5A	I A5J2	28	0		
33B	A2PC16 5B	I A5J2	31	4		
34						
34A	A2PC16 6A	I A5J2	24	0		
34B	A2PC16 6B	I A5J2	27	4		
35						
35A	A2PC16 7A	I A5J2	29	0		
35B	A2PC16 7B	I A5J2	32	4		
36						
36A	A2PC16 8A	I A5J2	23	0		
36B	A2PC16 8B	I A5J2	26	4		
37						
37A	A2PC16 9A	I A5J2	30	0		
37B	A2PC16 9B	I A5J2	33	4		
38						
38A	A2PC1610A	I A5J2	34	0		
38B	A2PC1610E	I A5J2	37	4		
39						
39A	A2PC18 5A	I A5J2	40	0		
39B	A2PC18 5B					
40						
40A	A2PC18 6A	I A5J2	36	0		
40B	A2PC18 6B					

TITLE I/O PANEL			1	NL D	770	SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINAT	ION	WIRE COLOR	Z LEVEL	NOTES	
41							
41A	A2PC18 8A	I A5J2	35	0			
41B	A2PC18 8B	I A5J2	38	4			
42							
42A	A2PC18 9A	I A5J2	52	0			
42B	A2PC18 9B	I A5J2	55	4			
43							
43A	A2PC1810A	I A5J2	47	0			
43B	A2PC1810B	I A5J2	50	4			
44							
44A	A2PC17 7B	I A5J2	22	0			
44B	A2PC17 7A	I A5J2	25	4			
45							
45A	A2PC15 7B	I A5J1	E	0			
45B	A2PC15 7A	I A5J1	Н	4			
46							
46A	A2PC15	I A5J1	В	0			
46B	A2PC15	I A5J1	D	4			
47							
47A	A2PC14 6A	I A5J1	D	0			
47B	A2PC14 6B	I A5J1	F	4			
48							
48A	A2PC14 7A	I A5J1	Z	0		 	
48B	A2PC14 7B	I A5J1	B	4			
49							
49A	A2PC9 10A	I A5J1	c	0			
49B	A2PC9 10B	I A5J1	Ē	4			
50			-				
50A	A2PC9 9A	I A5J1	Y	0			
50B	A2PC9 9B	I A5J1	Ā	4			
51							
51A	A2PC17 8B	I A5J1	A	0			
51B	A2PC17 8A	I A5J1	С	4			
52							

TITLE I/O PANEL	<del> </del>		1	NL D		ENT NO. 08	SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINAT	ION	WIRE COLOR	Z LEVEL		NOTES	
52A	A2PC18 7A	I A5J1	P	0				
52B	A2PC18 7B	I A5J1	s	4				
53								
53A								
53B								
54								
54A	A2PC20 4A	I A5J1	BB	0				
54B	A2PC20 4B	I A5J1	DD	4				
55								
55A	A2PC20 7B	I A5J1	K					
. 55B	A2PC20 7A	I A5J1	K					
56								
56A	A2PC20 8B	I A5J1	L					
56B	A2PC20 8A	I A5J1	L					
57								
57A	A2PC20 6B	I A5J1	M					
57B	A2PC20 6A	I A5J1	M					
58								
58A	A2PC20 5B	I A5J1	EE	4				
58B	A2PC20 5A	I A5J1	CC	0				
59.								
59A	A2PC20 9A	I A5J1	T	0				,
59B	A2PC20 9B	I A5J1	V	4				
60								
60A	A2PC2010A	I A5J2	41	0				
60B	A2PC2010E	I A5J2	44	4				
61								
61A								
61B								
62	A2TB3 10	I A5J1	Ÿ	0				
62A								
62B								·
62C								
63	A2TB3 10	I A5J1	X	0				

TITLE I/O PANEL			NL D	OCUM 77	SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE COLOR	₹ LEVEL	NOTES	
64	A2TB3 9	II A5J1 Ÿ	0			
65	A2TB3 9	II A5J1 X	0			
66	A2TB4 5	II A5J1 N	2			
67	A2TB4 4	II A5J1 M	2			
68	A2TB1 16	II A5J1 H	2			
69	A2TB4 1	<b>п</b> А5J1 Р	2			
70	A2TB4 3	II A5J1 J	2			
71	A2TB4 2	II A5J1 K	2			
72	A2TB3 9	II A5J1 S	0			
73	A2TB3 9	II A5J1 J	0			
. 74	A2TB4 10	II A5J1 5	0			
75						
75A	A2PD10 6B	II A5J2 1	0			
75B	A2PD10 6A	II A5J2 4	4			
76						
76A	A2PD10 7B	II A5J2 2	0			
76B	A2PD10 7A	II A5J2 5	4			
77						
77A	A2PD10 8B	II A5J2 8	0			
77B	A2PD10 8A	II A5J2 12	4			
78						
78A	A2PD10 9B	II A5J2 3	0			
78B	A2PD10 9A	II A5J2 7	4			
79						
79A	A2PD13 6B	II A5J2 10	0			
79B	A2PD13 6A	П А5Ј2 13	4		·	
80						
80A	A2PD13 7B	II A5J2 11	0			
80B	A2PD13 7A	II A5J2 14	4			
81		}				
81A	A2PD13 8B	II A5J2 16	0			
81B	A2PD13 8A	II A5J2 20	4			
82						
82A	A2PD13 9B	II A5J2 15	0			

TITLE I/O PANEL			NL D	OCUM 77(	SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE COLOR	Z LEVEL	NOTES	
82B	A2PD13 9A	II A5J2 18	4			
83						
83A	A2PD17 6B	II A5J2 17	0			
83B	A2PD17 6A	II A5J2 21	4			
84						
84A	A2PD15 9B	II A5J2 74	0			
84B	A2PD15 9A	II A5J2 77	4			
85						
85A	A2PD15 8B	II A5J2 75	0			
85B	A2PD15 8A	II A5J2 78	4			
86						
86A	A2PD8 5A	II A5J2 67	0			
86B	A2PD8 5B	II A5J2 72	4			
87						
87A	A2PD8 6A	II A5J2 73	0			
87B	A2PD8 6B	II A5J2 76	4			
88						
88A	A2PD8 9A	II A5J2 59	0			
88B	A2PD8 9B	II A5J2 63	4			
89						
89A	A2PD8 7A	II A5J2 60	0			
89B	A2PD8 7B	II A5J2 64	4			
90						
90A	A2PD8 8A	II A5J2 53	0			
90B	A2PD8 8B	II A5J2 56	4			
91				<u> </u>		
91A	A2PD8 10A	II A5J2 54	0			
91B	A2PD8 10B	II A5J2 57	4			
92						
92A	A2PD14 5A	II A5J2 42	0			
92B	A2PD14 5B	II A5J2 45	4			
93						
93A	A2PD14 9A	II A5J2 46	0			
93B	A2PD14 9B	II A5J2 49	4			

TITLE  I/O PANEL			WI	L	770		SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATIO	N C	VIRE OLOR	Z LEVEL	U.	NOTES	
94								
94A	A2PD14 8A	II A5J2 4	8	0				
94B	A2PD14 8B	II A5J2 5	1	4				
95	-							
95A	A2PD9 5A	II A5J2 5	8	0				
95B	A2PD9 5B	II A5J2 6	2	4				
96								
9 <b>6</b> A	A2PD9 6A	II A5J2 6	6	0				
96B	A2PD9 6B	II A5J2 7	1	4		,		
97								
97A	A2PD9 8A	II A5J2 6	5	0				
97B	A2PD9 8B	II A5J2 7	0	4				
98								
98A	A2PD16 5A	II A5J2 2	8	0			-	
98B	A2PD16 5B	II A5J2 3	1	4				
99								
99A	A2PD16 6A	II A5J2 2	4	0				
99B	A2PD16 6B	II A5J2 2	7	4				
100								
100A	A2PD16 7A	II A5J2 2	9	0				
100B	A2PD16 7B	II A5J2 3	2	4				
101								
101 A	A2PD16 8A	II A5J2 2	3	0				
101 B	A2PD16 8B	II A5J2 2	6	4				
102								
102A	A2PD16 9A	II A5J2 3	0	0				
<b>102</b> B	A2PD16 9B	II A5J2 3	3	4				
103								
103A	A2PD1610A	II A5J2 3	4	0				
103B	A2PD1610B	II A5J2 3	7	4				
104								
104A	A2PD18 5A	II A5J2 4	0	0				
104B	A2PD18 5B	п А5Ј2 4	3	4				
105								

TITLE  I/O PANEL			V	VL P	770	SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINAT	ION	WIRE COLOR	Z LEVEL	NOTES	
105A	A2PD18 6A	II A5J2	36	0			
105B	A2PD18 6B	II A5J2	39	4			
106							
106A	A2PD18 8A	II A5J2	35	0			
106B	A2PD18 8B	II A5J2	38	4			
107							
107A	A2PD18 9A	II A5J2	52	0		 	
107B	A2PD18 9B	II A5J2	55	4			
108							
108A	A2PD1810A	II A5J2	47	0			ı
108B	A2PD1810E	II A5J2	50	4	1	 	
109	1				<u> </u>	 	
109A	A2PD17 7B	II A5J2	22	, 0	i		<u>:</u>
109B	A2PD17 7A	II A5J2	25	4	! !		
110							
110A	A2PD15 7B	II A5J1	E	0	! !		
110B	A2PD15 7A	II A5J1	Н	4	 		
111							
111A	A2PD15 6B	II A5J <b>2</b>	В	0			
111B	A2PD15 6A	II A5J1	D	4			
112						· · · · · · · · · · · · · · · · · · ·	
112A	A2PD14 6A	II A5J1	D	0		·	
112B	A2PD14 6B	II A5J1	F	4			
113						 	
113A	A2PD14 7A	II A5J1	Z	0			
113B	A2PD14 7B	II A5J1	В	4		 	
114							
114A	A2PD9 10A	II A5J1	c	0_		 ·	
114B	A2PD9 10B	II A5J1	E	4			
115							
115A	A2PD9 9A	II A5J1	Y	0			
115B	A2PD9 9B	II A5J1	A	4			
116							
116A	A2PD17 8B	II A5J1	A	0			

TITLE I/O PANEL	· · · · · · · · · · · · · · · · · · ·		I	NL D	OCUM 77		SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINAT	ION	WIRE COLOR	Z LEVEL		NOTES	
116B	A2PD17 8A	II A5J1		4				
117								
117A	A2PD18 7A	II A5J1	P	0				
117B	A2PD18 7B	II A5J1	s	4				
118								
118A								
118B					<u> </u>			
119								
119A	A2PD20 4A	II A5J1	вв	0				· 
119B	A2PD20 4B	II A5J1	DD	4				
120								
120A	A2PD20 7B	II A5J1	К					
120B	A2PD20 7A	II A5J1	K					
121								
121A	A2PD20 8B	II A5J1	L					
121B	A2PD20 8A	п А5J1	L					
122			_					
122A	A2PD20 6B	II A5J1	_M		ļ			
122B	A2PD20 6A	п А5Ј1	M					
123								· 
123A	A2PD20 5B	II A5J1	EE	4				
123B	A2PD20 5A	п А5J1	CC	0				
124					<u> </u>			
124A	A2PD20 9A	п А5Ј1	T	0				<u>-</u>
124B	A2PD20 9B	П А5J1	$\bar{v}$	4	<u> </u>			
125					<u> </u>			
125A	A2PD2010A	II A5J2	41	0				·
125B	A2PD2010B	II A5J2	44	4	ļ			
126								
126A					1			· .
126B					<u> </u>			
126C					<u> </u>			
127					<u> </u>			
127A 127B	·							

CONTROL PANEL (W-8) (1	Ref: 75042900)		WL D	OCUM 74	SHEET NO. 1 OF 1	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE	Z LEVEL	NOTES	
1	A2TB1 5	A4DS1A T	2			
2	A4DS1B T	A4DS1A T	2			····
3	A4DS1B T	A4DS5A T	2		·	
4	A4DS5B T	A4DS5A T	2	<u> </u>	 	
5	A4DS5B T	A4DS3A´ 7	2		 	
6	A4DS3B T	A4DS3A 7	2	<u> </u>		
7	A4DS3B T	A4DS4A 7	2			
8	A4DS4B T	A4DS4A 7	2			
9	A4DS4B T	A4DS2A 7	2			
10	A4DS2B T	A4DS2A	2			
11	A2TB1 16	A4DS6B 7	2			
12	A4DS6A T	A4DS6B 7	2			
13	A4DS6A B	A4DS6B I	3 0			
14	A2TB1 14	A4DS6B I	3 0		<u> </u>	
15	A4DS6A B	A4S7A NO	0			
16	A2TB1 10	A4S7A	0	<u> </u>		
17	A2TB4 6	A4S7B NC	2			
18	A2TB4 4	A4S7B (	2			
19	A2TB4 5	A4S7B NO	2			
20	A2PA82 8B	A4S7C NC	0			
21.	A2PA82 3A	A4S1 NO	0		 	
22	A2PA82 5A	A4DS1A I	3 4			
23	A2PA82 5E	A4DS1B I	3 4			
24	A2PA82 6A	A4DS5A I	3 4			
25	A2PA82 3E	A4DS5B I	3 4			
26	A2PA82 4A	A4DS3A 1	3 4			
27	A2PA82 4E	A4DS3B 1	3 4			
28	A2PA82 1A	A4DS4A	3 4			
29	A2PA82 1E	A4DS4B	3 4			
30		A4DS2A				
31		A4DS2B				
32	A2TB1 8		0			
33	<u> </u>		0			

TITLE  MAINTENANCE PANEL (Re	f: 76462300)	1	WL D		ENT NO. 623	SHEET NO. 1 OF 2	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE COLOR	Z LEVEL		NOTES	
1		A2PA85 1A	8				
1A	2	2	4				
1B	3	3					
1C	4	4		,			
1D	5	5					
1E	6	6			1		
1F	7	7					
1G	8	8					
1H	9	9					
1J	10	10					
1K	11	11					
1L	12	12					
1M	13	13					
1N	A2A1P1 14A	A2PA85 14A					
1P		A2PA85 1B					
1R	2	2					
18	3	3					
1T	4	4					
1U	5	5					
1V	6	6					
1W .	7	7					
1X	8	8				·	
1Y	9	9					
1AA	10	10					
1BB	11	11					
1CC	12	12					
1DD	13	13					
1EE	A2A1P1 14B	A2PA8514B					
2	1	A2PA84 1A					
2A	4A	4A					
2B	8A	. 8A					
2C	9A	. 9A					
2D	10A	. 10A	\				
2E	A2A1P2 1B	A 2PA84 1B	8				

TITLE MAINTENANCE PANEL			W	IL DO	OCUMI	ENT NO. 623	SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATIO	N	WIRE COLOR	Z LEVEL		NOTES	
2F	A2A1P2 11B		T	8				
2G	A2A1P2 12B		$\neg$	8				
2H	A2A1P2 14B	A2PA84 14	В	8				
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			$\neg$					
			$\exists$					

AC HARNESS (50 or 60 Hz)	(Ref: 774623	00)	WL D	OCUM 762	SHEET NO. 1 OF 3	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATIO	WIRE	Z LEVEL	NOTES	
1	A1CB1 A2	A1K4 3	4			
2	A1CB1 B2	A1K4 4	4			
3	A1K4' 5	A1FL1 In	4			٠.
4 .	A1K4 6	A1FL2 In	4			
5	A1FL1 Out	A1CB2 A	1 1			
6	A1CB2 A1	A1M1 7	1			
7	A1CB2 B1	A1FL2 Ou	t 1			
8	A1CB2 B1	A1M1 I	3 1			
9					 	
9 <b>A</b>	A1FL1 Out	A1P2 2	1			
9B	A1FL2 Out	A1P2 3	1			
9C	A1P2 1	A1FL1 Gn	Shld			
9D	A1P2 1	A1FL1 Gn	d 54			
10	Safety Gnd Gnd	A1P7(1) 1	54			·
11	A1K1 5	A1P7(1) 2	1		 	
12	A1K1 5	A1A1 E10	1		 	
13	A1CB2 A3	A1P7(1) 3	1		 	
14	A1CB2 A3	A1CB2 B	1		 	· .
15	A1CB2 A4	A1P7(1) 4	1			
16	A1K2 5	A1P7(1) 5	5 1			
. 17	A1K2 5	A1A1 E1	1 1			
18	Safety Gnd Gnd	A1P7(1) 8	5			
19	A1CB2 A2	l .	3 1			
20	A1K1 3	A1A1 E	) 1	<u> </u>		·
21	A1CB2 B3	A1K2 3	3 1			
22		A1A1 E	8 1	<u> </u>		
23						
24						
25	A1TB2 2	A1XF1 I	n 1			
26	A1TB2 1	A1XF2 I	n 1			
27	A1TB2 4	A1TB3	2 1			
28	A1TB2 1	A1TB3	1. 1			
29	A1XF1 Out	A1TB2	5 1			
30	A1XF2 Out	A1TB2	3 1			

TITLE  AC HARNESS (50 or 60 Hz)			WL	762	SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE	Z R LEVEL	NOTES	
31	A1TB2 5	A1T3 2	1			
32	A1TB2 6	A1T3 1	1			
33	A1 Safety Gnd	A2 Safety Gnd	54			
34	A1CR7-10+	A2TB2	3 2			
35	A1TB4 7	A1TB4	1 0			
36	A1TB4 4	A2TB2 2	0			
37	A1CR7-10-	A2TB2	6			
38	A1CR5-6 C	A2TB2 8	3 2			
39	A1CR15 A	A2TB2	6			
40	A1CR11-14+	A2TB2 10	) 2			
41	A1TB3 6	A2TB2	0			
42	A1CR11-14-	A2TB2 1	1 6			
43	A1CR16-17-	A2TB2 1	2 6			·
44	A1K2 2	A1P7(1)	7 4			
45	A1K2 2	A1A1 E	6 4			
46	A1K4 2	A1P7(1)	3 O			
47	A1K4 2	A1K1	2 0			
48	A1TB3 5	A1CR16 -17 AC1	4			
49	A1TB3 7	A1CR16 -17 AC2	4			
50	A1T3 4	A1CR1 -2 AC	1 4			
51	A1T3 6	A1CR1 -2 AC	2 4			
52	A1TB3 8	A1CR11 -14 AC	2 4			
53	A1TB4 3	A1CR5	A 4		,	
54	A1TB3 4	A1CR11 -14 AC	1 4			
55	A1TB4 5		A 4			
56	A1TB4 6	A1CR7 -10 AC	1 4			
57	A1CR6 A	A1CR3 -4 AC				
58	A1CR5 A	A1CR3 -4 AC	1 4			
59	A1TB4 8	A1CR7				
60	A1CR3-4 -	A1CR15	C 6			
61	A1CR1-2 +	A2TB2 1	4 2			
62	A1CR1-2 +	A1K4	1 2			
63	A1K4 1	A1A1 E	1 2			
64	A1T3 5	A2TB2	1 0			

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TITLE AC HARNESS (50 or 60 Hz)			V	VL DO		ENT NO. 7623	SHEET NO.	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINAT	ION	WIRE COLOR			NOTES	
65	A1T3 5	A1A1	E2	0				
66	A1A1 E2	A1A1	E4	0				
67			,					
68	A1K1 2	A1A1	E4	0				
60	A2TB2 4	A1A1	E6	4				
70								
71	A2TB2 5	A1A1	E5	2				
72	A1A1 E5	A1K2	1	2				
73	A1K2 1	A1K1	1	2				· · · · · · · · · · · · · · · · · · ·
74	A1K1 1	A1A1	E3	2				
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TITLE POWER CABLE (W-2) (1)	Ref: 7	7463900	)	W	IL DO	OCUM 76:	ENT NO. SH	HEET NO. 1 OF 1	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	0	RIGIN	DESTINATI	ON	WIRE COLOR	Z LEVEL		NOTES	
1									
1A	P1	X	A1CB1	A1	1				
1B	P1		A1CB1		6				
1C	P1		Frame Gi	$\neg$	5	ĺ			
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TITLE  AC HARNESS (400 Hz) (	Ref: 77464800)		WL D	OCUM	ENT NO. 7648	SHEET NO. 1 OF 1	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN	DESTINATION	WIRE	Z LEVEL		NOTES	
1							
2	Main Frame Safety Gnd	A1 Safety Gnd	54				
3	Shld	Sh1d					
4		A1TB2 2	4				
5	A1CB3B 2	A1TB2 3	4			- <del> </del>	
6	A1CB3C 2	A1TB2 1	4				
	MICESC 2	ATTB2 I	<del>                                     </del>				
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TITLE CIRCUIT BREAKER BOX	(Ref: 7746	43	300)	V	VL D	764	ENT NO. 3	SHEET NO. 1 OF 1	REV.
SIGNAL NAME OR NUMBER IDENTIFICATION	ORIGIN		DESTINATI	ON	WIRE COLOR	₹ LEVEL		NOTES	
1	A1CB3A			1	4				
2	A1CB3B	1	A1TB1	2	4				
3	A1CB3C	1.	A1TB1	3	4				
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	<u> </u>	-			<u> </u>				
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